

The Complexity of Gradient Descent: $CLS = PPAD \cap PLS$

ALEXANDROS HOLLENDER

JOINT WORK WITH JOHN FEARNLEY, PAUL GOLDBERG AND RAHUL SAVANI



Some interesting computational problems

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They are NP Total Search (TFNP) problems!

- Total: there is always a solution
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Can a TFNP problem be NP-hard?

Not unless $\text{co-NP} = \text{NP}$...

The class TFNP [Megiddo-Papadimitriou, 1991]

Total NP search problems:

- “search” : looking for a solution, not just YES or NO
- “NP”: any solution can be checked efficiently
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TFNP lies between P and NP (search versions)

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$3\text{-SAT} \leq \text{NASH} \Rightarrow$ certificate for unsatisfiable 3-SAT formulas

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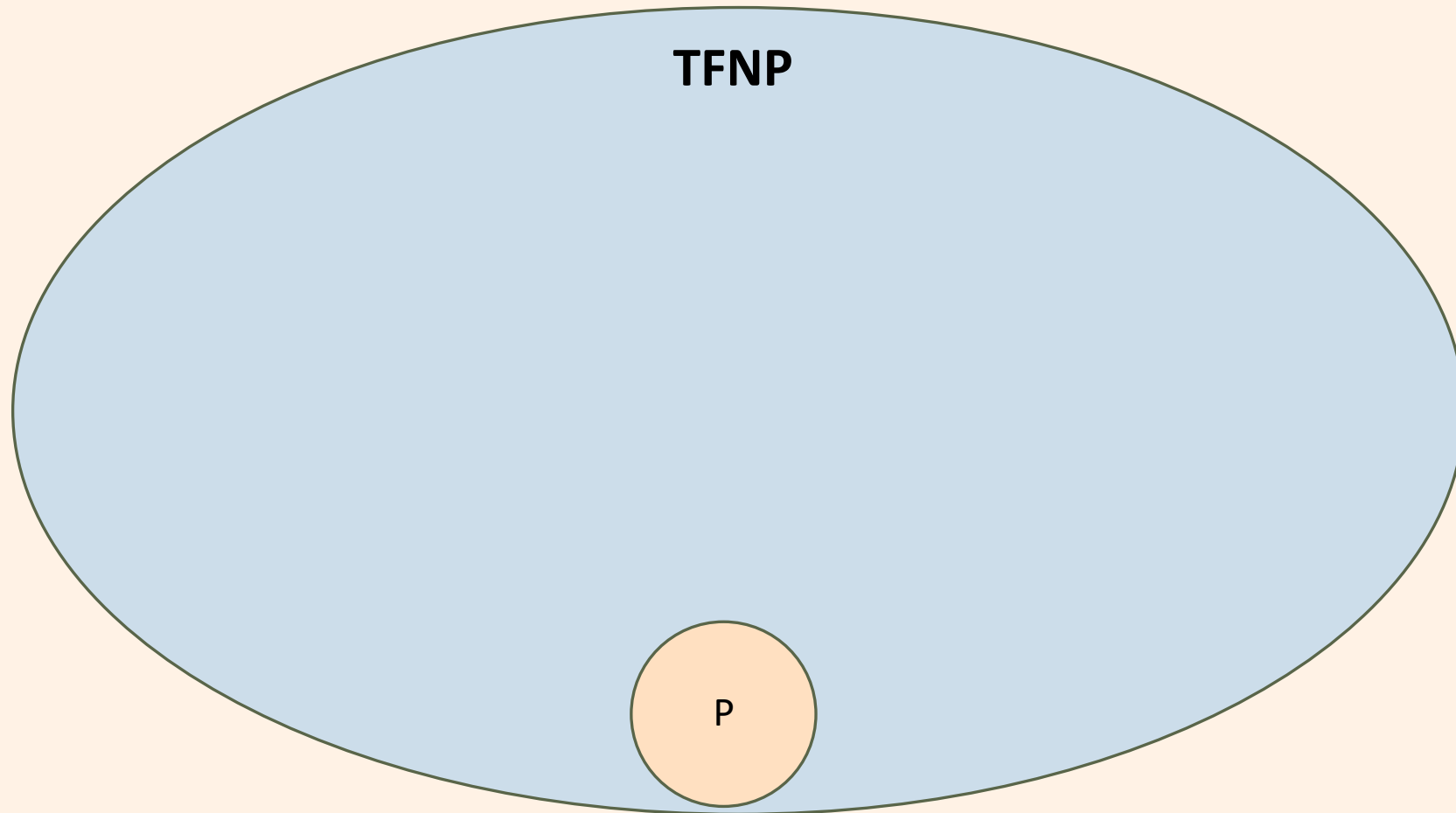
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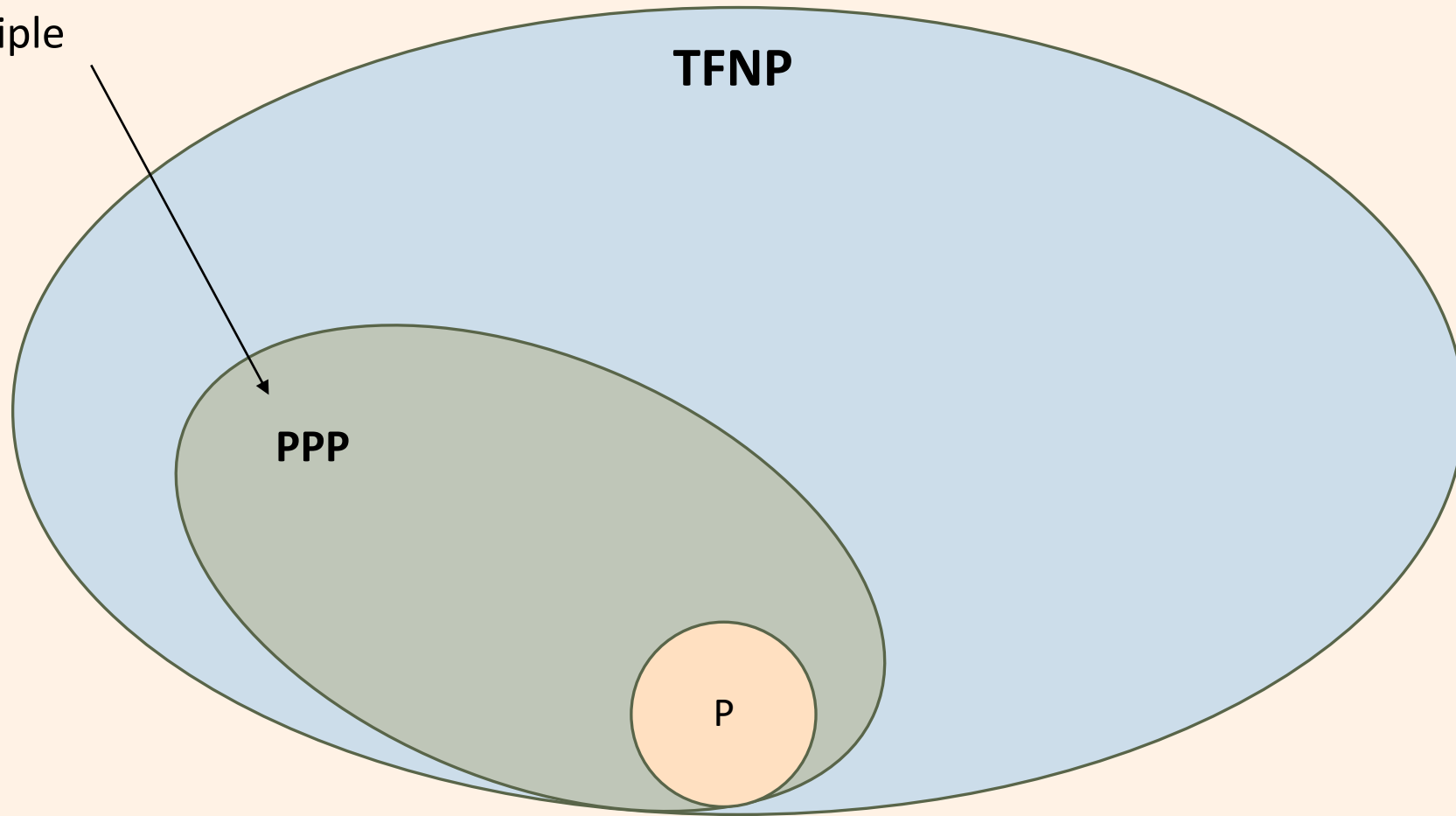
- No TFNP-problem can be NP-hard, unless $NP = coNP$...
- Believed that no TFNP-complete problems exists...

The TFNP landscape



The TFNP landscape

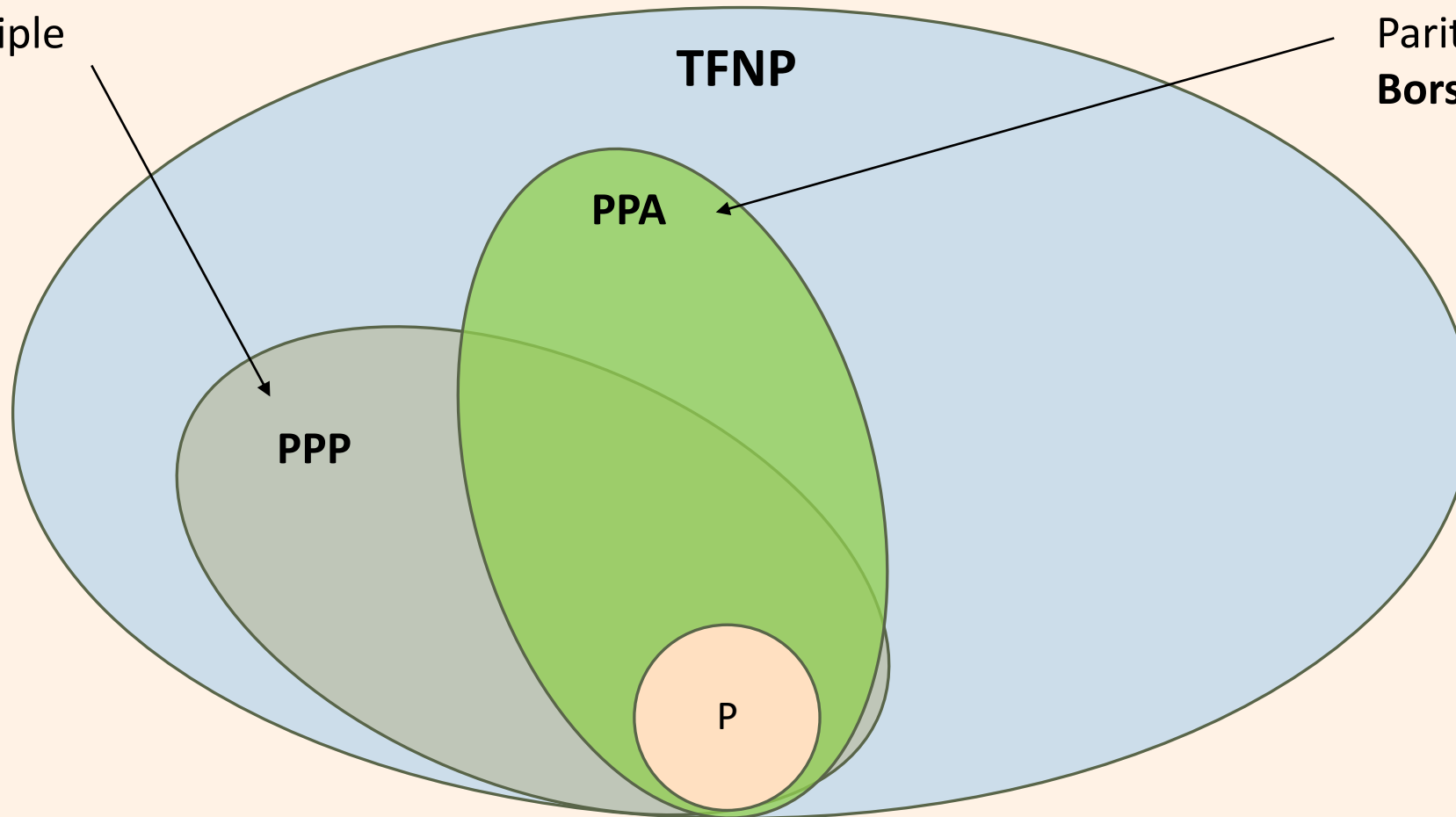
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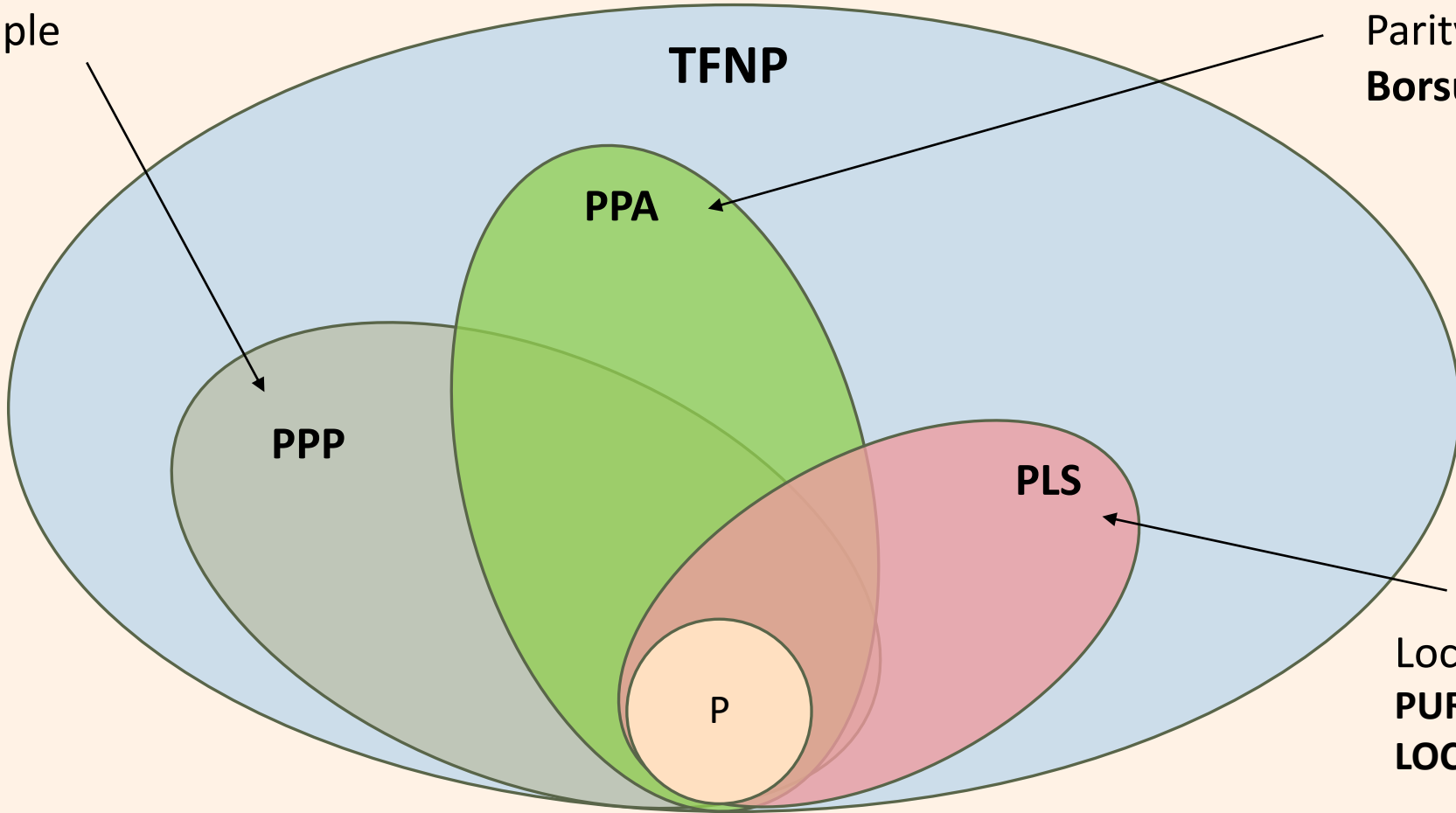
Parity Argument
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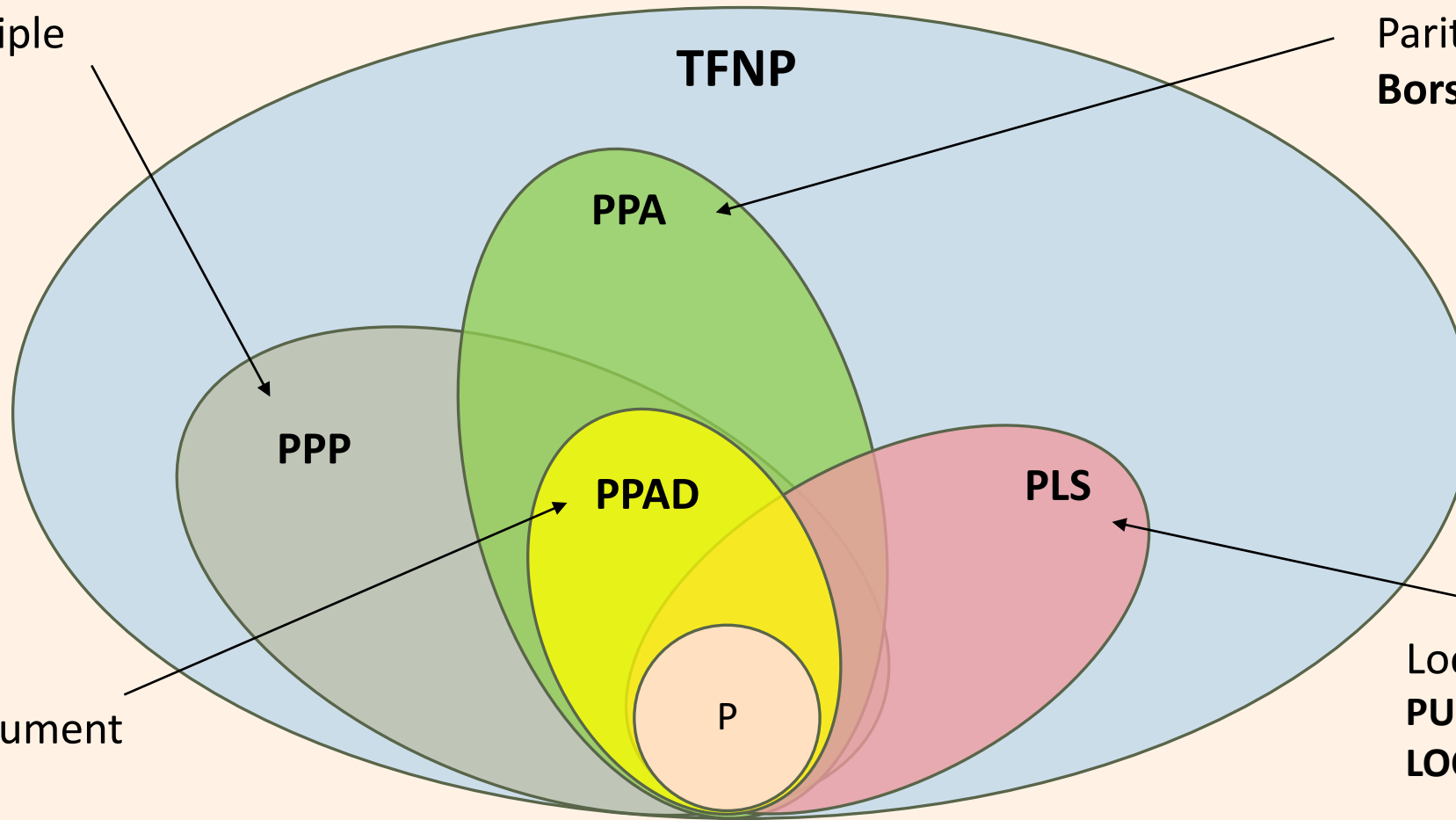


