

Tight Bounds for Worst-Case Equilibria*

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Abstract

We study the problem of traffic routing in non-cooperative networks. In such networks, users may follow selfish strategies to optimize their own performance measure and therefore their behavior does not have to lead to optimal performance of the entire network. In this paper we investigate the worst-case coordination ratio, which is a game theoretic measure aiming to reflect the price of selfish routing.

Following a line of previous work, we focus on the most basic networks consisting of parallel links with linear latency functions. Our main result is that the worst-case coordination ratio on m parallel links of possibly different speeds is

$$\Theta\left(\frac{\log m}{\log \log \log m}\right).$$

In fact, we are able to give an exact description of the worst-case coordination ratio depending on the number of links and the ratio of the speed of the fastest link over the speed of the slowest link. For example, for the special case in which all m parallel links have the same speed, we can prove that the worst-case coordination ratio is $\Gamma^{(-1)}(m) + \Theta(1)$, with Γ denoting the Gamma (factorial) function. Our bounds entirely resolve an open problem posed recently by Koutsoupias and Papadimitriou [KP99].

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1 Introduction

A fundamental problem arising in the management of large-scale communication networks, like the Internet, is that of routing traffic through the network. Due to the large size of these networks, however, it is often impossible to employ a centralized traffic management. A natural assumption in the absence of central regulation is to assume that network users behave selfishly and aim at optimizing their own individual welfare. To understand such non-cooperative network systems, it is of great importance to investigate the selfish behavior of users and their influence on the performance of the entire network.

In this paper, we investigate the price of selfish behavior under game theoretic assumptions, that is, we assume that each *agent* (i.e., user) is aware of the situation facing all other agents and aims at optimizing its own strategy. In particular, we investigate the structure of the network in a *Nash equilibrium*, i.e., a combination of mixed (randomized) strategies from which no users has an incentive to deviate. It is well known that such equilibria may be inefficient and do not always optimize the overall performance (see, e.g., the Prisoner's dilemma [PY94]).

As proposed by Koutsoupias and Papadimitriou [KP99], we address the most basic case of a routing problem, a network consisting of m *parallel links* $1, 2, \dots, m$ from an origin to a destination, all with possibly different speeds s_1, \dots, s_m . There are n agents $1, 2, \dots, n$, each having an amount of traffic w_i to send from the origin to the destination. Each agent i sends the traffic using a possibly randomized *mixed strategy*, with p_i^j denoting the probability that agent i sends the entire traffic w_i to a link j . We assume the agents are *selfish* in the sense that each of them aims at minimizing its individual cost.

Assuming each agent is aware of the strategies of the other agents and behaves in a non-cooperative and selfish way, the system results in a Nash equilibrium. In an attempt to understand non-cooperative network systems, Koutsoupias and Papadimitriou [KP99] (see also, [Pap01a, Pap01b]) proposed to investigate the behavior of the worst-case *coordination ratio*, which is the ratio between the cost in the worst possible Nash equilibrium and the social (i.e., overall) optimum. In other words, this analysis seeks the price of uncoordinated individual decisions, the so-called price of anarchy.

We notice that the model considered in this paper is a simplification of the problems arising in real networks. However, as pointed out in [KP99, MS01, Pap01a], this model seems to be appropriate to describe several basic networking problems. We believe that understanding the ratio between worst possible Nash equilibrium and the social optimum in simple situations is necessary for making rigorous analyses in more complicated networks (see also the recent work of Roughgarden [Rou02] that gives an additional support to this claim). Readers interested in more detailed exposition of this model and in its applications are referred to [CKV02, KP99, MS01, Pap01a, Pap01b, RT02].

1.1 Model

We define now our model formally following the notation introduced by Koutsoupias and Papadimitriou [KP99].

The routing model described above can be formally defined as an allocation problem with m independent links with speeds s_1, \dots, s_m and n independent tasks with weights w_1, \dots, w_n . The goal is to allocate the tasks to the links to minimize the maximum load of the links in the system.

We use the notation $[N]$ to denote set $\{1, \dots, N\}$. The set of *pure strategies* for task i is therefore $[m]$ and a *mixed strategy* is a distribution on this set.

Given a combination $(j_1, \dots, j_n) \in [m]^n$ of pure strategies, one for each task, the *cost* for task i is

$$\sum_{j_k=j_i} \frac{w_k}{s_{j_i}},$$

which is the time needed for link j_i chosen by task i to complete all tasks allocated to that link¹.

Similarly, for a combination of pure strategies $(j_1, \dots, j_n) \in [m]^n$, the *load* of link j is defined as

$$\sum_{j_k=j} \frac{w_k}{s_j}.$$

Given n tasks of length w_1, \dots, w_n and m links of speed s_1, \dots, s_m , let *opt* denote the *social optimum*, that is, the minimum cost of a pure strategy:

$$\text{opt} := \min_{(j_1, \dots, j_n) \in [m]^n} \max_{j \in [m]} \sum_{i: j_i=j} \frac{w_i}{s_j}.$$

For example, if all links have the same unit speed ($s_j = 1$ for every $j \in [m]$) and all weights are the same ($w_i = 1$ for every $i \in [n]$), then the social optimum is $\lceil \frac{n}{m} \rceil$. Furthermore, it is easy to see that in any system

$$\text{opt} \geq \frac{\max_i w_i}{\max_j s_j}. \quad (1)$$

It is known that computing the social optimum is \mathcal{NP} -hard even for identical speeds (see [KP99]).

