

Local Distributed Decision

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Decision problems

Does randomization helps?

Nondeterminism

Power of oracles

Further works

Outline

Decision problems

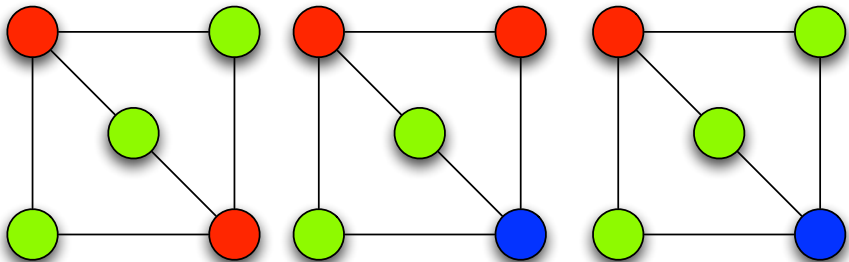
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Decide coloring



Computational model

LOCAL model

In each round during the execution of a distributed algorithm, every processor:

1. **sends** messages to its neighbors,
2. **receives** messages from its neighbors, and
3. **computes**, i.e., performs individual computations.

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Input

An input configuration is a pair (G, x) where G is a connected graph, and every node $v \in V(G)$ is assigned as its **local** input a binary string $x(v) \in \{0, 1\}^*$.

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Output

The output of node v performing Algorithm \mathcal{A} running in G with input x and identity assignment Id :

$$out_{\mathcal{A}}(G, x, Id, v)$$

Languages

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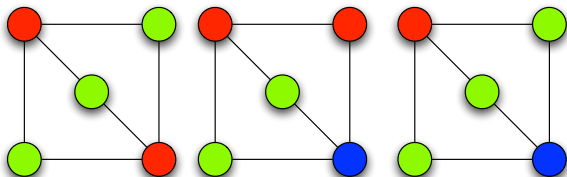
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 $\{(G, (x_1, x_2)) \text{ s.t. } \exists u \in V(G), \forall v \in V(G), x_2(v) = x_1(u)\}.$
- ▶ MIS = $\{(G, x) \text{ s.t. } S = \{v \in V(G) \mid x(v) = 1\} \text{ is a MIS}\}.$

Decision

Let \mathcal{L} be a distributed language.

Algorithm \mathcal{A} decides $\mathcal{L} \iff$ for every configuration (G, x) :

- ▶ If $(G, x) \in \mathcal{L}$, then for every identity assignment Id ,
 $\text{out}_{\mathcal{A}}(G, x, \text{Id}, v) = \text{"yes"}$ for every node $v \in V(G)$;
- ▶ If $(G, x) \notin \mathcal{L}$, then for every identity assignment Id ,
 $\text{out}_{\mathcal{A}}(G, x, \text{Id}, v) = \text{"no"}$ for at least one node $v \in V(G)$.



Local decision

Let t be a function of triplets (G, x, Id) .

Definition

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Definition

$LD(t)$ is the class of all distributed languages that can be decided by a distributed algorithm that runs in at most t communication rounds.

- ▶ $Coloring \in LD(1)$ and $MIS \in LD(1)$.
- ▶ $AMOM$, $Consensus$, and $SpanningTree$ are not in $LD(t)$, for any $t = o(n)$.

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Related work

What can be computed locally?

Define **LCL** as **LD($O(1)$)** involving

- ▶ solely graphs of constant maximum degree
- ▶ inputs taken from a set of constant size

Theorem (Naor and Stockmeyer [STOC '93])

*If there exists a **randomized** algorithm that constructs a solution for a problem in **LCL** in $O(1)$ rounds, then there is also a **deterministic** algorithm constructing a solution for that problem in $O(1)$ rounds.*

Proof uses Ramsey theory.

Not clearly extendable to languages in **LD($O(1)$)** \ **LCL**.

$(\Delta + 1)$ -coloring

Arbitrary graphs

- ▶ can be randomly computed in expected #rounds $O(\log n)$
(Alon, Babai, Itai [J. Alg. 1986]) (Luby [SIAM J. Comput. 1986])
- ▶ best known deterministic algorithm performs in $2^{O(\sqrt{\log n})}$ rounds (Panconesi, Srinivasan [J. Algorithms, 1996])

Bounded degree graphs

- ▶ Randomization does not help for 3-coloring the ring
(Naor [SIAM Disc. Maths 1991])
- ▶ can be randomly computed in expected #rounds $O(\log \Delta + \sqrt{\log n})$ (Schneider, Wattenhofer [PODC 2010])
- ▶ best known deterministic algorithm performs in $O(\Delta + \log^* n)$ rounds
(Barenboim, Elkin [STOC 2009]) (Kuhn [SPAA 2009])

2-sided error Monte Carlo algorithms

Focus on distributed algorithms that use randomization but whose running time are deterministic.