Local Search Argument
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TFNP

PPA

PPP

PPAD

P

PLS

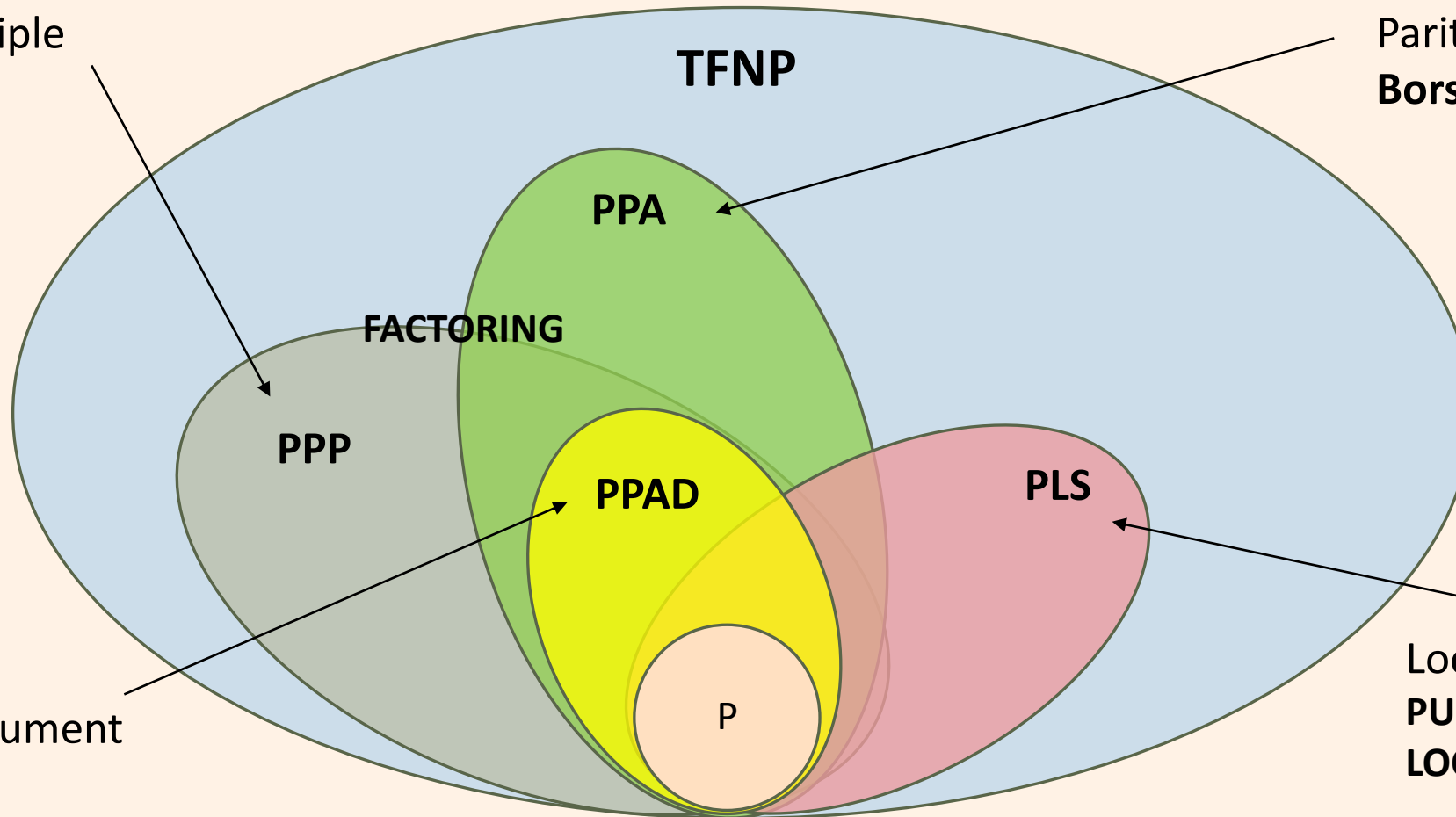
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TFNP subclasses