Let p_i^j denote the probability that an agent $i \in [n]$ sends the entire traffic w_i to a link $j \in [m]$. Let ℓ_j denote the *expected load* on a link $j \in [m]$, that is,

$$\ell_j := \frac{1}{s_j} \cdot \sum_{i \in [n]} w_i p_i^j.$$

For a task i , the *expected cost of task i on link j* (or its *finish time* when its load w_i is allocated to link j [KP99]) is equal to

$$c_i^j := \frac{w_i}{s_j} + \sum_{t \neq i} \frac{w_t p_t^j}{s_j} = \ell_j + (1 - p_i^j) \frac{w_i}{s_j}.$$

Definition 1.1 (Nash equilibrium) *The probabilities $(p_i^j)_{i \in [n], j \in [m]}$ define a Nash equilibrium if and only if any task i will assign non-zero probabilities only to links that minimize c_i^j , that is, $(p_i^j) > 0$ implies $c_i^j \leq c_i^q$, for every $q \in [m]$.*

In other words, a Nash equilibrium is characterized by the property that there is no incentive for any task to change its strategy. As an example, we observe that in the system considered above in which all links have the same unit speed and all weights are the same, the uniform probabilities $p_i^j = \frac{1}{m}$ for all $j \in [m]$ and $i \in [n]$ define a system in a Nash equilibrium. In general, the existence of such an

¹In the original formulation of Koutsoupias and Papadimitriou [KP99], an additional additive term L^{j_i} was used. However, since in all papers we are aware of all analyzes assumed $L^{j_i} = 0$, we skipped that term in our presentation. We want to point out, however, that our bounds are not affected by these additive terms.

equilibrium over mixed strategies for non-cooperative games was shown by Nash [Nas51]. In fact, the routing game considered in this paper admits an equilibrium even if all players are restricted to pure strategies. Rosenthal [Ros73] proved this property for a more general class of routing games by a simple, elegant potential function argument.

For the rest of the paper, we fix an arbitrary Nash equilibrium, that is, fix the probabilities $(p_i^j)_{i \in [n], j \in [m]}$ that define a Nash equilibrium. Let us consider the randomized allocation strategies in which each task i is allocated to a single link chosen independently at random according to the probabilities p_i^j , that is, task i is allocated to link j with probability p_i^j . Let C_j , $j \in [m]$, be the random variable indicating the *load of link j* in our random experiment. We observe that C_j is the weighted sum of independent 0-1 random variables J_i^j , $\Pr[J_i^j = 1] = p_i^j$, such that

$$C_j = \frac{1}{s_j} \sum_{i=1}^n w_i \cdot J_i^j . \quad (2)$$

Let c denote the *maximum expected load* over all links, that is,

$$c := \max_{j \in [m]} \ell_j .$$

Notice that $\mathbf{E}[C_j] = \ell_j$, and therefore $c = \max_{j \in [m]} \mathbf{E}[C_j]$.

Finally, we define the *social cost* C to be the expected maximum load (instead of maximum expected load), that is,

$$C := \mathbf{E}[\max_{j \in [m]} C_j] .$$

Observe that $c \leq C$ and possibly $c \ll C$. Recall that opt denotes the *social optimum* (i.e., the minimum cost of a pure strategy). In this paper our main focus is on estimating the *coordination ratio* which is the worst-case ratio

$$R := \max \frac{C}{\text{opt}} ,$$

where the maximum is over all Nash equilibria.

1.2 Previous results

Koutsoupias and Papadimitriou [KP99] initiated the study of the worst-case coordination ratio and showed the following results for networks consisting of m parallel links:

- For two identical links the worst-case coordination ratio is exactly $\frac{3}{2}$.
- For two links (not necessarily identical, that is, with possibly different speeds) the worst-case coordination ratio is at least $\phi = \frac{1+\sqrt{5}}{2}$.
- For m identical links the worst-case coordination ratio is $\Omega(\frac{\log m}{\log \log m})$ and it is at most $3 + \sqrt{4m \ln m}$.
- The worst-case coordination ratio for any number of tasks and m (not necessarily identical) links is $\mathcal{O}(\sqrt{\frac{s_1}{s_m} \sum_{j=1}^m \frac{s_j}{s_m}} \sqrt{\log m})$, where s_j is the speed of link j , and $s_1 \geq s_2 \geq \dots \geq s_m$.

Mavronicolas and Spirakis [MS01] greatly extended some of the bounds above and show the following results in the so-called *fully-mixed model*²:

- For m identical links in the fully-mixed Nash equilibrium the worst-case coordination ratio is $\Theta\left(\frac{\log m}{\log \log m}\right)$.
- For m (not necessarily identical) links and n identical weights in the fully-mixed Nash equilibrium, if $m \leq n$, then the worst-case coordination ratio is $\Theta\left(\frac{\log n}{\log \log n}\right)$.

We emphasize that besides the very special case of $m = 2$ parallel links, no asymptotically tight results have been known even for systems with identical links. In particular, even the main conjecture from the work of Koutsoupias and Papadimitriou [KP99] that the worst-case coordination ratio for m identical links is $\Theta\left(\frac{\log m}{\log \log m}\right)$, has remained unproved prior to our work.

1.3 New results

Our first result is an upper bound for the worst-case coordination ratio.³

Theorem 1 *The coordination ratio for m parallel links is bounded from above by*

$$\mathcal{O}\left(\min\left\{\frac{\log m}{\log \log \log m}, \frac{\log m}{\log\left(\frac{\log m}{\log(s_1/s_m)}\right)}\right\}\right),$$

where it is assumed that the speeds satisfy $s_1 \geq \dots \geq s_m$.

In particular, the worst-case coordination ratio for m parallel links is

$$\mathcal{O}\left(\frac{\log m}{\log \log \log m}\right).$$

The theorem follows directly from the following two lemmas.

Lemma 1.2 *The maximum expected load c satisfies*

$$c = \text{opt} \cdot \mathcal{O}\left(\min\left\{\frac{\log m}{\log \log m}, \log\left(\frac{s_1}{s_m}\right)\right\}\right),$$

where it is assumed that the speeds satisfy $s_1 \geq \dots \geq s_m$.

Lemma 1.3 *The social cost C satisfies*

$$C = \text{opt} \cdot \mathcal{O}\left(\frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)} + 1\right).$$

²The *fully-mixed model* is a special class of Nash equilibria in which all p_i^j are non-zero.

³To simplify the notation, throughout the entire paper, for any non-negative real x we shall use $\log x$ to denote $\log x = \max\{\log_2 x, 1\}$.

Lemmas 1.2 and 1.3 give also some interesting results for a few special cases. We first state their applications for systems in which all agents follow only *pure strategies*. Since in that case, $\ell_j = C_j$ for every $j \in [m]$, we also have $C = c$. Therefore Lemma 1.2 gives immediately the following result.

Corollary 1.4 *For pure strategies the worst-case coordination ratio for m parallel links is bounded from above by*

$$\mathcal{O} \left(\min \left\{ \frac{\log m}{\log \log m}, \log \left(\frac{s_1}{s_m} \right) \right\} \right),$$

where it is assumed that the speeds satisfy $s_1 \geq \dots \geq s_m$. □

Theorem 3 below proves that this corollary gives an asymptotically tight bound for the worst-case coordination ratio for pure strategies.