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(p, q) -decider

- ▶ If $(G, x) \in \mathcal{L}$ then, for every identity assignment Id ,
 $\Pr[\text{out}_{\mathcal{A}}(G, x, \text{Id}, v) = \text{"yes"} \text{ for every node } v \in V(G)] \geq p$
- ▶ If $(G, x) \notin \mathcal{L}$ then, for every identity assignment Id ,
 $\Pr[\text{out}_{\mathcal{A}}(G, x, \text{Id}, v) = \text{"no"} \text{ for at least one node } v \in V(G)] \geq q$

Example: AMOM



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Randomized algorithm

- ▶ every unmarked node says “yes” with probability 1;
- ▶ every marked node says “yes” with probability p .

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Randomized algorithm

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- ▶ every marked node says “yes” with probability p .

Remarks:

- ▶ Runs in zero time;
- ▶ If the configuration has at most one marked node then correct with probability at least p .
- ▶ If there are at least $k \geq 2$ marked nodes, correct with probability at least $1 - p^k \geq 1 - p^2$
- ▶ Thus there exists a (p, q) -decider for $q + p^2 \leq 1$.

Bounded-probability error local decision

Definition

$\text{BPLD}(t, p, q)$ is the class of all distributed languages that have a randomized distributed (p, q) -decider running in time at most t .

I.e., can be decided in time at most t by a randomized distributed algorithm with “yes” success probability p and “no” success probability q .

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Remark

For p and q such that $p^2 + q \leq 1$, there exists a language $\mathcal{L} \in \text{BPLD}(0, p, q)$, such that $\mathcal{L} \notin \text{LD}(t)$, for any $t = o(n)$.

A sharp threshold for hereditary languages

A **prefix** of a configuration (G, x) is a configuration $(G[U], x[U])$, where $U \subseteq V(G)$

Hereditary languages

A language \mathcal{L} is *hereditary* if every prefix of every configuration $(G, x) \in \mathcal{L}$ is also in \mathcal{L} .

- ▶ **Coloring** and **AMOM** are hereditary languages.
- ▶ Every language $\{(G, \epsilon) \mid G \in \mathcal{G}\}$ where \mathcal{G} is hereditary is... hereditary. (Examples of hereditary graph families are planar graphs, interval graphs, forests, chordal graphs, cographs, perfect graphs, etc.)

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Theorem

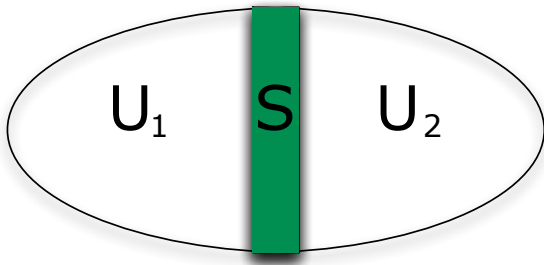
Let \mathcal{L} be an hereditary language and let t be a function of triples (G, x, Id) . If $\mathcal{L} \in BPLD(t, p, q)$ for constants $p, q \in (0, 1]$ such that $p^2 + q > 1$, then $\mathcal{L} \in LD(O(t))$.

One ingredient in the proof

Let $0 < \delta < p^2 + q - 1$, and define $\lambda = 11 \cdot \lceil \log p / \log(1 - \delta) \rceil$.

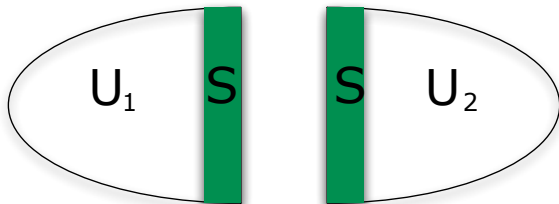
Separating partition

A *separating partition* of (G, x, Id) is a triplet (S, U_1, U_2) of pairwise disjoint subsets of nodes such that $S \cup U_1 \cup U_2 = V$, and $\text{dist}_G(U_1, U_2) \geq \lambda \cdot t$.



Glueing lemma

Given a separating partition (S, U_1, U_2) of (G, x, Id) , let $G_k = G[U_k \cup S]$, and let x_k be the input x restricted to nodes in G_k , for $k = 1, 2$.