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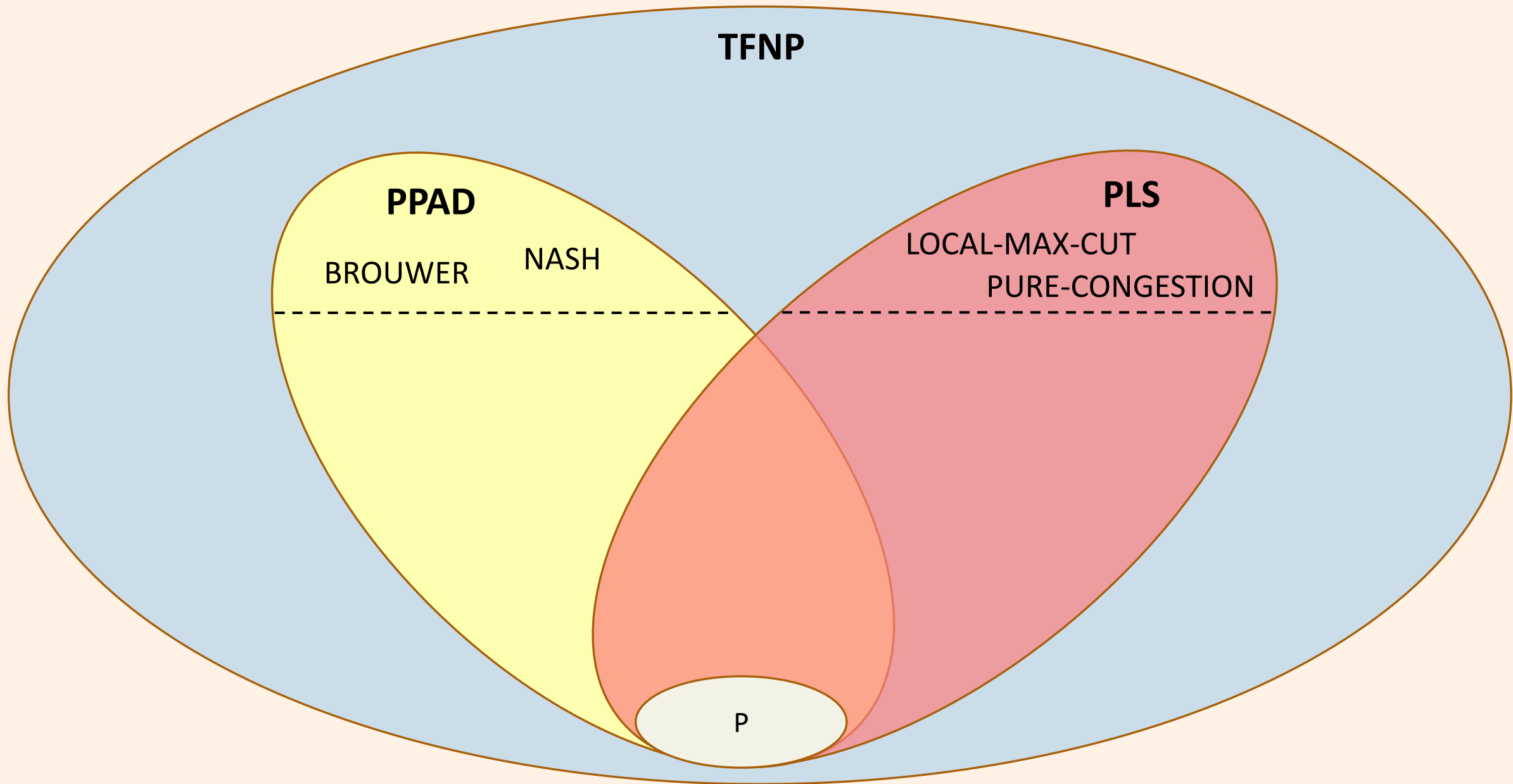
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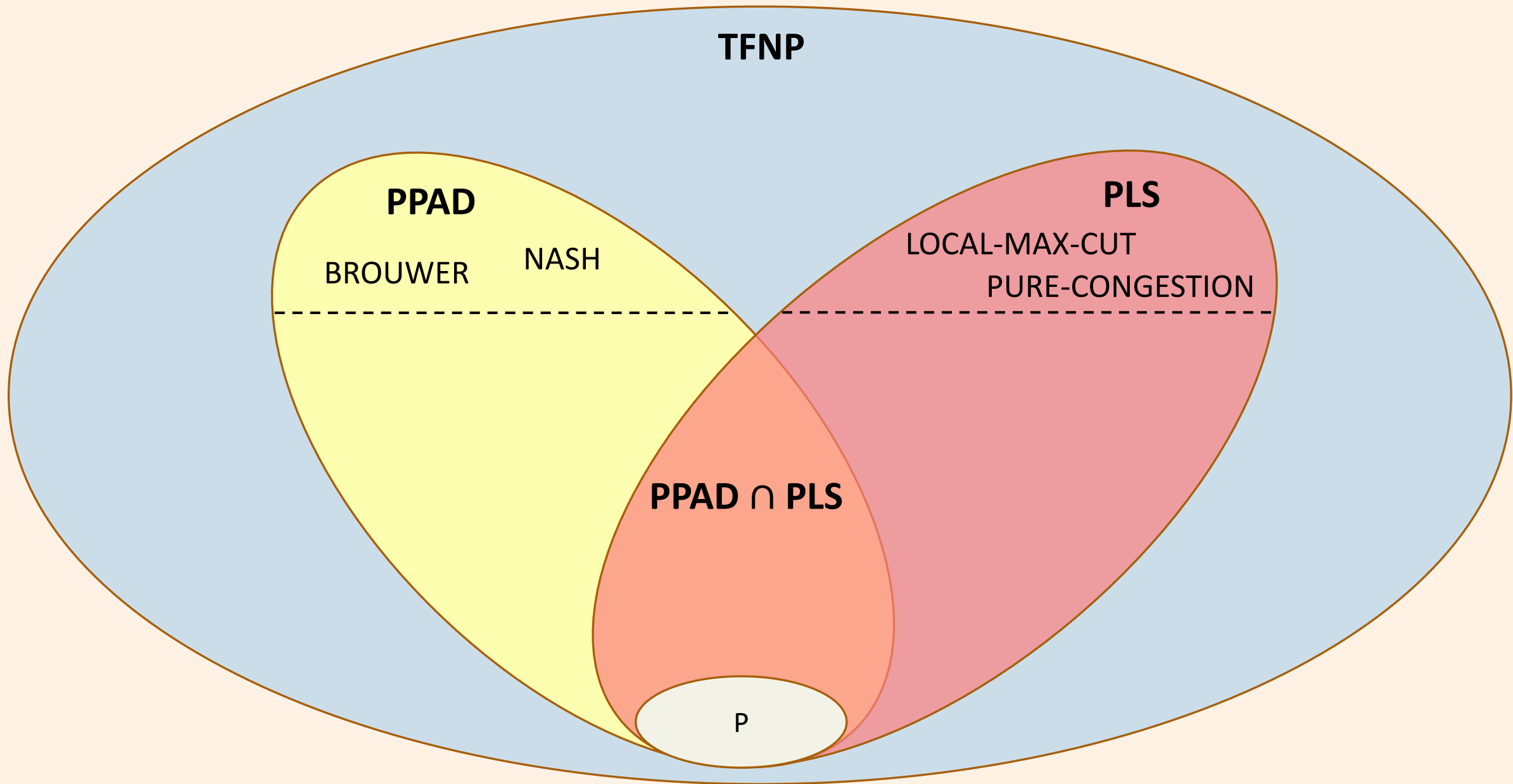
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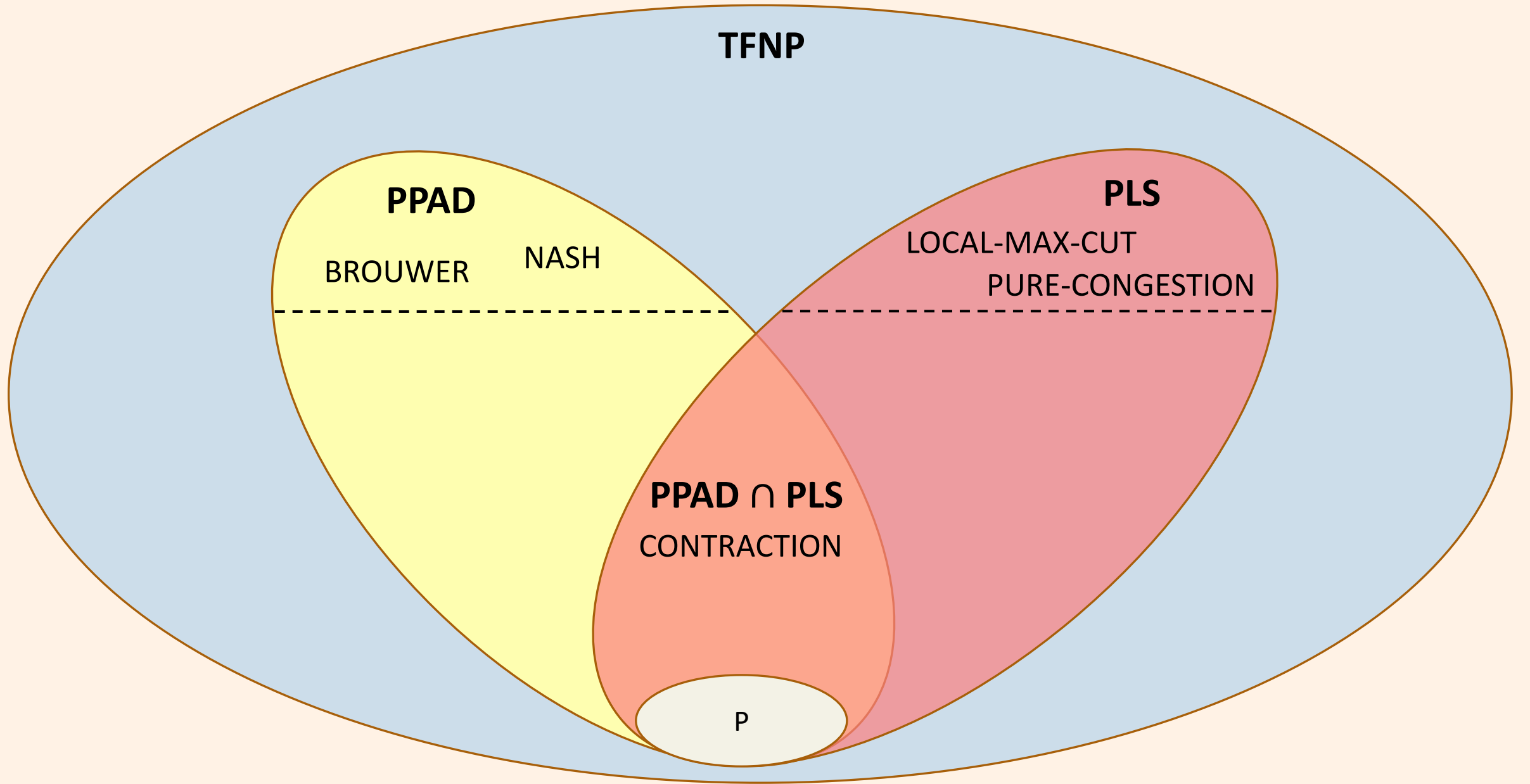
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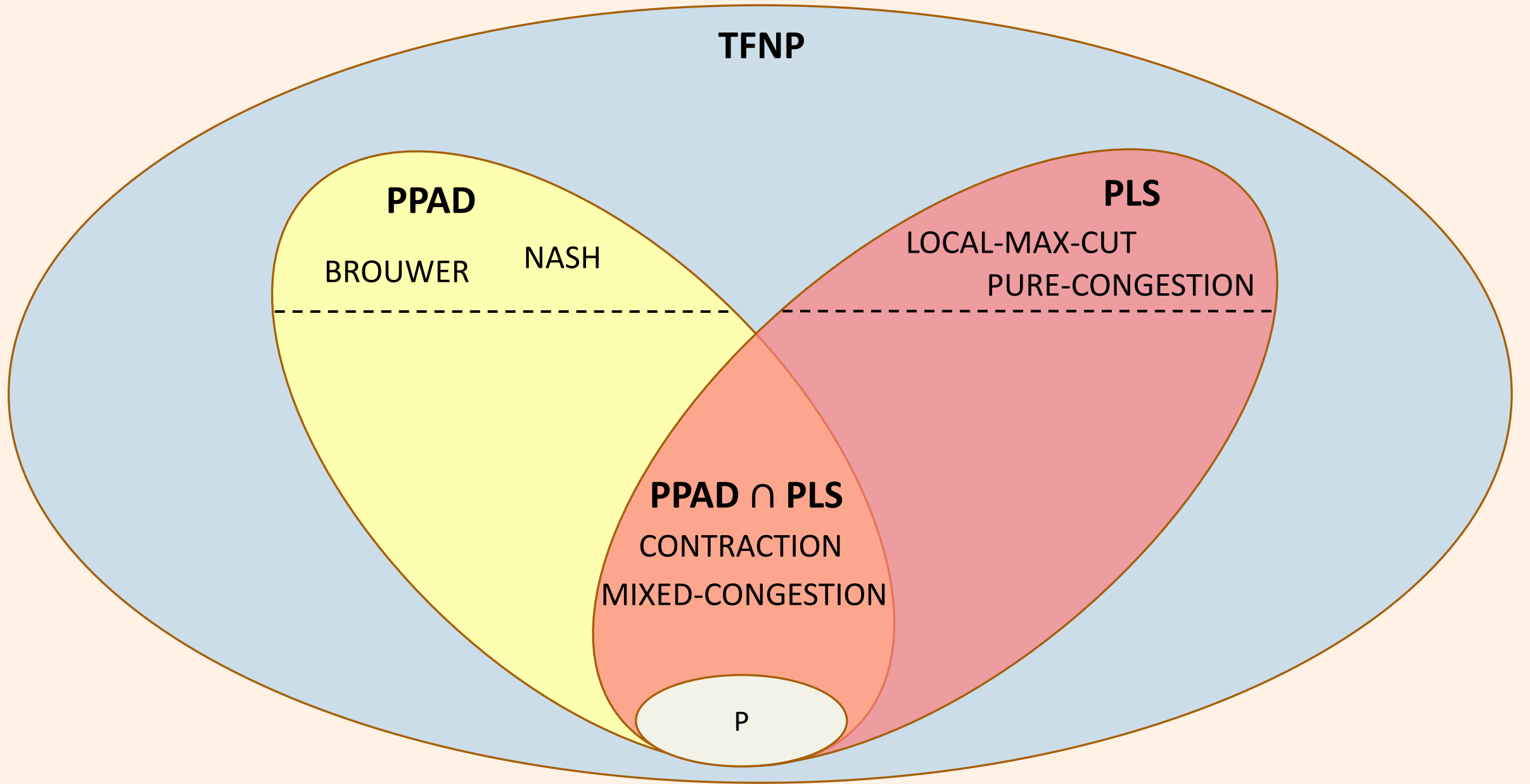
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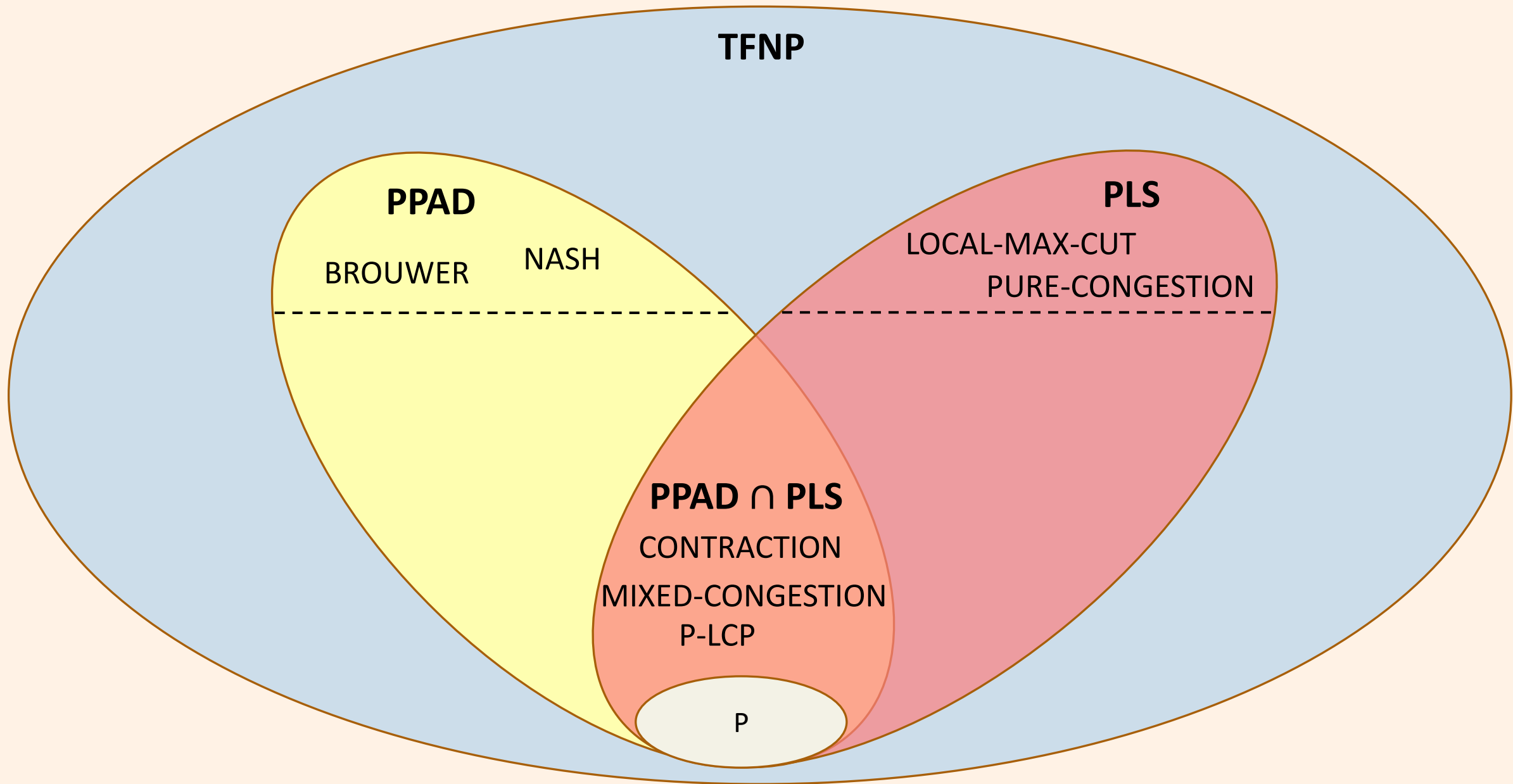
- many seemingly hard problems lie in $PPAD$, PLS etc...
- oracle separations between the classes (in particular $PPAD \neq PLS$)
- hard under cryptographic assumptions