Furthermore, by Theorem 1, in the special case when all links are identical, the coordination ratio is $\mathcal{O} \left(\frac{\log m}{\log \log m} \right)$. Recently, and independently of our work, also Koutsoupias et al. [KMS02] obtained the same upper bound. However, in this special case we get a much stronger bound that is actually tight up to an additive constant.

Theorem 2 *For m identical links the worst-case coordination ratio is at most*

$$\Gamma^{(-1)}(m) + \Theta(1) = \frac{\log m}{\log \log m} \cdot (1 + o(1)).$$

In Theorem 2 we use standard notation to denote by $\Gamma(N)$ the *Gamma (factorial) function*, which for any natural number N is defined by $\Gamma(N+1) = N!$ and for an arbitrary real number $x > 0$ is defined as $\Gamma(x) = \int_0^\infty t^{x-1} e^{-t} dt$. We shall use frequently the inverse of the Gamma function, $\Gamma^{(-1)}(N)$, where for our applications we shall use the fact that $\Gamma^{(-1)}(N) = x$ such that $\lfloor x \rfloor! \leq N - 1 \leq \lceil x \rceil!$. It is well known that $\Gamma^{(-1)}(N) = \frac{\log N}{\log \log N} (1 + o(1))$ and that $(\alpha/e)^\alpha = N$ for $\alpha = \Gamma^{(-1)}(N) + \Theta(1)$.

The bound in Theorem 2 improves upon the result due to Mavronicolas and Spirakis [MS01], not only by extending the class of Nash equilibria for which the upper bound holds, but also by tightening the result up to a constant additive factor. Indeed, as it was observed by Koutsoupias and Papadimitriou [KP99] and by Mavronicolas and Spirakis [MS01], one can obtain a lower bound for the worst-case coordination ratio for m identical links by considering the system in which all $n = m$ tasks have $p_i^j = \frac{1}{m}$ for every $i, j \in [n]$; the classical result of Gonnet [Gon81] implies that in such a system the worst-case coordination ratio is $\Gamma^{(-1)}(m) - \frac{3}{2} + o(1)$.

Furthermore, we prove that the upper bound in Theorem 1 is asymptotically tight.

Theorem 3 *The coordination ratio for m parallel links is lower bounded by*

$$\Omega \left(\min \left\{ \frac{\log m}{\log \log \log m}, \frac{\log m}{\log \left(\frac{\log m}{\log(s_1/s_m)} \right)} \right\} \right).$$

In particular, the worst-case coordination ratio for m parallel links is

$$\Omega \left(\frac{\log m}{\log \log \log m} \right).$$

In fact, we will show, analogously to the upper bound, that for every positive integer m , positive real r , and $S \geq 1$, there exists a set of m links with $\frac{s_1}{s_m} = S$ being in a Nash equilibrium and satisfying

- (i) $\text{opt} = r$,
- (ii) $c = \text{opt} \cdot \Omega\left(\min\left\{\frac{\log m}{\log \log m}, \log\left(\frac{s_1}{s_m}\right)\right\}\right)$, and
- (iii) $C = \text{opt} \cdot \Omega\left(\frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)}\right)$.

Combining Theorems 1 and 3 we obtain an asymptotically tight bound for the worst-case coordination ratio for m parallel links.

1.4 Organization

To provide some intuition behind our proofs, we begin in Section 2 with a simple proof that for identical links the worst-case coordination ratio is $\mathcal{O}(\log m / \log \log m)$. Then, in Section 3, we present a proof Theorem 1. The proof follows from Lemmas 1.2 and 1.3 that are proven in Sections 3.1 and 3.2. Then, in Section 3.3, we extend arguments used in Sections 3.1 and 3.2 to prove Theorem 2 that gives a tight upper bound for the worst-case coordination with identical links. In Section 4 we prove Theorem 3, a lower bound for the worst-case coordination ratio. In our proof we first investigate in Section 4.1 pure strategies and then in Section 4.2 we extend our analysis to mixed strategies.

2 Warm up: Simple analysis for identical links

In this section we present some basic ideas behind our proofs for the upper bound on the example of the system with identical links. We show that for m identical links the worst-case coordination ratio is at most $\mathcal{O}(\log m / \log \log m)$. The same upper bound was presented by Koutsoupias et al. [KMS02] with a significantly longer proof. Later, in Section 3.3, we further tighten this bound and show that for m identical links the worst-case coordination ratio is exactly $\Gamma^{(-1)}(m) + \Theta(1)$ (Theorem 2).

Let us begin with a simple property of Nash equilibria that will be used frequently in our analysis.

Claim 2.1 *In an arbitrary Nash equilibrium, if $p_i^q > 0$ for certain $i \in [n]$ and $q \in [m]$, then $\ell_j + \frac{w_i}{s_j} \geq \ell_q$ for every $j \in [m]$. In particular, if $\ell_j + 1 < \ell_q$ then $w_i > s_j$.*

(Actually, the same proof implies that if $p_i^j > 0$ and $p_i^q > 0$, then $|\ell_j - \ell_q| \leq \text{opt}$.)

Proof: First, let us notice that $c_i^j \leq \ell_j + \frac{w_i}{s_j}$ and $c_i^q = \ell_q + (1 - p_i^q) \frac{w_i}{s_q} \geq \ell_q$. Therefore, since $p_i^q > 0$, the definition of Nash equilibria implies that $c_i^q \leq c_i^j$ and hence, $\ell_q \leq \ell_j + \frac{w_i}{s_j}$.

The second part of the claim follows trivially from the first one. \square

Now, we are ready to proceed with the analysis of the worst-case coordination ratio for m identical links. Let us first re-scale the weights and speeds in the problem and assume, without loss of generality, that all speeds are identical and equal to 1 and that the social optimum is $\text{opt} = 1$.

Since $\text{opt} = 1$, then, by (1), we must have

$$w_i \leq 1 \quad \text{for all } i \in [n] .$$

Furthermore, by Claim 2.1, the assumption that the system is in a Nash equilibrium implies that (see also [KP99, Theorem 7])

$$c = \max_{j \in [m]} \ell_j < 2 \quad \text{for all } j \in [m] . \quad (3)$$

Next, to estimate the load C_j of any link $j \in [m]$ we apply to (2) a standard concentration inequality due to Hoeffding⁴ to obtain the following bound that holds for any $t > 0$:

$$\Pr[C_j \geq t] \leq (e \cdot \mathbf{E}[C_j]/t)^t \leq (2e/t)^t ,$$

where the last inequality follows from the fact that $\mathbf{E}[C_j] = \ell_j$ and $\ell_j < 2$.