Lemma (\star)

For every instance (G, x) with identity assignment Id , and every separating partition (S, U_1, U_2) of (G, x, Id) , we have:

$$\left((G_1, x_1) \in \mathcal{L} \text{ and } (G_2, x_2) \in \mathcal{L} \right) \Rightarrow (G, x) \in \mathcal{L}.$$

Remark. Lemma (\star) does not use the fact that \mathcal{L} is hereditary, but uses $p^2 + q > 1$.

Derandomization

Deterministic Algorithm \mathcal{D} , applied at a node u

Given an instance (G, x) and an id-assignment Id :

If $(B_G(u, 2\lambda t), x[B_G(u, 2\lambda t)]) \in \mathcal{L}$
then $\text{out}(u) = \text{"yes"}$
else $\text{out}(u) = \text{"no"}$

Remark

Nodes do not know t , but this can be fixed.

Correctness (1/4)

Assume $(G, x) \in \mathcal{L}$.

Since \mathcal{L} is hereditary, every prefix of (G, x) is also in \mathcal{L} .

Thus, every node u outputs $\text{out}(u) = \text{"yes"}$.

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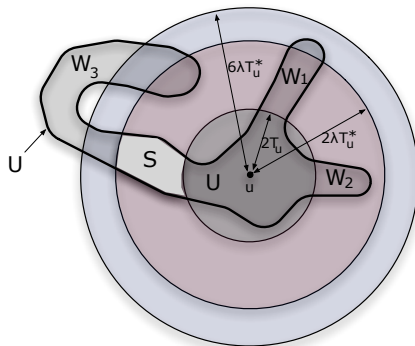
Conversely, assume $(G, x) \notin \mathcal{L}$.

Assume towards contradiction that by applying \mathcal{D} on (G, x, Id) , every node u outputs $\text{out}(u) = \text{"yes"}$.

Let $U \subseteq V(G)$ be a maximal set of vertices such that $G[U]$ is connected and $(G[U], x[U]) \in \mathcal{L}$.

- ▶ U is not empty, as $(B_G(u, 2\lambda t), x[B_G(u, 2\lambda t)]) \in \mathcal{L}$ for every node u .
- ▶ $|U| < |V(G)|$, because $(G, x) \notin \mathcal{L}$.

Correctness (2/4)



Let $u \in U$ be a node such that $B_G(u, 2t)$ contains a node outside U .

Let $G' = G[U \cup V(B_G(u, 2t))]$.

Observe that G' is connected and that G' strictly contains U .

Our goal is to show that $(G', x[G']) \in \mathcal{L}$, for contradiction.

Correctness (3/4)

Let W^1, W^2, \dots, W^ℓ be the ℓ connected components of $G[U] \setminus B_G(u, 2t)$, ordered arbitrarily.

Let H denote the maximal graph such that H is connected and

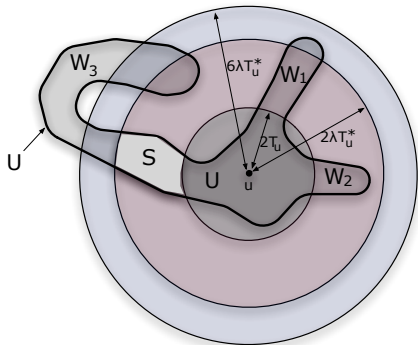
$$B_G(u, 2t) \subset V(H) \subseteq B_G(u, 2t) \cup (U \cap B_G(u, 2\lambda t))$$

Let W^0 be the empty graph, and for $k = 0, 1, 2, \dots, \ell$, define the graph $Z^k = H \cup W^0 \cup W^1 \cup W^2 \cup \dots \cup W^k$.

Observe that Z^k is connected for each $k = 0, 1, 2, \dots, \ell$, and that $Z^\ell = G'$.

We prove by induction on k that $(Z^k, x[Z^k]) \in \mathcal{L}$ for every $k = 0, 1, 2, \dots, \ell$. (This will establish the contradiction since, as we mentioned before, $Z^\ell = G'$).

Correctness (4/4)



Define the sets of nodes

- ▶ $S = V(Z^k) \cap V(W^{k+1})$
- ▶ $U_1 = V(Z^k) \setminus S$
- ▶ $U_2 = V(W^{k+1}) \setminus S$

A crucial observation is that (S, U_1, U_2) is a separating partition of Z^{k+1} .

By induction, we have $(G_1, x[G_1]) \in \mathcal{L}$, because $G_1 = G[U_1 \cup S] = Z^k$.

In addition, we have $(G_2, x[G_2]) \in \mathcal{L}$, because $G_2 = G[U_2 \cup S] = W^{k+1}$, and W^{k+1} is a prefix of $G[U]$.