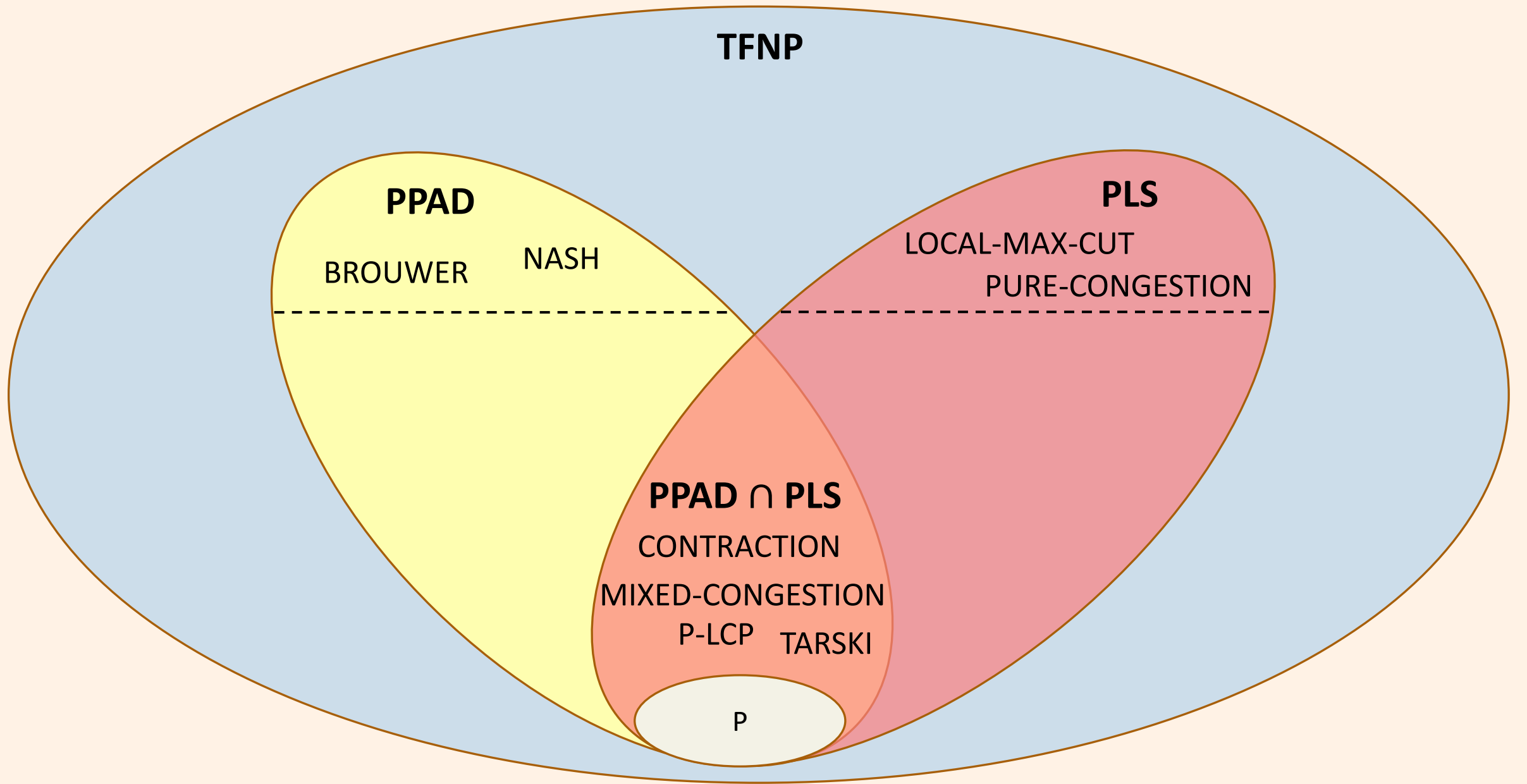


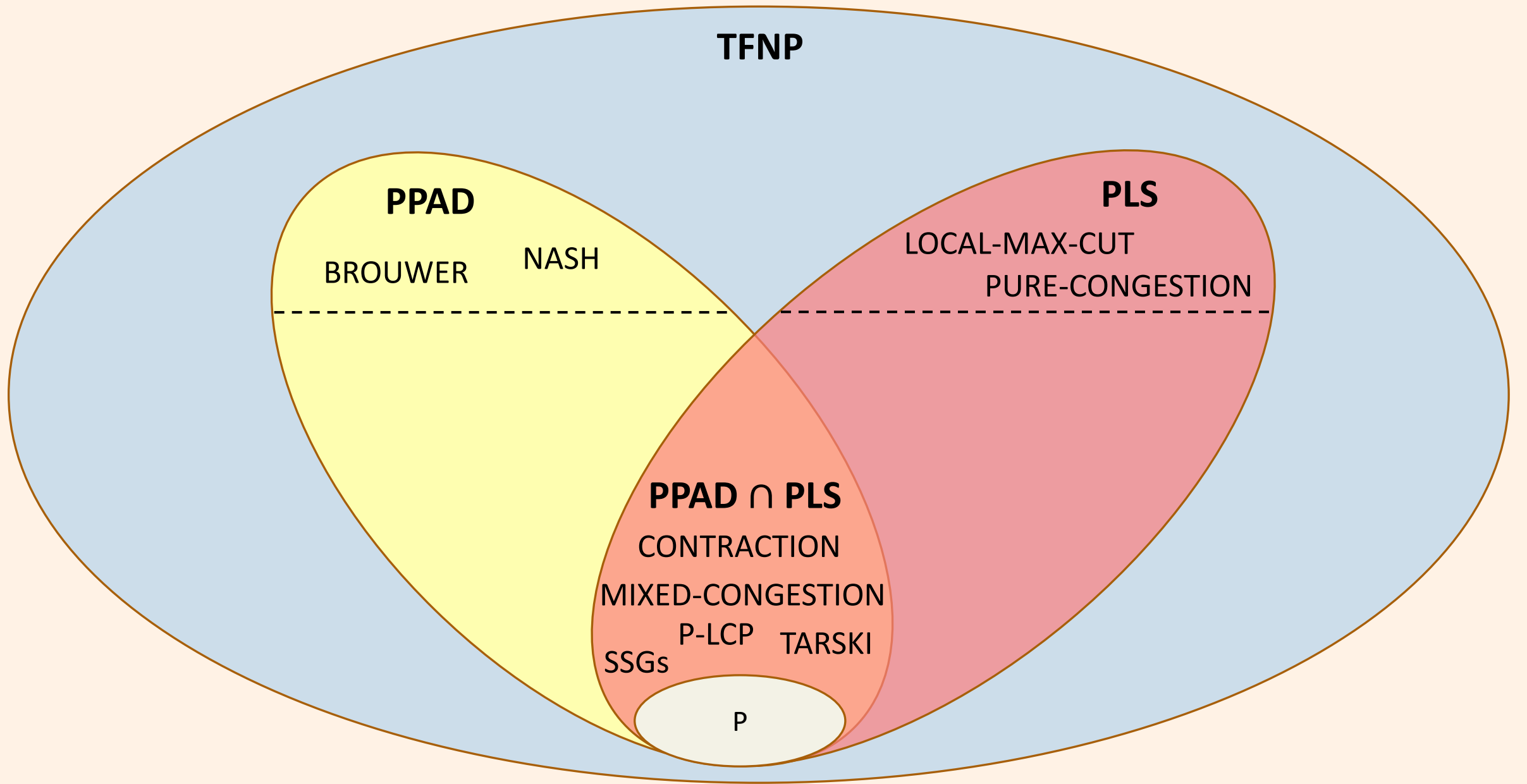












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Problem A : PPAD-complete

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Input: instance I_A of A , instance I_B of B

Goal: find a solution of I_A , or a solution of I_B

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PPAD \cap PLS seems unnatural...

BROUWER:

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Goal: find a fixpoint x

$$f(x) = x$$

PPAD \cap PLS seems unnatural...

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Input: a continuous function $f: [0,1]^n \rightarrow [0,1]^n$, precision $\varepsilon > 0$

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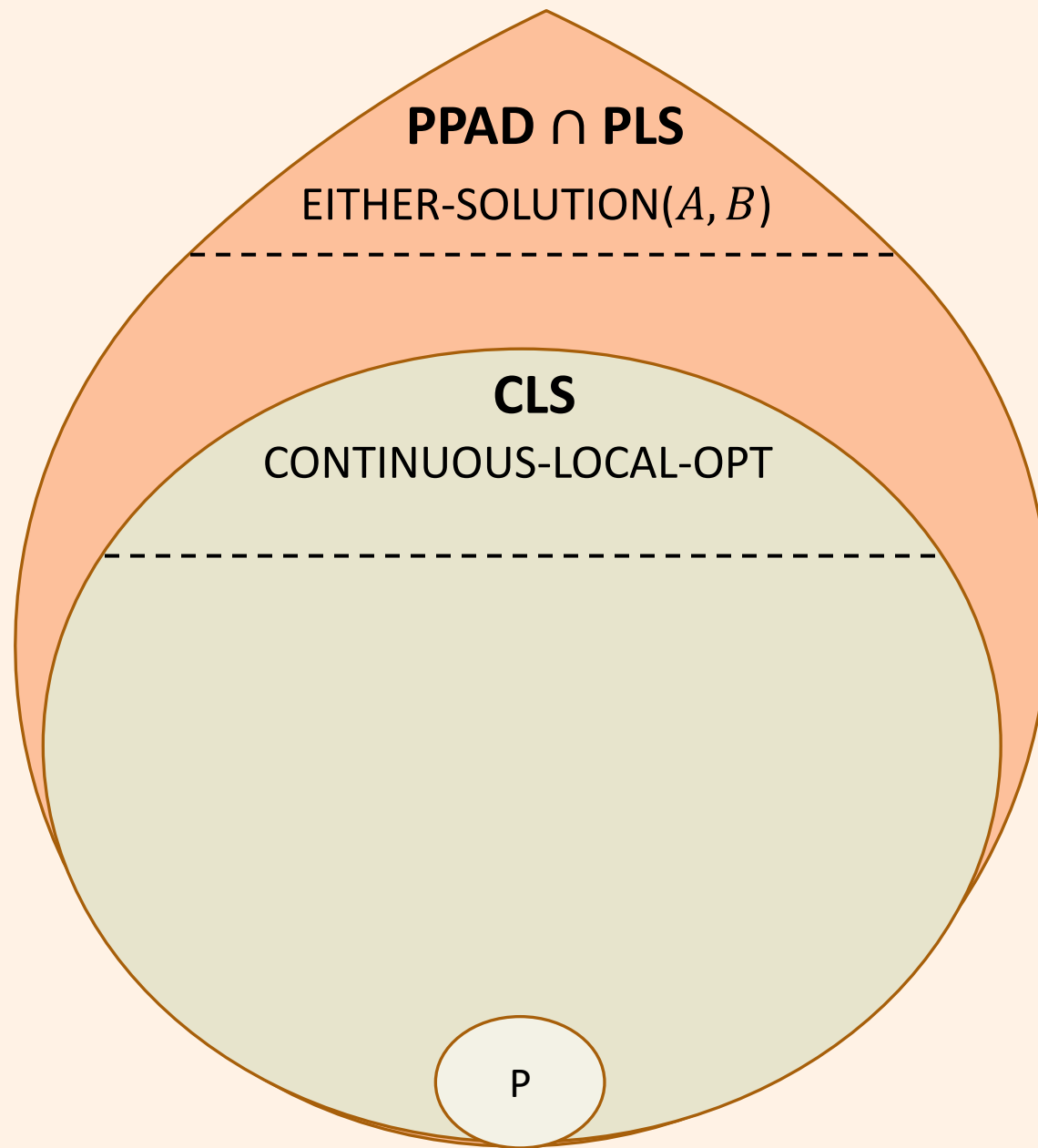
→ class **Continuous Local Search (CLS)** [Daskalakis-Papadimitriou, 2011]

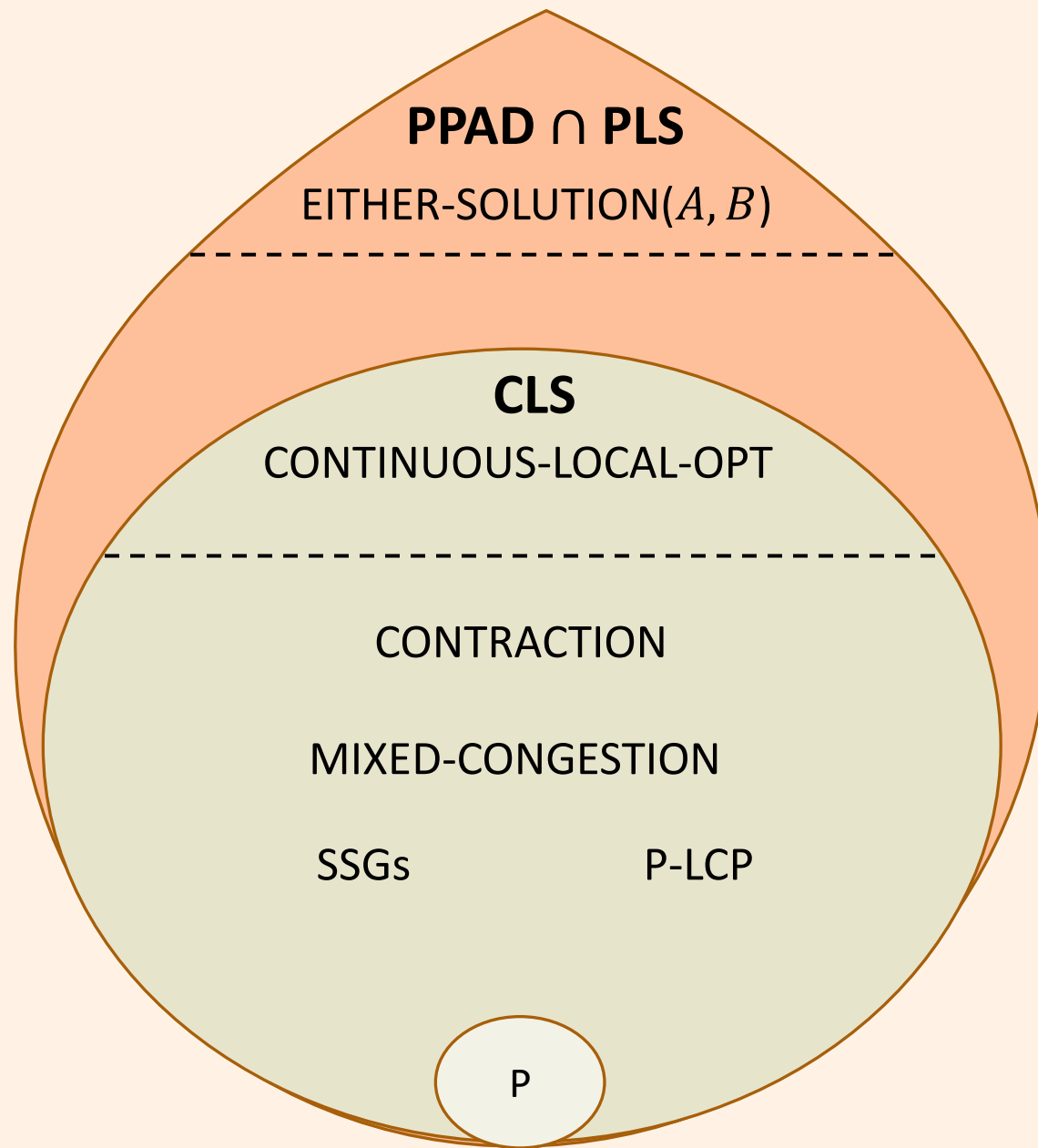
PPAD \cap PLS

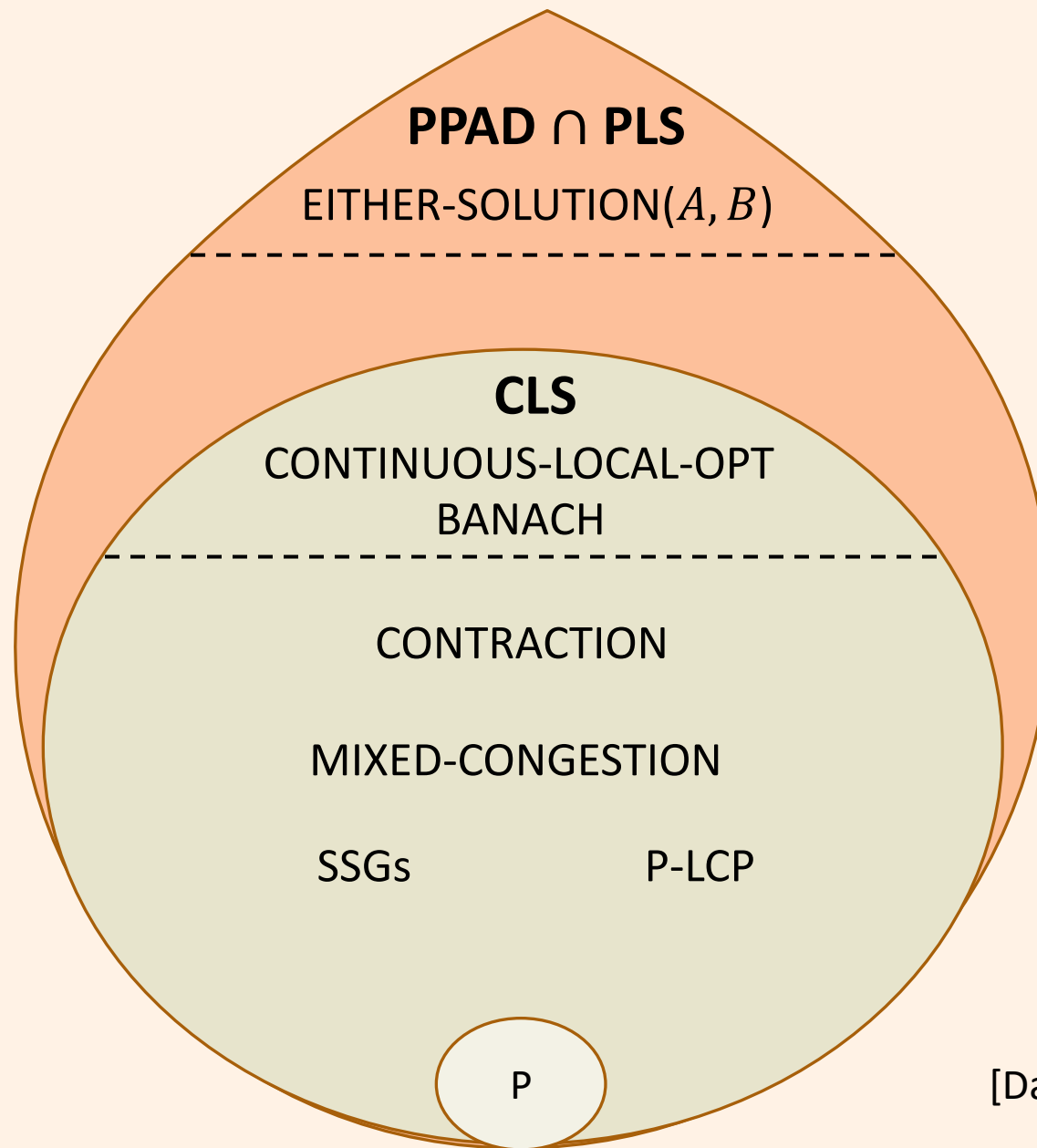
EITHER-SOLUTION(A, B)