Therefore, if we pick $t \geq 3 \ln m / \ln \ln m$, then $\Pr[C_j \geq t] \ll 1/m$ and therefore it is intuitively clear that $C = \mathbf{E}[\max_{j \in [m]} C_j] = \mathcal{O}(t)$. The following inequalities prove this more formally.

$$C = \mathbf{E}[\max_{j \in [m]} C_j] \leq t + \sum_{\tau=t}^{\infty} \Pr[\exists_{j \in [m]} C_j \geq \tau] \leq t + \sum_{\tau=t}^{\infty} m \cdot (2e/\tau)^\tau \leq t + \sum_{\tau=t}^{\infty} 2^{-\tau} \leq t + 1 .$$

Thus, we can summarize the discussion in this section with the following theorem.

Theorem 4 *For m identical links the worst-case coordination ratio is $\mathcal{O}(\log m / \log \log m)$.* \square

3 Upper bound: Proof of Theorem 1

In this section we prove Lemmas 1.2 and 1.3, from which Theorem 1 directly follows. Our proofs follow similar arguments as those used in Section 2. The difficulty with extending the proof from the previous section directly stems from the fact that for non-identical links we do not have a simple characterization for the upper bound of w_i and c . The main idea behind our proofs in Lemmas 1.2 and 1.3 is to provide good bounds for these two values: Lemma 1.2 gives a tight upper bound for the value of c and the main part of Lemma 1.3 is to provide a good bound for the values of w_i (see, Lemma 3.6).

3.1 Proof of Lemma 1.2

Fix an arbitrary Nash equilibrium, that is, fix the probabilities $(p_i^j)_{i \in [n], j \in [m]}$ that define a Nash equilibrium. Without loss of generality, assume $s_1 \geq s_2 \geq \dots \geq s_m$. Let us normalize (scale) the weights of all tasks such that $\text{opt} = 1$. Under this normalization, we have to show that $c = \mathcal{O}(\frac{\log m}{\log \log m})$ and $c = \mathcal{O}\left(\log\left(\frac{s_1}{s_m}\right)\right)$. We prove these bounds in two separate Lemmas 3.1 and 3.4.

Lemma 3.1 $c \leq \Gamma^{(-1)}(m) + 1 = \frac{\log m}{\log \log m} (1 + o(1))$.

⁴In this paper we use the following standard version of Hoeffding bound [Hoe63]: Let X_1, \dots, X_N be independent random variables with values in the interval $[0, z]$ for some $z > 0$, and let $X = \sum_{i=1}^N X_i$, then for any t it holds that $\Pr[\sum_{i=1}^N X_i \geq t] \leq (e \cdot \mathbf{E}[X] / t)^{t/z}$.

Proof : For $k \geq 1$, define j_k to be the smallest index in $\{0, 1, \dots, m\}$ such that $\ell_{j_k+1} < k$ or, if no such index exists, $j_k = m$. Let us observe that the following properties hold:

- for every $k \geq 1$ with $0 < j_k \leq m$, all links $j \leq j_k$ have load at least k , and
- for every $k \geq 1$ with $0 \leq j_k < m$, link $j_k + 1$ has load less than k .

Let $c^* = \lfloor c - 1 \rfloor$. We will show that $j_1 \geq c^*$. Combining this inequality with the obvious constraint $j_1 \leq m$ will imply the asserted upper bound on c .

In order to estimate j_1 , we start with estimating j_{c^*} . Observe that link 1 does not need to be the link with highest expected load. The following claim, however, shows that ℓ_1 is close to c^* .

Claim 3.2 $j_{c^*} \geq 1$, and hence $\ell_1 \geq c^*$.

Proof : For the purpose of contradiction, assume $j_{c^*} = 0$. This implies that $\ell_1 < c^* \leq c - 1$. Let q denote the link with the maximum expected load. Then $\ell_1 + 1 < c = \ell_q$.

We observe that all the tasks that have positive probability on q must have weight larger than s_1 . Indeed, if one such a task i had weight $w_i \leq s_1$, then it would have expected cost on link 1 to be at most $\ell_1 + \frac{w_i}{s_1} \leq \ell_1 + 1 < \ell_q$, which contradicts to Claim 2.1.

Thus, we have shown the existence of a task i of weight $w_i > s_1$. This and inequality (1) contradict our initial assumption that $\text{opt} = 1$. This completes the proof of Claim 3.2. \square

The next claim gives a lower bound on j_k in terms of j_{k+1} .

Claim 3.3 For $k \geq 1$, $j_k \geq (k + 1)j_{k+1}$.

Proof : Let T be the set of tasks in the system that have positive probability on at least one of the links in $\{1, \dots, j_{k+1}\}$. Fix an optimal allocation strategy OPTStr . We distinguish between two different ways of how OPTStr might allocate the tasks in T to the links.

Case 1: Suppose OPTStr allocates at least one of the tasks in T to a link j , $j > j_k$. We will show that this implies $\text{opt} > 1$ and hence contradicts our assumptions.

Let W_T denote the minimum weight of the tasks in T . We first derive a lower bound on W_T . The expected load of the links in $\{1, \dots, j_{k+1}\}$ (and hence of all links in T) is at least $k + 1$. The expected load of link $j_k + 1$ is less than k . Therefore, the requirement of Nash equilibria yields $W_T > s_{j_k+1}$. But this implies that allocating a task from T to link j gives cost at least $\frac{W_T}{s_j} \geq \frac{W_T}{s_{j_k+1}} > 1$ which by (1) yields $\text{opt} > 1$ and hence a contradiction.

Case 2: Now let us assume OPTStr allocates all tasks in T to the links in $\{1, \dots, j_k\}$. We will show that this implies $j_k \geq (k + 1)j_{k+1}$.