We can now apply Lemma (\star) and conclude that $(Z^{k+1}, x[Z^{k+1}]) \in \mathcal{L}$.

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Distributed certification

One motivation

Settings in which one must perform local verifications repeatedly.

- ▶ Proof Labeling Scheme (Korman, Kutten, Peleg [PODC 2007])
- ▶ Distributed verification (Das Sarma et al. [STOC 2011])

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Definition

An algorithm \mathcal{A} verifies \mathcal{L} if and only if for every configuration (G, x) , the following hold:

- ▶ If $(G, x) \in \mathcal{L}$, then there exists a certificate y such that, for every id-assignment Id , $out_{\mathcal{A}}(G, (x, y), Id, v) = \text{"yes"}$ for all $v \in V(G)$;
- ▶ If $(G, x) \notin \mathcal{L}$, then for every certificate y , and for every id-assignment Id , $out_{\mathcal{A}}(G, (x, y), Id, v) = \text{"no"}$ for at least one node $v \in V(G)$.

Non-determinism helps

Definition

Let t be a function of triplets (G, x, Id) . $\text{NLD}(t)$ is the class of all distributed languages that can be verified in at most t communication rounds.

Example

$\text{Tree} = \{(G, \epsilon) \mid G \text{ is a tree}\} \in \text{NLD}(1)$.

Certificate given at node v is $y(v) = \text{dist}_G(v, \hat{v})$, where $\hat{v} \in V(G)$ is an arbitrary fixed node.

Verification procedure verifies the following:

- ▶ $y(v)$ is a non-negative integer,
- ▶ if $y(v) = 0$, then $y(w) = 1$ for every neighbor w of v , and
- ▶ if $y(v) > 0$, then there exists a neighbor w of v such that $y(w) = y(v) - 1$, and, for all other neighbors w' of v , we have $y(w') = y(v) + 1$.

NLD-complete problem

Reduction

\mathcal{L}_1 is **locally reducible** to \mathcal{L}_2 , denoted by $\mathcal{L}_1 \preceq \mathcal{L}_2$, if there exists a constant time local algorithm \mathcal{A} such that, for every configuration (G, x) and every id-assignment Id , \mathcal{A} produces $\text{out}(v) \in \{0, 1\}^*$ as output at every node $v \in V(G)$ so that

$$(G, x) \in \mathcal{L}_1 \iff (G, \text{out}) \in \mathcal{L}_2 .$$

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The language Containment

$x(v) = (\mathcal{E}(v), \mathcal{S}(v))$ where:

- ▶ $\mathcal{E}(v)$ is an element
- ▶ $\mathcal{S}(v)$ is a finite collection of sets

$\{(G, (\mathcal{E}, \mathcal{S})) \mid \exists v \in V, \exists \mathcal{S} \in \mathcal{S}(v) \text{ s.t. } \mathcal{S} \supseteq \{\mathcal{E}(u) \mid u \in V\}\}.$

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Theorem

Containment is **NLD($O(1)$)-complete**.

Combining non-determinism with randomization

Let $\text{BPNLD}(t) = \cup_{p^2+q \leq 1} \text{BPNLD}(t, p, q)$.

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Proof

The certificate is a map of the graph, i.e., an isomorphic copy H of G , with nodes labeled from 1 to n .

Each node v is also given its label $\ell(v)$ in H .

The proof that nodes can probabilistically check $H \sim G$ relies on two facts:

- ▶ To be “cheated”, a wrong map must be a lift of G .
- ▶ One can check whether H is a lift of G by having node(s) labeled 1 acting as in AMOM.



The “most difficult” decision problem

The problem **Cover**

$\{(G, (\mathcal{E}, \mathcal{S})) \mid \exists v \in V, \exists S \in \mathcal{S}(v) \text{ s.t. } S = \{\mathcal{E}(u) \mid u \in V\}\}.$

Theorem

Cover is ***BP**NLD($O(1)$)-complete.*

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The oracle `GraphSize`

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$$\text{GraphSize} = \{(G, k) \text{ s.t. } |V(G)| = k\}.$$

Theorem

For every language \mathcal{L} , we have $\mathcal{L} \in \text{NLD}^{\text{GraphSize}}$.

Proof

Certificate is the `map` of G . (Cannot be “cheated” whenever the nodes know the number of nodes).

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- ▶ Connections between classical computational complexity theory and the local complexity one, e.g., by putting **constraints on individual computation time**.
- ▶ Also, one could restrict the **memory** used by a node, in addition to, or instead of, bounding the sequential time.
- ▶ Complexity framework taking also **traffic congestion** into account. (This can be done by, e.g., considering the *CONGEST* model).

Thank You!