P









[Daskalakis-Tzamos-Zampetakis, 2018]

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→ in CLS: $p(x) := f(x)$ and $g(x) := x - \eta \nabla f(x)$

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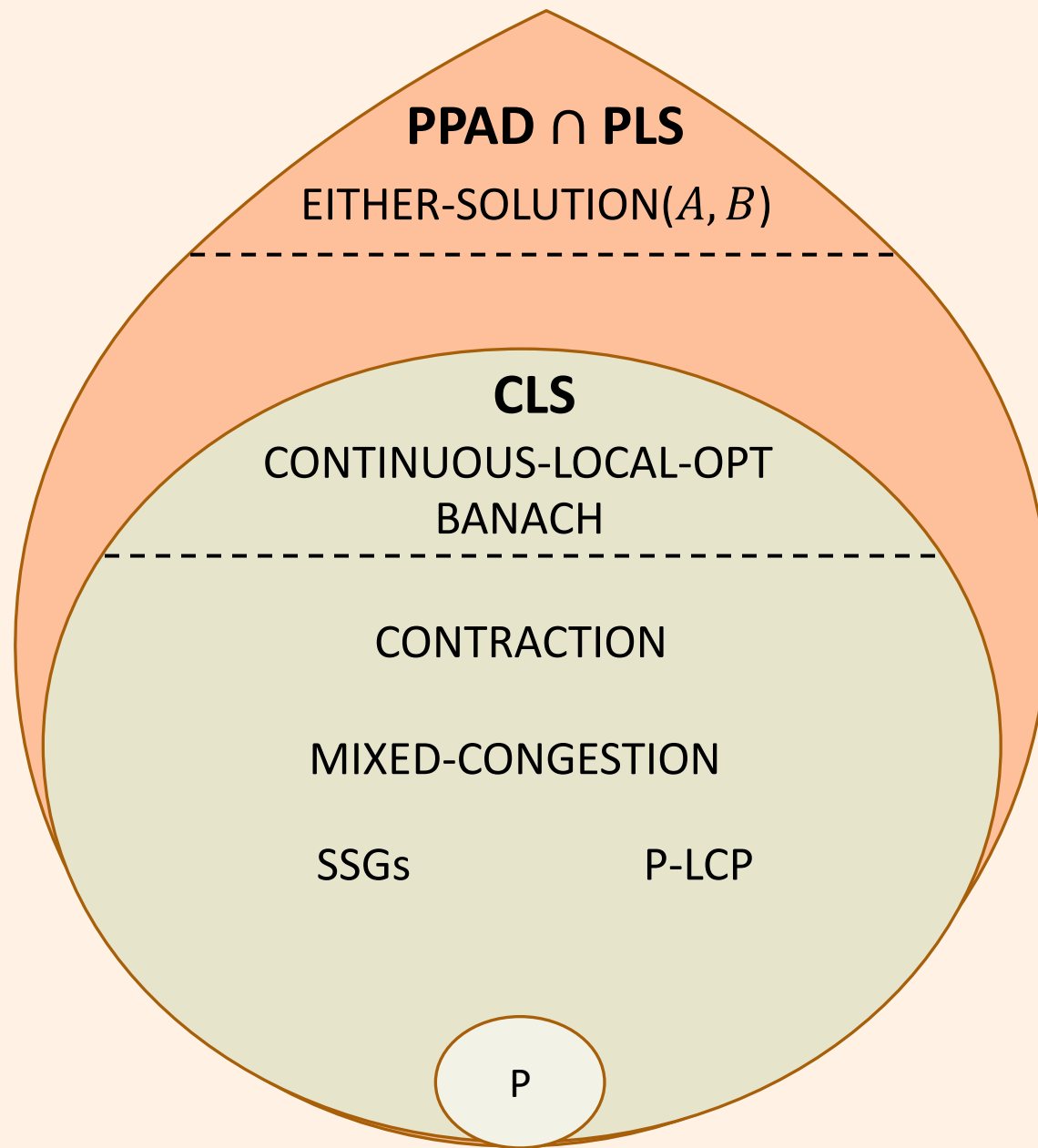
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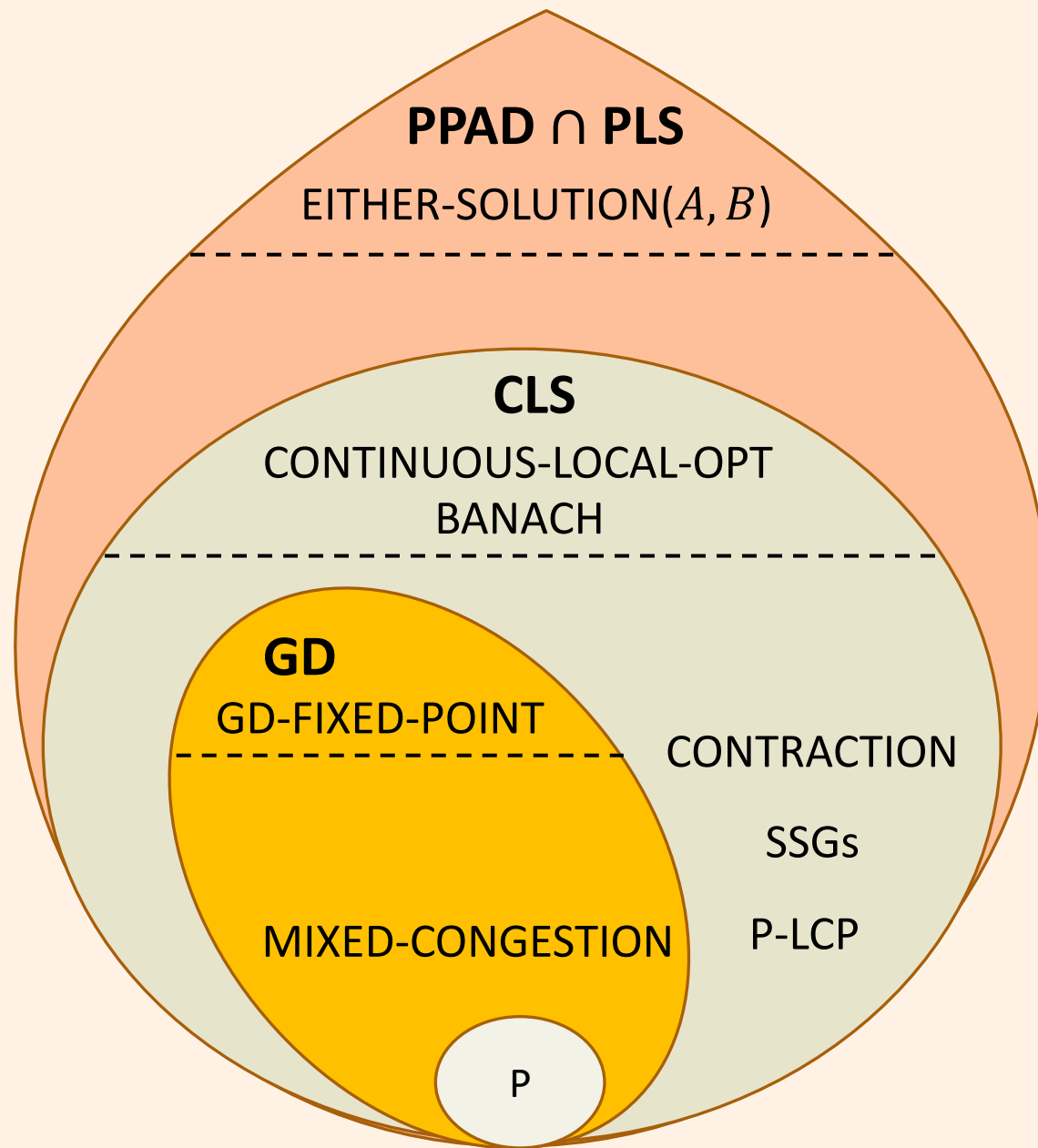
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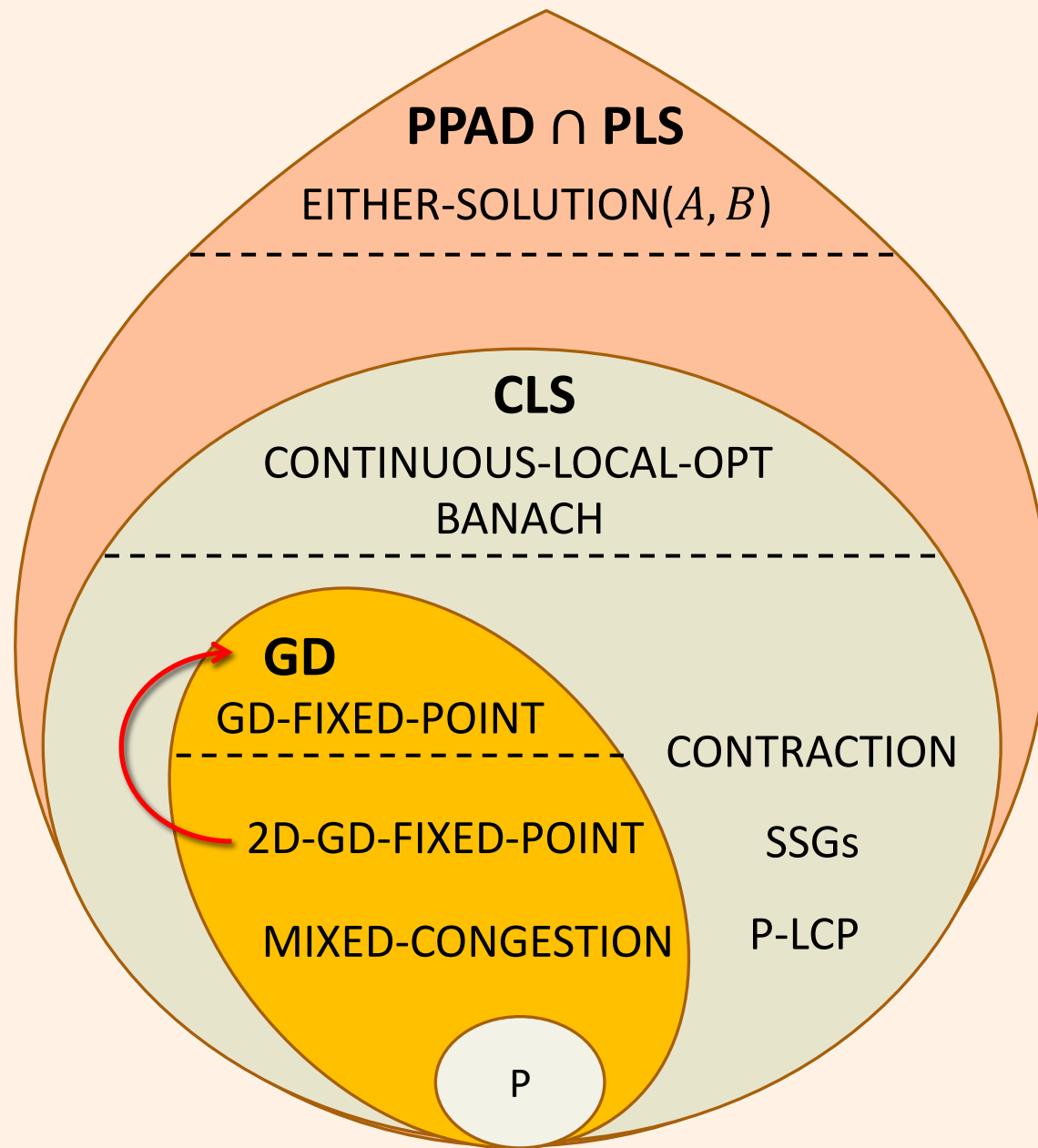
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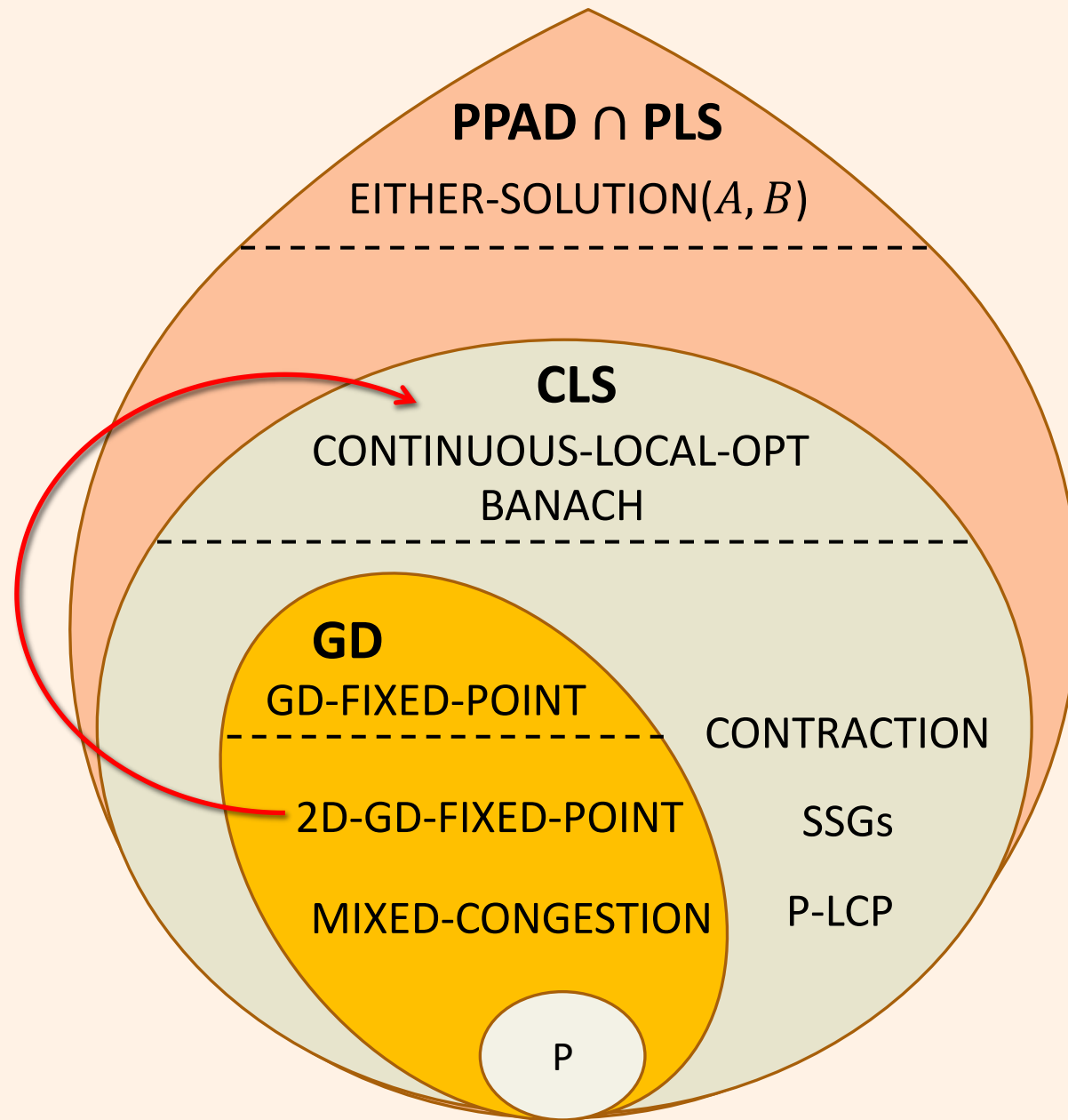
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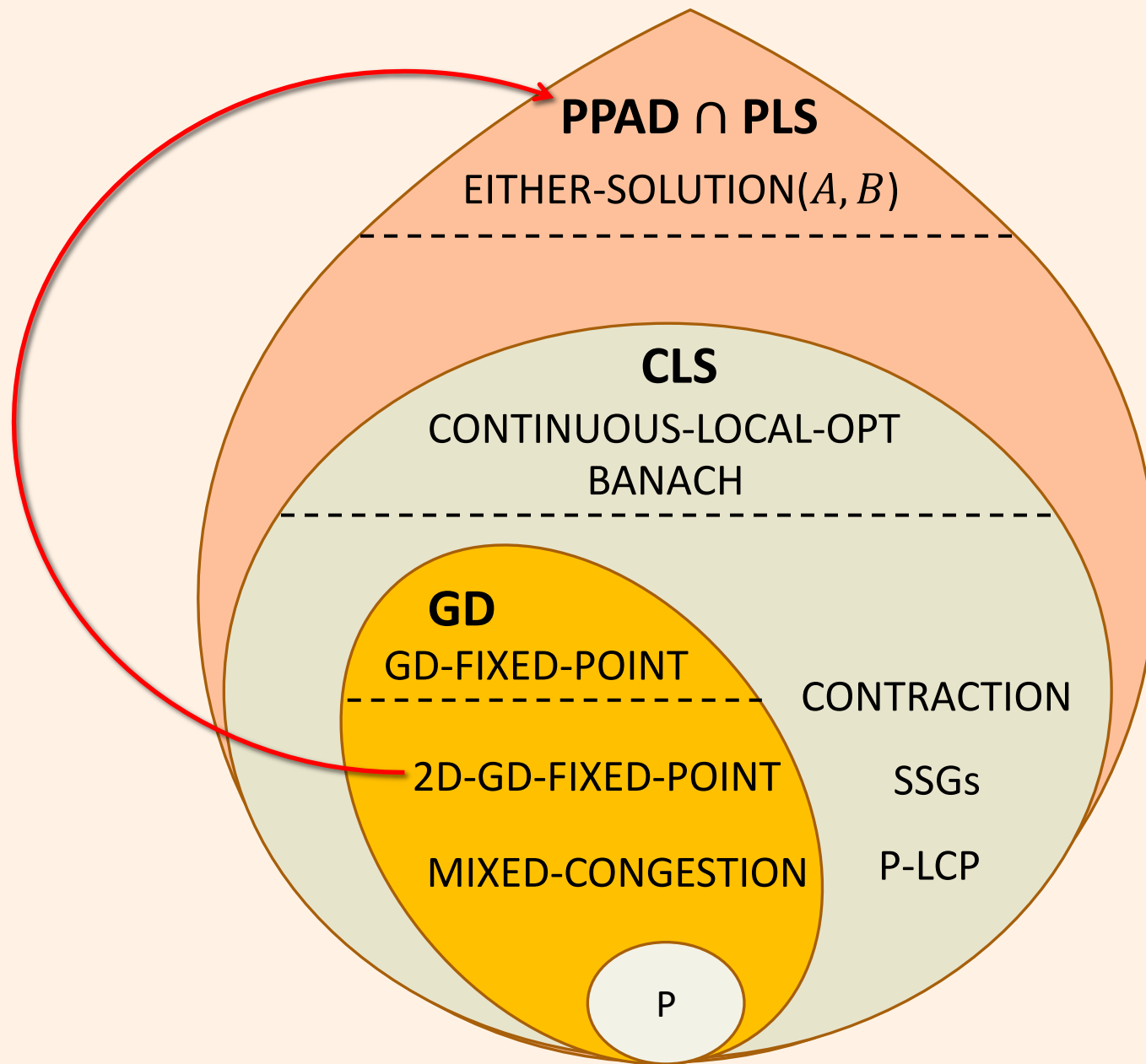
→ polynomial-time equivalent!