Let $W_{\Sigma T}$ denote the sum of the weights of the tasks in T . On one hand, we observe that $W_{\Sigma T}$ is lower bounded by the sum of the expected weight on the links $\{1, \dots, j_{k+1}\}$, that is,

$$W_{\Sigma T} = \sum_{i \in T} w_i \geq \sum_{i \in T} w_i \cdot \sum_{j=1}^{j_{k+1}} p_i^j = \sum_{j=1}^{j_{k+1}} \sum_{i \in T} w_i p_i^j = \sum_{j=1}^{j_{k+1}} \sum_{i=1}^n w_i p_i^j = \sum_{j=1}^{j_{k+1}} \ell_j s_j .$$

Therefore, since $\ell_j \geq k + 1$ for all $j \leq j_{k+1}$, we obtain

$$W_{\Sigma T} \geq \sum_{j=1}^{j_{k+1}} \ell_j s_j \geq (k+1) \sum_{j=1}^{j_{k+1}} s_j .$$

On the other hand, since we assumed that $\text{opt} = 1$ and OPTStr allocates all tasks in T to the links $\{1, \dots, j_k\}$, we obtain

$$W_{\Sigma T} \leq \sum_{j=1}^{j_k} s_j .$$

Combining these inequalities gives $\sum_{j=1}^{j_k} s_j \geq (k+1) \sum_{j=1}^{j_{k+1}} s_j$. Since the sequence of link speeds is non-increasing, this implies that $j_k \geq (k+1) j_{k+1}$. This completes the proof of Claim 3.3. \square

Finally, we combine the two claims above and obtain

$$j_1 \geq (c^*)! \cdot j_{c^*} \geq (c^*)! .$$

By definition, $j_1 \leq m$. Consequently $(c^*)! \leq m$, which implies $c \leq \Gamma^{(-1)}(m) + 1 = \frac{\log m}{\log \log m} (1 + o(1))$. This completes the proof of Lemma 3.1. \square

Next, we prove another upper bound for the maximum expected cost c .

Lemma 3.4 $c = \mathcal{O}(\log(s_1/s_m))$.

Proof : The following claim shows that the speeds of the links j_1, j_2, \dots increase in a geometric fashion.

Claim 3.5 For $1 \leq k \leq c - 3$, $s_{j_{k+2}+1} \geq 2 s_{j_{k+1}}$.

Proof : Fix an optimal strategy OPTStr . Notice that every link $j' \leq j_{k+2}$ has cost $\ell_{j'} \geq (k+2) > 1 = \text{opt}$. Therefore, OPTStr has to allocate at least one of the tasks that has positive probability on one of the links $1, \dots, j_{k+2}$ to the links $j_{k+2}+1, \dots, m$. (Observe that in Claim 3.2 it is shown that $j_{\lfloor c-1 \rfloor} \geq 1$. Hence, the existence of link $j_{k+2} \geq j_{\lfloor c-1 \rfloor}$ is guaranteed.) Clearly, such a task can have weight at most $s_{j_{k+2}+1}$ because otherwise the cost of OPTStr would be larger than opt . Therefore, there exists a link $j \in \{1, \dots, j_{k+2}\}$ and a task i of weight $w_i \leq s_{j_{k+2}+1}$ with $p_i^j > 0$.

Given that, on one hand, the expected cost of task i on link j in the Nash equilibrium is at least $k+2$ because, for $j \leq j_{k+2}$, we have $c_i^j \geq \ell_j \geq k+2$. On the other hand, the expected cost of task i on link j_k+1 is $c_i^{j_k+1} < k + w_i/s_{j_k+1}$. Now, the Nash equilibrium property implies that the cost of task i on link j is not larger than on j_k+1 . Consequently, $k+2 \leq k + w_i/s_{j_k+1} \leq k + s_{j_{k+2}+1}/s_{j_k+1}$. Clearly, this inequality implies that $2s_{j_k+1} \leq s_{j_{k+2}+1}$ and hence, Claim 3.5 is shown. \square

Claim 3.5 says that in a Nash equilibrium the speeds increase geometrically with the expected load. This implies that

$$s_m \leq s_{j_1} \leq 2^{-(c-5)/2} \cdot s_{c-1} \leq 2^{-(c-5)/2} \cdot s_1 .$$

Thus, $c \leq 2 \log(s_1/s_m) + \mathcal{O}(1)$. This completes the proof of Lemma 3.4. \square

We conclude the proof of Lemma 1.2 by observing that it follows directly from Lemmas 3.1 and 3.4. \square

3.2 Proof of Lemma 1.3

Without loss of generality, let us assume that $s_1 \geq s_2 \geq \dots \geq s_m$. Recall (see (2)) that C_j is a random variable describing the load on link j . We have $\mathbf{E}[C_j] = \ell_j \leq c$ and $C = \mathbf{E}[\max_{j \in [m]} C_j]$. Our goal is to show, for every $j \in [m]$, that it is unlikely that C_j deviates much from its expectation. For this purpose, we will use a Hoeffding bound. In order to apply this bound, we need to show that the weights of the tasks assigned to link j cannot be much larger than s_j . This is shown in the next lemma.

Lemma 3.6 *For every link j and every task i with $p_i^j \in (0, \frac{1}{4}]$, $w_i \leq 12 \cdot s_j \cdot \text{opt}$.*

Proof : Previously, in the proof of Lemma 1.2, we defined indices j_r provided $\text{opt} = 1$. Now, we extend this definition to hold for arbitrary opt in natural way: for $k \geq 1$, we define j_k as the smallest index in $\{0, 1, \dots, m\}$ such that $\ell_{j_{k+1}} < k \cdot \text{opt}$, or, $j_k = m$ if no such index exists.

With this modification, we first observe that Claim 3.5 holds without any change. We will apply Claim 3.5 to show that $w_i \leq 12 \cdot s_j \cdot \text{opt}$ for $p_i^j \in (0, \frac{1}{4}]$. First, assume that $j \in \{j_k + 1, \dots, j_{k-1}\}$ for some $k \leq c - 3$. Then, on one hand, the expected cost of task i on link j is

$$c_i^j = \ell_j + (1 - p_i^j) \frac{w_i}{s_j} \geq (k - 1) \cdot \text{opt} + \frac{3w_i}{4s_j},$$

because $\ell_j \geq (k - 1) \text{opt}$ and $1 - p_i^j \geq \frac{3}{4}$. On the other hand, the expected cost of task i on link $j_{k+2} + 1$ is

$$c_i^{j_{k+2}+1} \leq \ell_{j_{k+2}+1} + \frac{w_i}{s_{j_{k+2}+1}} \leq (k + 2) \cdot \text{opt} + \frac{w_i}{2s_j},$$

by applying $\ell_{j_{k+2}+1} \leq (k + 2) \text{opt}$, $s_{j_{k+2}+1} \geq 2s_{j_k+1}$ (Claim 3.5), and $s_{j_k+1} \geq s_j$. Since we assume the system is in a Nash equilibrium, the cost of task i on link j cannot be larger than the cost of task i on link $j_{k+2} + 1$. Consequently, $(k - 1) \text{opt} + \frac{3w_i}{4s_j} \leq (k + 2) \text{opt} + \frac{w_i}{2s_j}$, which implies $w_i \leq 12 \cdot s_j \cdot \text{opt}$.

