

Generating Compiler Optimisations using Rosser

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Introduction

Motivation

Design

Representation

Generation Strategy

Performance Results

Methodology

Effectiveness

Motivation

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- ▶ TRANS *ideally* supports experimentation
- ▶ Existing optimisation specifications often difficult or impossible to compare formally
- ▶ Questions over efficiency of generated optimisations.

Overview

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- ▶ transform method corresponds to action
- ▶ condition method corresponds to side condition

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- ▶ Uses JEDD as output language

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- ▶ `Assign, IfStmt, ReturnsValues`
- ▶ `<eq, l, r, op>` Expr

Side Conditions

```
comp-s true      = [res =  $\top$ ]  
comp-s False    = [res =  $\perp$ ]  
comp-s conlit(v) = [temp1 =  $\top$ , res = temp1{v} >< meth.Conlit{c}]  
comp-s varlit(v) = [temp1 =  $\top$ , res = temp1{v} >< meth.Varlit{v}]  
comp-s  $\neg \phi$     = comp-s  $\phi$  @ [res =  $\top$  - pred]  
comp-s  $n \mid = \phi$  = comp-s  $\phi$  @ [res = (at =>) pred{n,at} <> pred{at,n}]  
comp-s  $\phi \wedge \psi$  = comp-s  $\phi$  @ comp-s  $\psi$  @ [res = pred1 & pred2]  
comp-s  $\phi \vee \psi$  = comp-s  $\phi$  @ comp-s  $\psi$  @ [res = pred1 | pred2]
```

Node Conditions

```
comp-t EX  $\phi$  = comp-t  $\phi$  @  
    [temp1 = (et=>)meth.Edges,  
    res = (to=>at) pred{at} <> temp1{from} ]
```

Until

```
temp1 = (et=>) meth.Edges;
acc = pred2;
do {
  prev = acc;
  temp2 = (from=>) pred1{at} <> temp1{to};
  acc |= pred2 & temp2
} while(prev != acc);
res = acc
```

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Applied: Dead Code Elimination, Common Subexpression elimination, Lazy Code Motion

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- ▶ Part of Spec JVM 2008

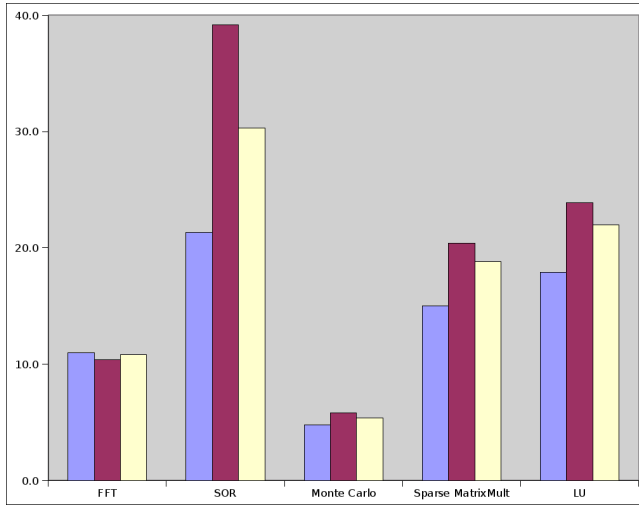
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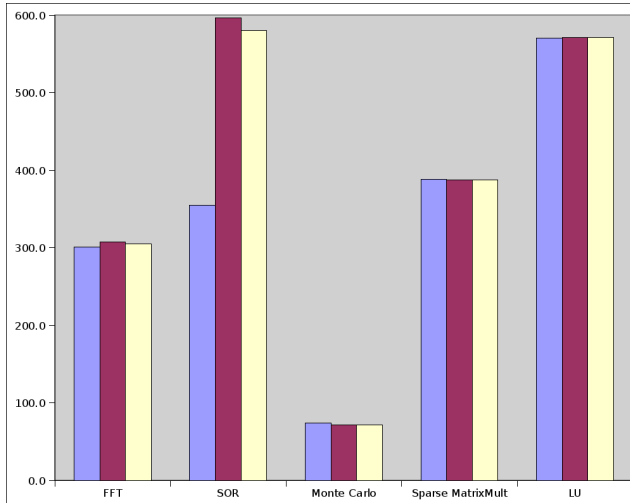
SableVM



The End

Anyone for Pub Questions?

SUN JVM



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- ▶ Usually: 2x slower than hand-coded
- ▶ Pathologically: > 1000x slower