PPAD \cap PLS = CLS = GD

EITHER-SOLUTION(A, B)
CONTINUOUS-LOCAL-OPT
BANACH
2D-GD-FIXED-POINT

CONTRACTION

SSGs

MIXED-CONGESTION

P-LCP

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- CLS and GD are robust with respect to:
 - dimension
 - domain
 - arithmetic circuits
 - ...

Proof Sketch

PPAD

Canonical complete problem: **END-OF-LINE**

PPAD

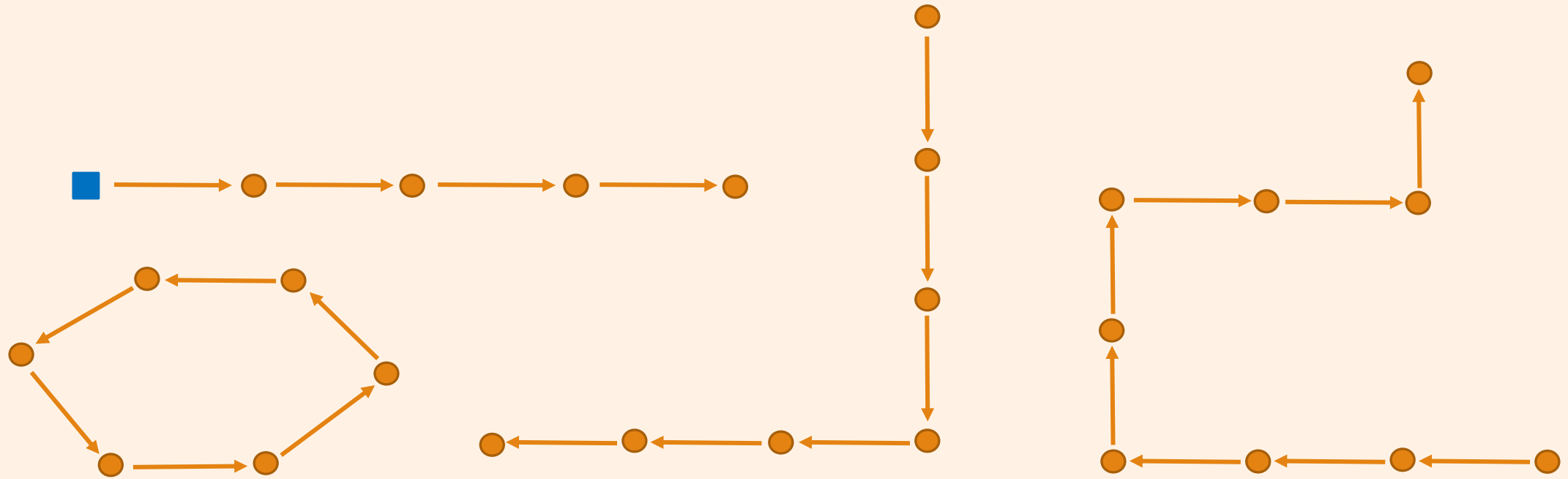
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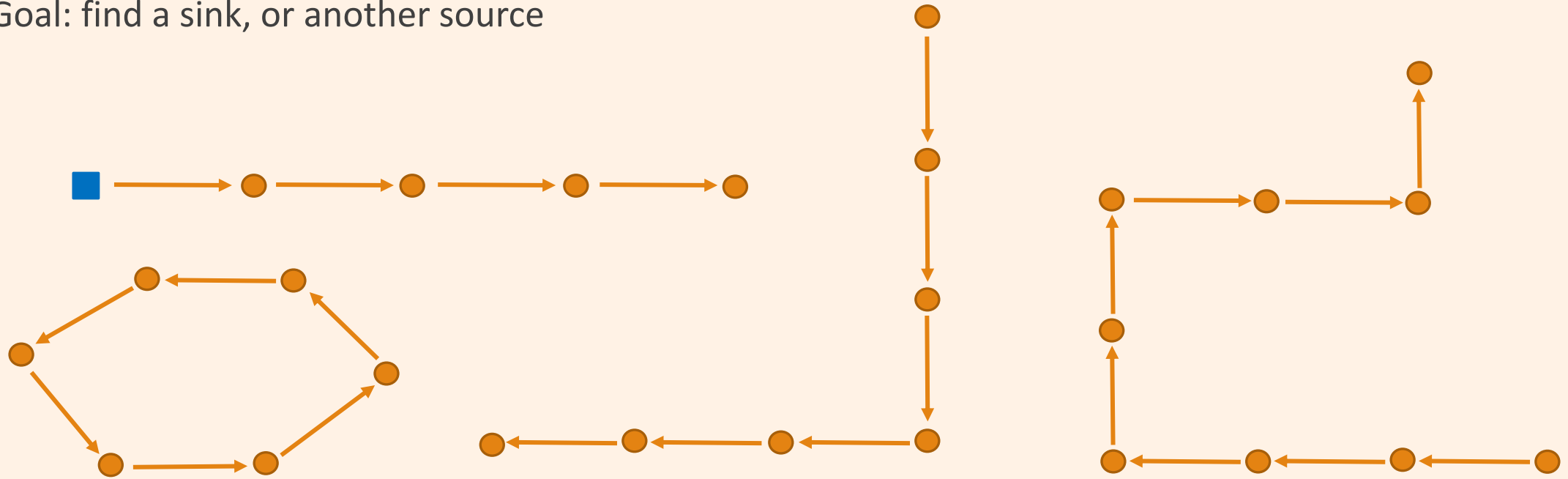


PPAD

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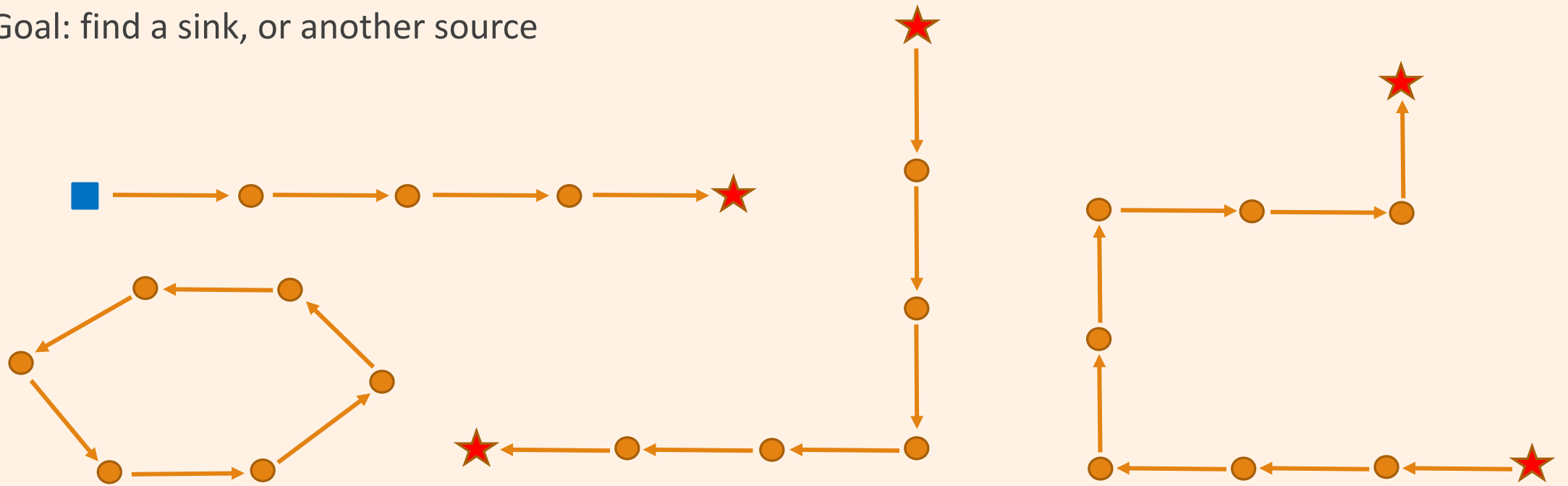


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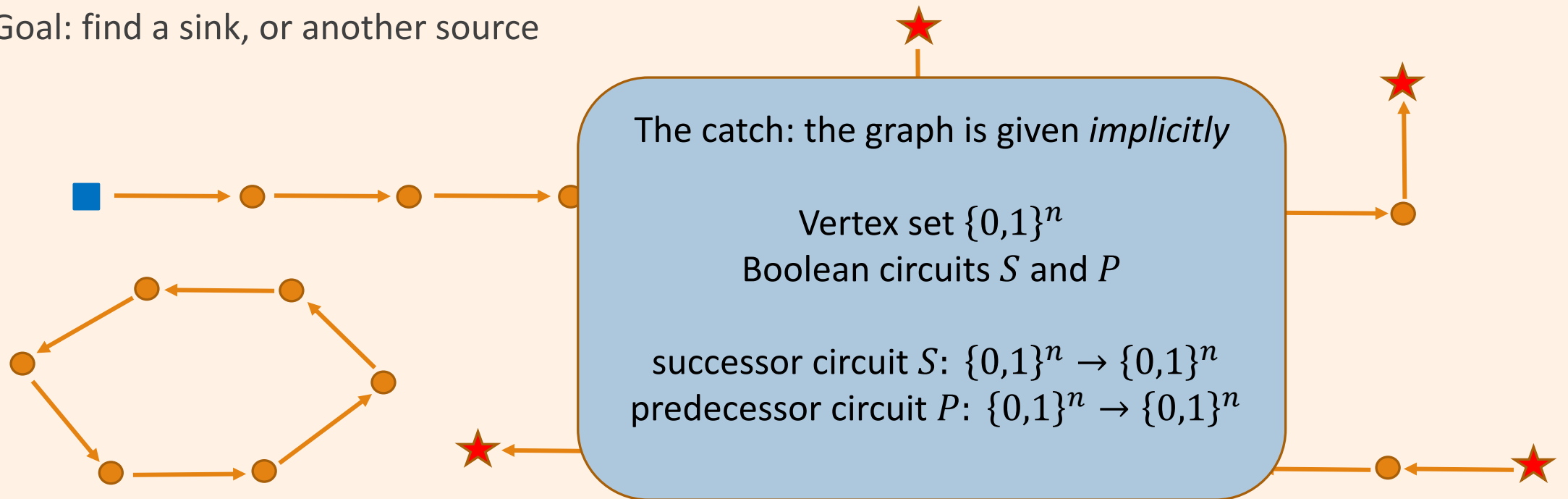