It remains to investigate the case $j \leq j_k$, where $k = \lfloor c - 3 \rfloor$. We observe that the expected cost of task i on the fastest link s_1 is at most $c \cdot \text{opt} + \text{opt} = (c + 1) \cdot \text{opt}$. The expected cost of task i on link j , however, is at least $k \cdot \text{opt} + \frac{3w_i}{4s_j} \geq (c - 4) \cdot \text{opt} + \frac{3w_i}{4s_j}$. Hence, in this case $w_i \leq \frac{20}{3} \cdot s_j \cdot \text{opt}$. This proves Lemma 3.6. \square

Now let us focus on a single link $j \in [m]$. We apply the lemma in order to show that it is unlikely that C_j deviates much from its expectation. Let $T_j^{(1)}$ denote the set of tasks with $p_i^j \in (0, \frac{1}{4}]$ and $T_j^{(2)}$ the set of tasks with $p_i^j \in (\frac{1}{4}, 1]$. Furthermore, let $C_j^{(1)}$ and $C_j^{(2)}$ denote random variables that describe the cost on link j only counting tasks in $T_j^{(1)}$ and $T_j^{(2)}$, respectively. Clearly, only tasks with $p_i^j > 0$ can be allocated to link j . Hence, $C_j = C_j^{(1)} + C_j^{(2)}$.

First, let us consider the tasks in $T_j^{(1)}$ only. Recall that C_j is defined as the weighted sum of independent 0-1 random variables J_i^j , see (2). Thus, $C_j^{(1)}$ is a weighted sum of independent 0-1 random variables as well. Next, by Lemma 3.6, we can bound the maximum weight in this sum by $\max_{i \in T_j^{(1)}} \frac{w_i}{s_j} \leq 12 \cdot \text{opt}$. Hence, we can apply the Hoeffding bound from Section 2. For every $\alpha > 1$, we obtain

$$\Pr[C_j^{(1)} \geq \alpha \cdot \text{opt}] \leq \left(\frac{e \cdot \mathbf{E}[C_j^{(1)}]}{\alpha \cdot \text{opt}} \right)^{\alpha \cdot \text{opt} / (12 \cdot \text{opt})} \leq \left(\frac{e \cdot c}{\alpha \cdot \text{opt}} \right)^{\alpha / 12}.$$

Now, let us consider the tasks in $T_j^{(2)}$. Since $p_i^j \geq \frac{1}{4}$ for every $i \in T_j^{(2)}$, we immediately obtain $C_j^{(2)} \leq 4\mathbf{E}[C_j^{(2)}] \leq 4c$. Hence, for every $\alpha > 1$,

$$\Pr[C_j \geq 4 \cdot c + \alpha \cdot \text{opt}] \leq \left(\frac{e \cdot c}{\alpha \cdot \text{opt}} \right)^{\alpha/12}.$$

Until now we focused on a single, fixed link. Summing over all m links, by the union bound, the probability that the maximum cost $\mathcal{L} = \max_{j \in [m]} C_j$ does exceed $4 \cdot c + \alpha \cdot \text{opt}$ can be upper bounded by $m \cdot (e \cdot c / (\alpha \cdot \text{opt}))^{\alpha/12}$. Recall that C is defined to be the expectation of the maximum cost over all links. Hence, for every $\lambda > 1$, we can estimate C as follows.

$$\begin{aligned} C = \mathbf{E}[\mathcal{L}] &\leq 4 \cdot c + \lambda \cdot \text{opt} + \text{opt} \cdot \int_0^\infty \Pr[\mathcal{L} \geq 4c + (\lambda + t) \text{opt}] dt \\ &\leq 4 \cdot c + \lambda \cdot \text{opt} + \text{opt} \cdot m \cdot \int_0^\infty \left(\frac{e \cdot c}{(\lambda + t) \cdot \text{opt}} \right)^{(\lambda+t)/12} dt \\ &\leq 4 \cdot c + \lambda \cdot \text{opt} + \text{opt} \cdot m \cdot \left(\frac{e \cdot c}{\lambda \cdot \text{opt}} \right)^{\lambda/12} \cdot \int_0^\infty \left(\frac{e \cdot c}{\lambda \cdot \text{opt}} \right)^{t/12} dt. \end{aligned}$$

Notice that for $\lambda \geq 21 \cdot e \cdot \frac{c}{\text{opt}}$ we have $\int_0^\infty \left(\frac{e \cdot c}{\lambda \cdot \text{opt}} \right)^{t/12} dt = \frac{12}{\ln\left(\frac{\lambda \cdot \text{opt}}{e \cdot c}\right)} \leq 4$, and therefore we obtain

$$C \leq 4 \cdot c + \lambda \cdot \text{opt} + 4 \cdot \text{opt} \cdot m \cdot \left(\frac{e \cdot c}{\lambda \cdot \text{opt}} \right)^{\lambda/12}.$$

Moreover, for $\lambda \geq \frac{c}{\text{opt}} \cdot (2 + \Gamma^{(-1)}(e \cdot m^{12 \cdot \text{opt}/c}))$, we can show that $\left(\frac{e \cdot c}{\lambda \cdot \text{opt}} \right)^{\lambda/12} \leq \frac{1}{m}$. To prove this inequality, let us set $\lambda_0 = \frac{c}{\text{opt}} \cdot \lceil 1 + \Gamma^{(-1)}(e \cdot m^{12 \cdot \text{opt}/c}) \rceil$. Next, we observe that $(k/e)^k \geq (k-1)! \cdot e^{-1}$ for any integer $k \geq 1$ (this can be easily proven by induction) and therefore $\left(\frac{\lambda_0 \cdot \text{opt}}{e \cdot c} \right)^{\lambda_0 \cdot \text{opt}/c} \geq \left(\frac{\lambda_0 \cdot \text{opt}}{e \cdot c} - 1 \right)! \cdot e^{-1}$. Since our setting of λ_0 ensures that $\left(\frac{\lambda_0 \cdot \text{opt}}{e \cdot c} - 1 \right)! \cdot e^{-1} \geq m^{12 \cdot \text{opt}/c}$, we can conclude that for any $\lambda \geq \lambda_0$ we have

$$\left(\frac{\lambda \cdot \text{opt}}{e \cdot c} \right)^{\lambda/12} \geq \left(\frac{\lambda_0 \cdot \text{opt}}{e \cdot c} \right)^{\lambda_0/12} = \left(\left(\frac{\lambda_0 \cdot \text{opt}}{e \cdot c} \right)^{\lambda_0 \cdot \text{opt}/c} \right)^{c/(12 \cdot \text{opt})} \geq (m^{12 \cdot \text{opt}/c})^{c/(12 \cdot \text{opt})} = m.$$

Therefore, if we set⁵

$$\begin{aligned} \lambda &= \max \left\{ 21 \cdot e \cdot \frac{c}{\text{opt}}, \frac{c}{\text{opt}} \cdot (2 + \Gamma^{(-1)}(e \cdot m^{12 \cdot \text{opt}/c})), 1 \right\} \\ &= \mathcal{O} \left(\frac{c}{\text{opt}} + \frac{c}{\text{opt}} \cdot \frac{\log(m^{\text{opt}/c})}{\log(\log(m^{\text{opt}/c}))} + 1 \right) = \mathcal{O} \left(\frac{c}{\text{opt}} + \frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)} + 1 \right), \end{aligned}$$

then we obtain

$$C \leq 4 \cdot c + \lambda \cdot \text{opt} + 4 \cdot \text{opt} = \text{opt} \cdot \mathcal{O} \left(\frac{c}{\text{opt}} + \frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)} + 1 \right).$$

⁵Recall that $\log x$ abbreviates $\max\{\log_2 x, 1\}$.

If $c \leq \text{opt}$, then the inequality above immediately yields Lemma 1.3. Now suppose $c > \text{opt}$. By Lemma 3.1, we have $\frac{c}{\text{opt}} = \mathcal{O}\left(\frac{\log m}{\log \log m}\right)$ which, for $c > \text{opt}$, is bounded by $\mathcal{O}\left(\frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)}\right)$. Hence,

$$C = \text{opt} \cdot \mathcal{O}\left(\frac{c}{\text{opt}} + \frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)} + 1\right) = \text{opt} \cdot \mathcal{O}\left(\frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)} + 1\right).$$

This concludes the proof of Lemma 1.3. \square

3.3 Extension of Lemma 1.3 for identical links: Proof of Theorem 2

It is easy to simplify the proof and to improve Lemma 1.3 when all links are identical, that is, all s_j are the same. In that case, one can assume without loss of generality that $\text{opt} = 1$ and $s_j = 1$ for every $j \in [m]$. Let T^j , $j \in [m]$, denote the set of all tasks i with $p_i^j > 0$. Given that, we can show the following lemma.

Lemma 3.7 *In systems with identical links it holds that $p_i^j w_i \geq \ell_j - 1$ for all $j \in [m]$, $i \in T^j$.*

Proof : We use similar arguments as in the proof of Lemma 3.6. The cost of task i on link j is $c_i^j = \ell_j + (1 - p_i^j) w_i$. Let q be any link with $\ell_q \leq \frac{1}{m} \sum_{r \in [j]} \ell_r$. Clearly, $\ell_q \leq 1$ and hence $c_i^q \leq 1 + w_i$. Now, the lemma follows from the requirement $c_i^j \leq c_i^q$ of Nash equilibria. \square

We consider two separate cases. Suppose first that $\ell_j - 1 \geq 2/\Gamma^{(-1)}(m)$. Notice that Lemma 3.7 implies that $\ell_j = \sum_{i \in T^j} p_i^j w_i \geq |T^j| \cdot (\ell_j - 1)$. Since we have $\ell_j < 2$ (see inequality (3)) and $1/(\ell_j - 1) \leq \Gamma^{(-1)}(m)/2$, we obtain $|T^j| \leq \ell_j/(\ell_j - 1) \leq \Gamma^{(-1)}(m)$. This inequality immediately implies $C_j \leq \Gamma^{(-1)}(m)$ because in this case at most $\Gamma^{(-1)}(m)$ tasks have positive probability on link j . The other case we have to consider is when $\mathbf{E}[C_j] = \ell_j \leq 1 + 2/\Gamma^{(-1)}(m)$. Here, applying Hoeffding bound in the same way as it is done in the proof of Lemma 1.3 yields $C_j \leq \Gamma^{(-1)}(m) + \mathcal{O}(1)$, with probability at least $1 - \frac{1}{m}$. This immediately implies Theorem 2. \square

4 Lower bound: Proof of Theorem 3

This section is devoted to the proof of Theorem 3, which states that our upper bounds proven in the previous section are essentially tight.

Our analysis follows a course similar to the one for the upper bound in the previous section. First, we will describe a mixed strategy in Nash equilibrium with $\text{opt} = \Theta(1)$ and $c = \Theta\left(\frac{\log m}{\log \log m}\right)$. Then, we apply a stochastic analysis showing $C = c \cdot \Theta\left(\frac{\log m}{\log\left(\frac{\log m}{\log \log m}\right)}\right)$. Finally, we will take into account also the speeds of the links in our construction. Combining these bounds yields the theorem.

In fact, our construction can be easily generalized to show that for every integer m , every positive real r and every $S \geq 1$, there exists a set of m links with $\frac{s_1}{s_m} = S$ having a Nash equilibrium satisfying $c = \Omega\left(\text{opt} \cdot \min\left\{\frac{\log m}{\log \log m}, \log\left(\frac{s_1}{s_m}\right)\right\}\right)$, $C = \text{opt} \cdot \Omega\left(\frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)}\right)$, and $\text{opt} = r$.