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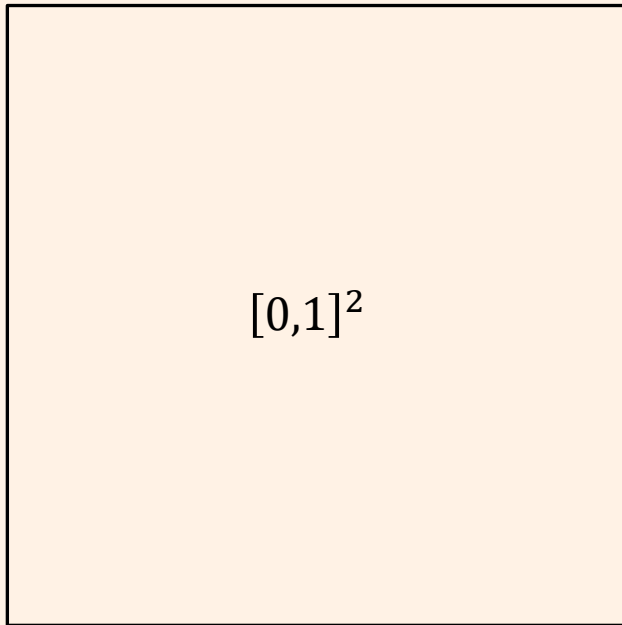
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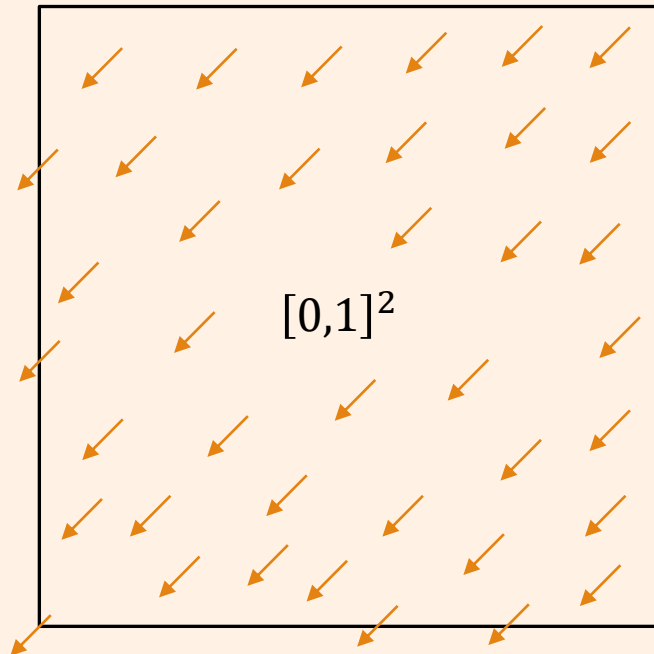
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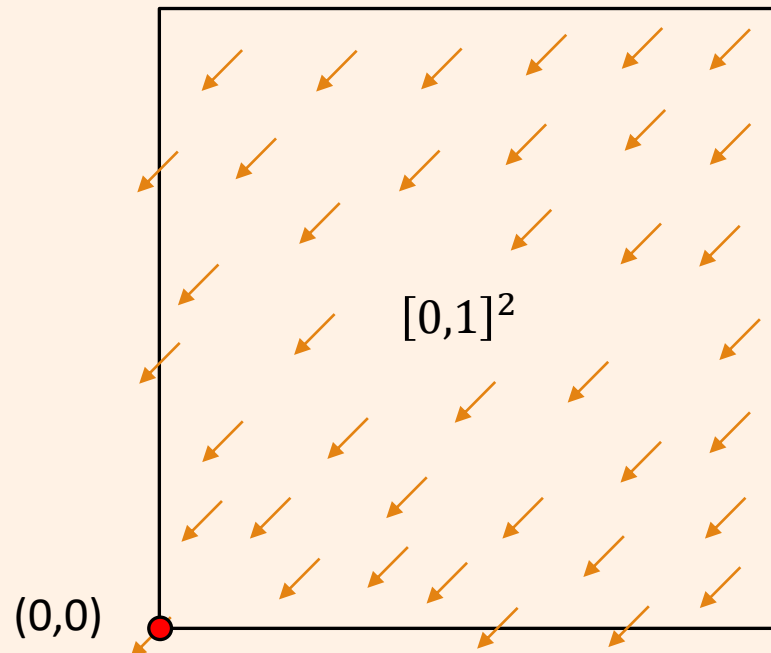
→ Construct a continuously differentiable function $f: [0,1]^2 \rightarrow \mathbb{R}$ such that any gradient descent fixed point yields a solution to the EITHER-SOLUTION instance



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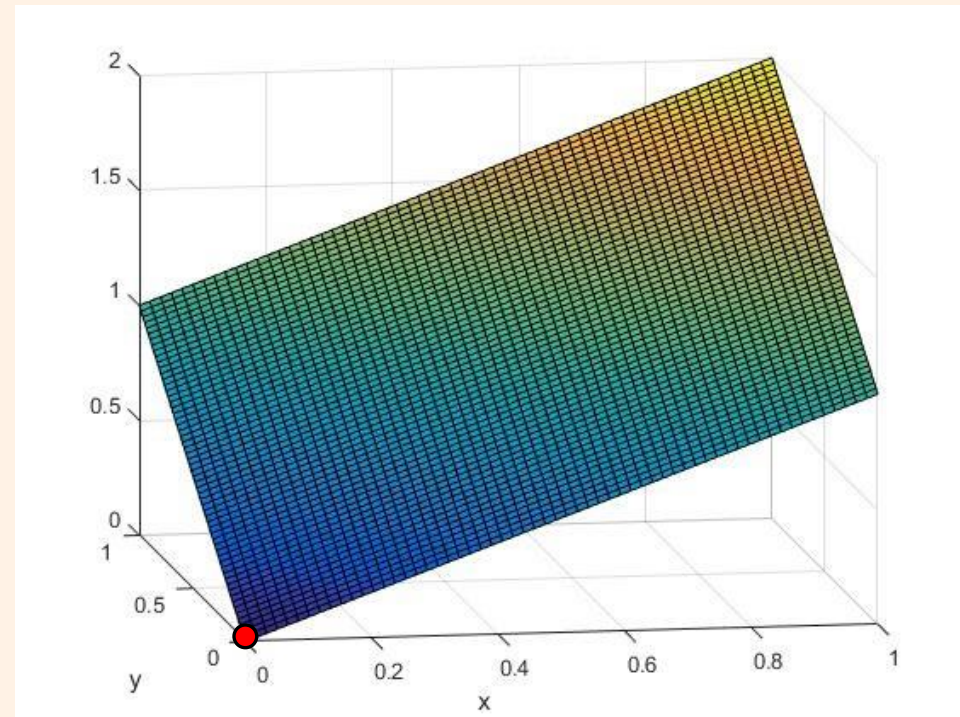
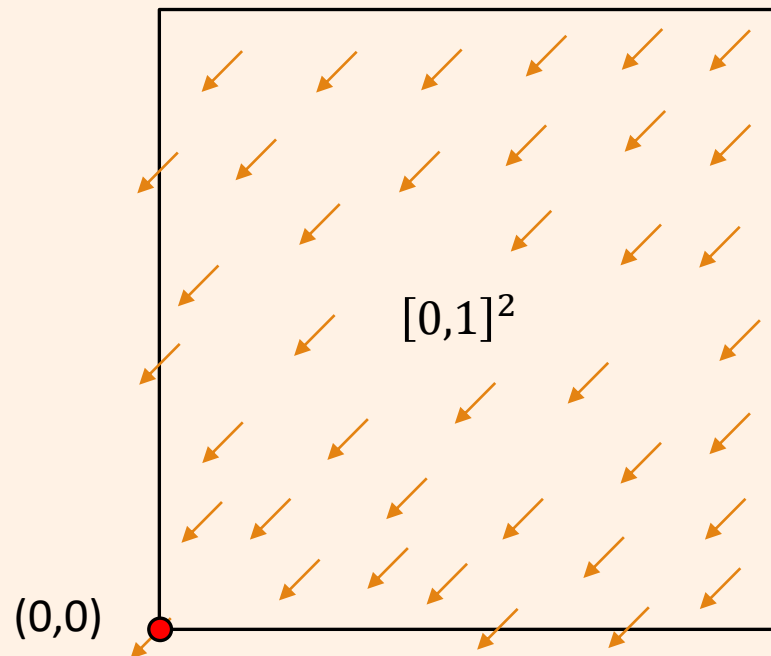
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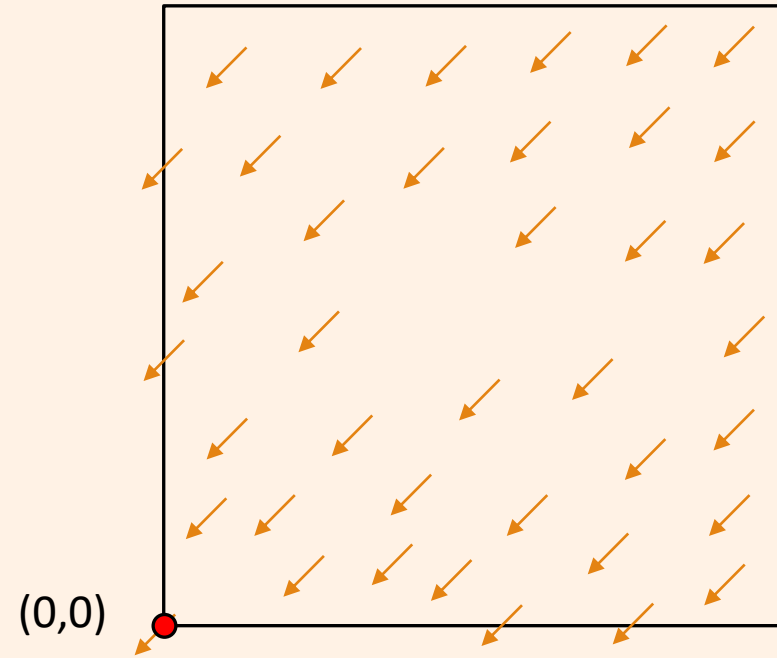


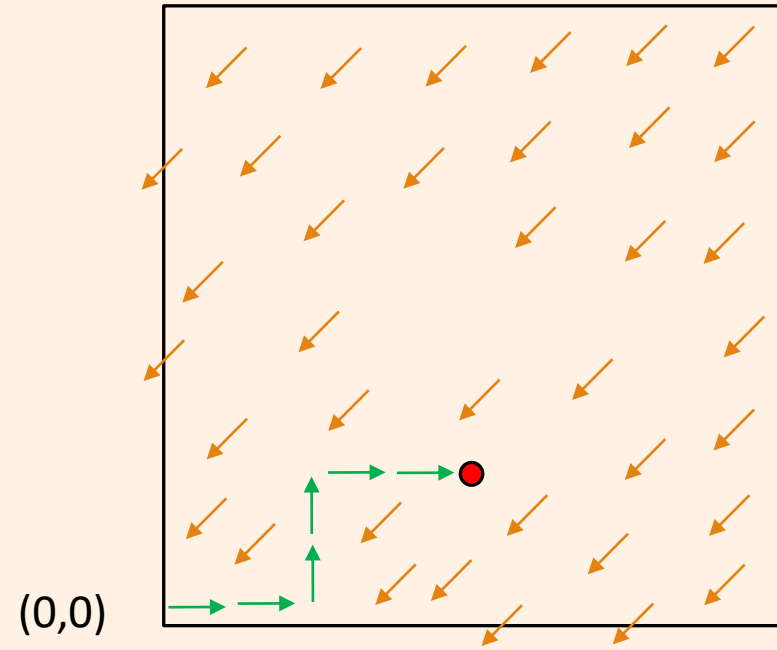
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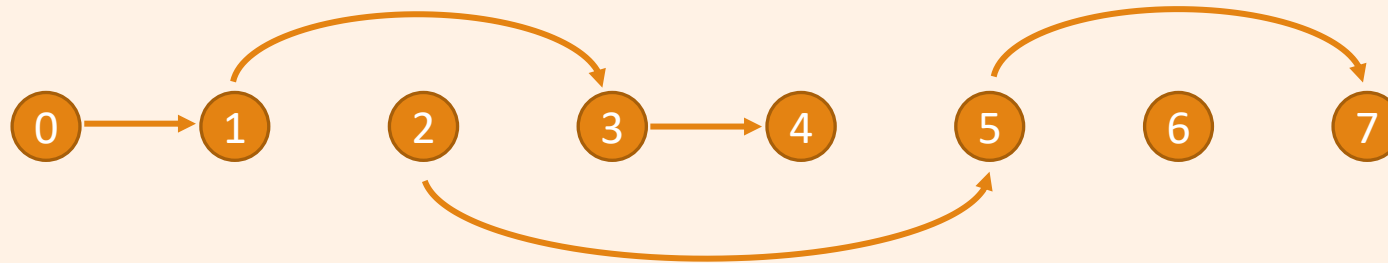


Warm up: Monotone-End-of-Line

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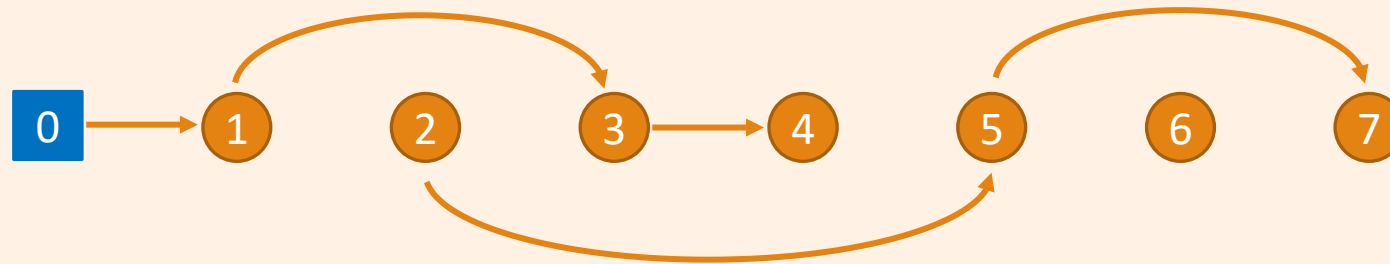


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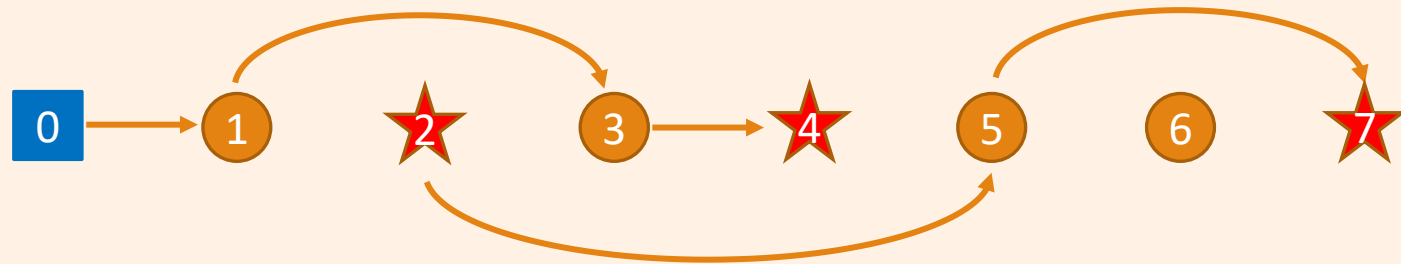
Special case of END-OF-LINE: No backward edges allowed!