4.1 Lower bound for pure strategies

We start by defining a pure strategy \mathcal{S} that we will transform afterwards into a mixed strategy \mathcal{S}' . Without loss of generality, let \sqrt{m} be an integer. We consider $K + 1$ groups of links $0, 1, \dots, K$, for a suitable K to be defined later. The groups are defined as follows:

- for $1 \leq k \leq K$, the number of links in group k is equal to $\sqrt{m} \cdot \frac{K!}{k!}$ (notice that for $1 \leq k < K$ the number of links in group k is exactly $(k + 1)$ times the number of links in group $k + 1$),
- the number of links in group 0 is at least $\sqrt{m} \cdot K!$,
- for $0 \leq k \leq K$, the speed of the links in group k is 2^k ,
- for $0 \leq k \leq K$, for each link in group k , there are exactly k tasks of weight 2^k each having probability one to be allocated to this link.

In our construction K can be chosen to be any positive integer that satisfies $\sqrt{m} \cdot \sum_{k=0}^K \frac{K!}{k!} \leq m$. Thus, in particular, our analysis can be carried over for all K satisfying $\sqrt{m} \cdot K! \cdot e \leq m$, and hence, for all $K \leq \Gamma^{(-1)}(\sqrt{m}/e) - 1 = \Theta(\log m / \log \log m)$.

Lemma 4.1 *Strategy \mathcal{S} satisfies the following properties:*

1. *the maximum load is $c = K$,*
2. *the social optimum is $1 \leq \text{opt} \leq 2$, and*
3. *the system is in Nash equilibrium.*

Proof :

1. This property follows from the fact that if a link j is in group k then its load is $C_j = \frac{k2^k}{s_j} = k$.
2. The social optimum cost 2 can be achieved, for example, by allocating all tasks “assigned” to the links in group k , $k \geq 1$, to the links in group $k - 1$. Observe that there are exactly $k \cdot \sqrt{m} \cdot \frac{K!}{k!}$ tasks assigned initially to the links in group k , $k > 0$ (and zero tasks assigned to the links in group 0) and each such a task has weight 2^k . On the other hand, there is at least the same number $\sqrt{m} \cdot \frac{K!}{(k-1)!}$ of links in group $k - 1$, each link with speed 2^{k-1} . Therefore, if we allocate each task from group k to a single link in group $k - 1$, then since the weight of each task is 2^k and the speed of each link is 2^{k-1} , the cost of every link in the system is at most 2. Hence, the social optimum is at most 2.

To see the lower bound for opt , let us observe that any task i in group K has weight $w_i = 2^K$ and the fastest link j has speed $s_j = 2^K$. This implies that the social optimum cannot be smaller than $\frac{w_i}{s_j} = 1$.

3. Let us take any task i that is allocated to link r in group $k \geq 1$ and let j be any link, $j \neq r$, in group t , $0 \leq t \leq K$. In order to prove that the system is in a Nash equilibrium, we must prove only that $c_i^j \geq c_i^r$. Observe that $c_i^r = k$ and $c_i^j = l_j + \frac{w_i}{s_j} = t + 2^{k-t}$. As $t + 2^{k-t} \geq k$ for any non-negative t and r , none of the tasks allocated to r has an incentive to migrate to another link. Therefore, by Definition 1.1, the system is in a Nash equilibrium.

□

4.2 Lower bound for mixed strategies

Clearly, since the strategy \mathcal{S} is pure, we have $c = C$. Now, our aim is to slightly modify the allocation of tasks to obtain a mixed strategy \mathcal{S}' for which $C = c \cdot \Theta\left(\frac{\log m}{\log((\log m)/c)}\right)$.

We focus our attention on group K . Let L denote the set of links in this group. L contains \sqrt{m} links. Each of these links has speed 2^K , and to each link we have assigned exactly K tasks of size 2^K each. Let T denote the set of these tasks. The cardinality of this set is $\sqrt{m} \cdot K$. Now, we change the pure strategy \mathcal{S} into a mixed strategy \mathcal{S}' by setting $p_i^j = \frac{1}{\sqrt{m}}$ for every $i \in T, j \in L$. We observe the following properties for our new mixed strategy \mathcal{S}' .

Lemma 4.2 *Strategy \mathcal{S}' satisfies the following properties:*

1. *the maximum load is $c = K$,*
2. *the social optimum is $1 \leq \text{opt} \leq 2$,*
3. *the system is in Nash equilibrium, and*
4. *the social cost is $C = \Omega\left(\frac{\log m}{\log((\log m)/K)}\right)$.*

Proof :

1. The maximum load c is the same as for strategy \mathcal{S} .
2. The value of opt is unaffected by the modification of the probabilities.
3. We have to check that the tasks in T do not have smaller expected costs on other links than on the links in L . Observe that the expected cost of these tasks on L slightly increased from K to $K + 1 - \frac{1}{\sqrt{m}} \leq K + 1$. However, for every link $j \notin L$ in group $t < K$ and any $i \in T$, we have $c_i^j = \ell_j + \frac{w_i}{s_j} = t + 2^{K-t} \geq K + 1$, where the last inequality holds for any two integers t and K . Consequently, the system is in a Nash equilibrium.
4. To observe this property, we notice that the allocation of the tasks in T to the links in L corresponds to the allocation problem of throwing $\sqrt{m} \cdot K$ balls uniformly at random into \sqrt{m} bins (see, e.g., [MR95]). In expectation, it is known that the expected maximum occupancy in this allocation problem is $\Theta\left(K + \frac{\log m}{\log((\log m)/K)}\right)$, which is $\Theta\left(\frac{\log m}{\log((\log m)/K)}\right)$ because $K = \mathcal{O}(\log m / \log \log m)$ in our case. Since the sizes of the tasks in T correspond to the speeds of the links in L , this bound on the maximum occupancy directly implies a lower bound on the social cost.

□

Thus, by Lemma 4.2, for every integer m and for every positive integer $K \leq \Gamma^{(-1)}(\sqrt{m}/e) - 1 = \frac{\log m}{2 \log \log m} (1 + o(1))$, there exists a set of m links and a Nash equilibrium with $\log(s_1/s_m) = K$ (unless $K = 1$, in which case $s_1 = s_m$), $1 \leq \text{opt} \leq 2$, $c = K$, and

$$C = \Omega\left(\frac{\log m}{\log\left(\frac{\text{opt} \cdot \log m}{c}\right)}\right).$$

Moreover, we can easily extend this construction to hold for arbitrary positive values of opt . This completes the proof of Theorem 3. □

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