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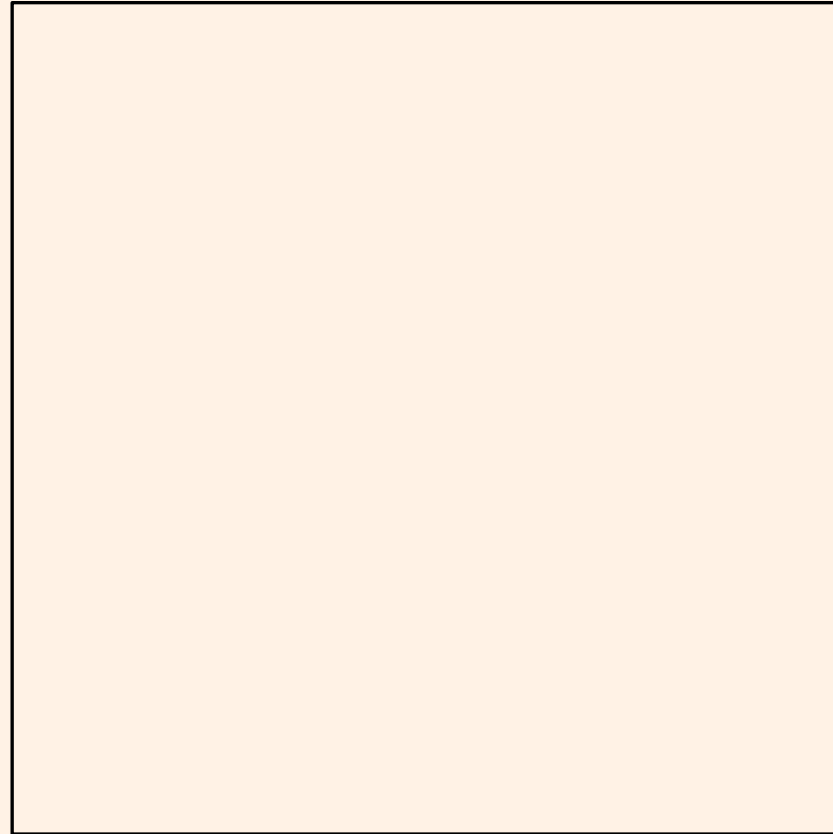
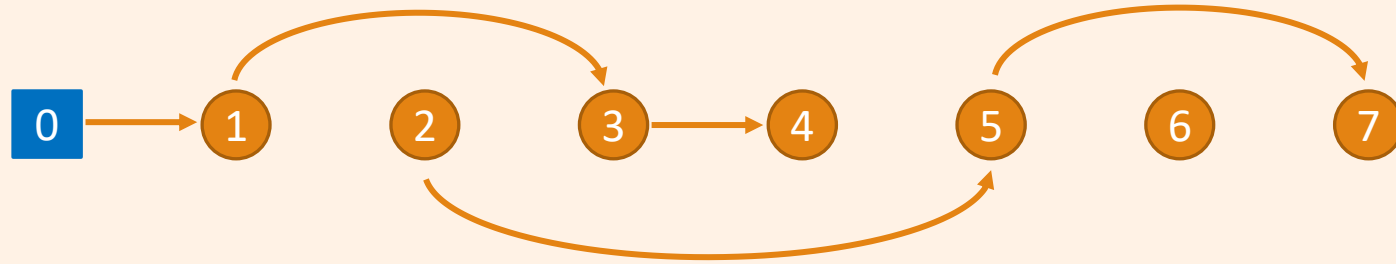


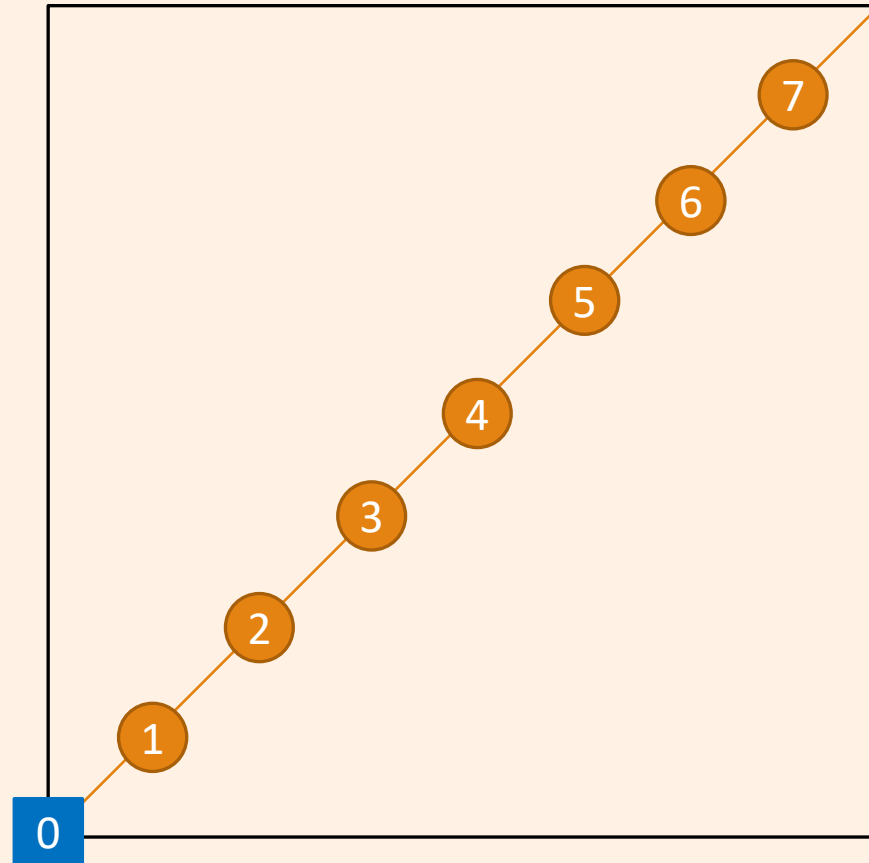
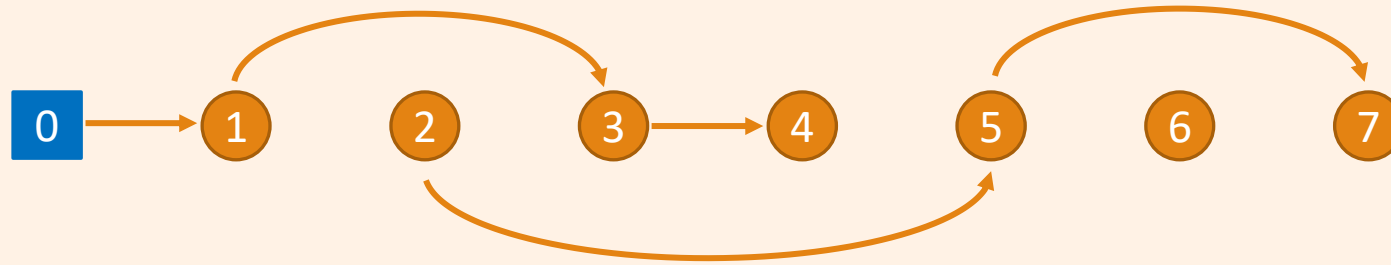
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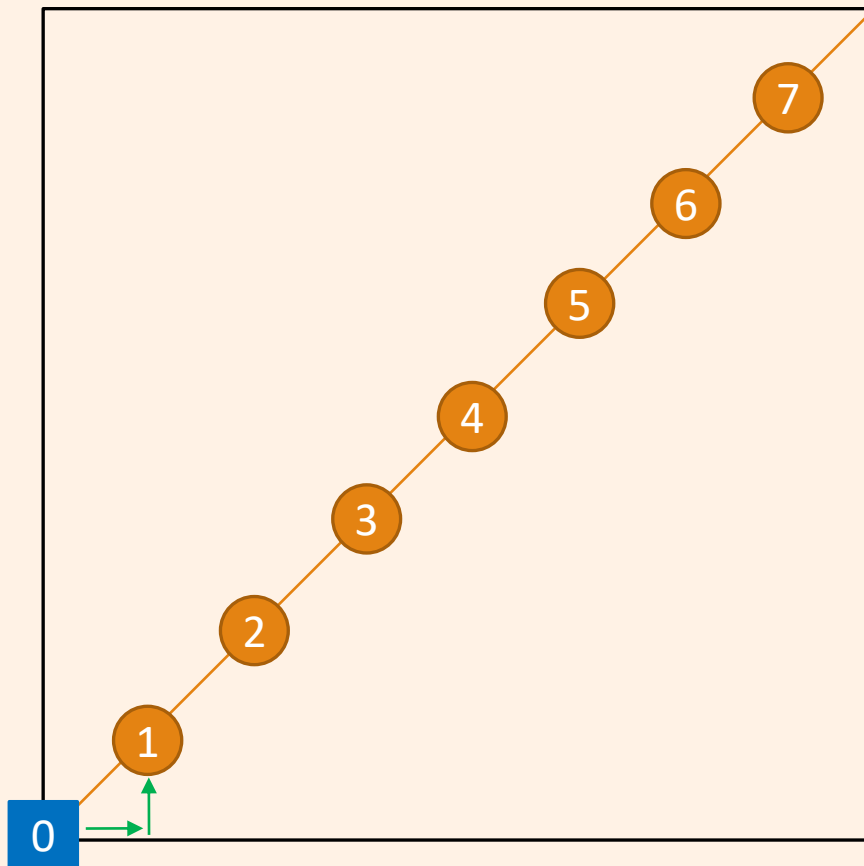
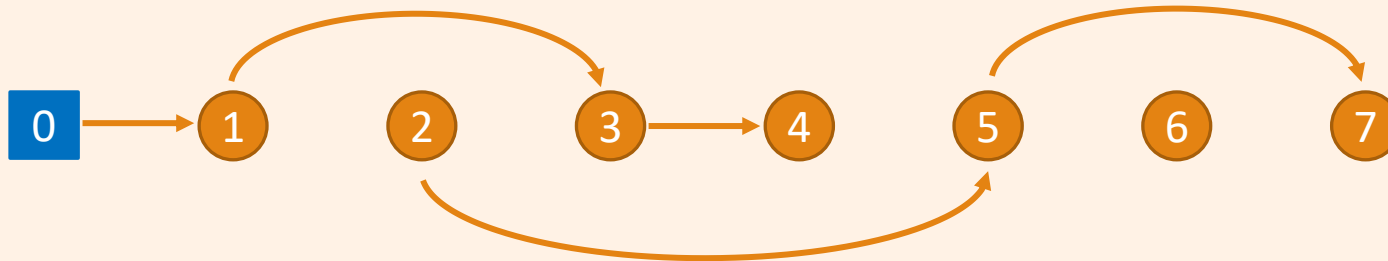
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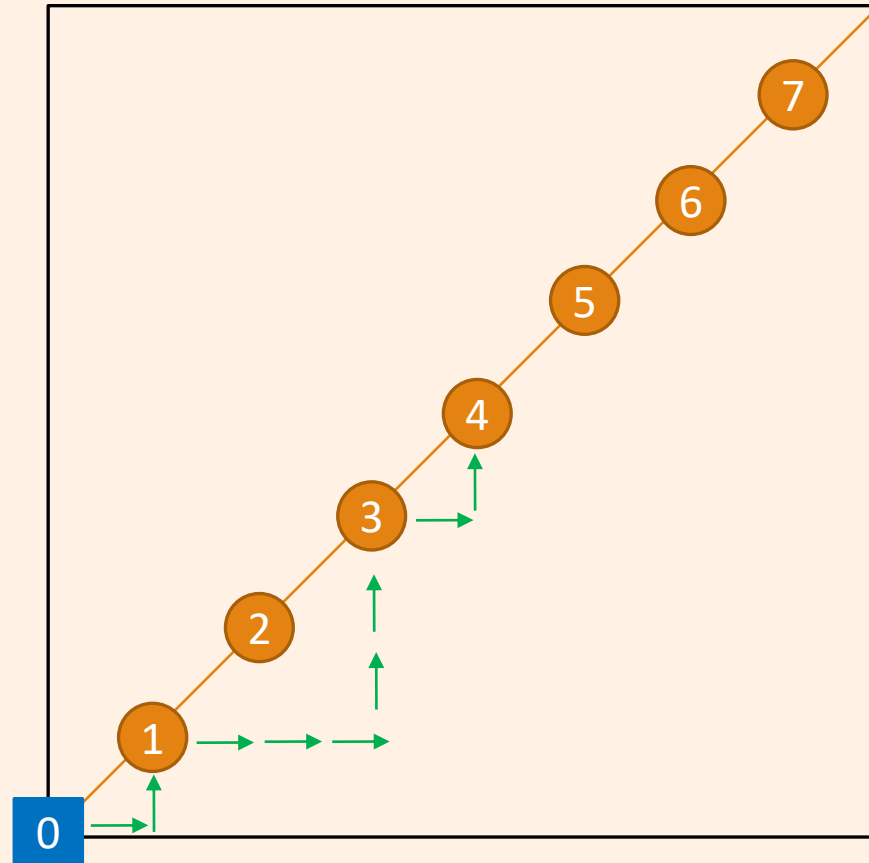
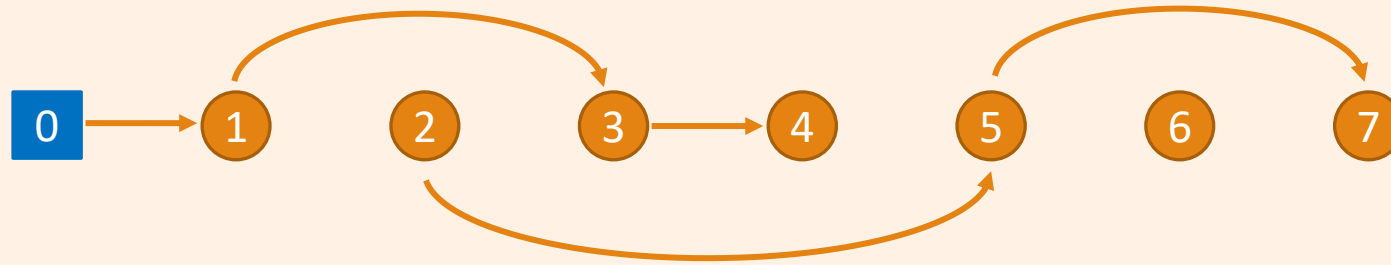


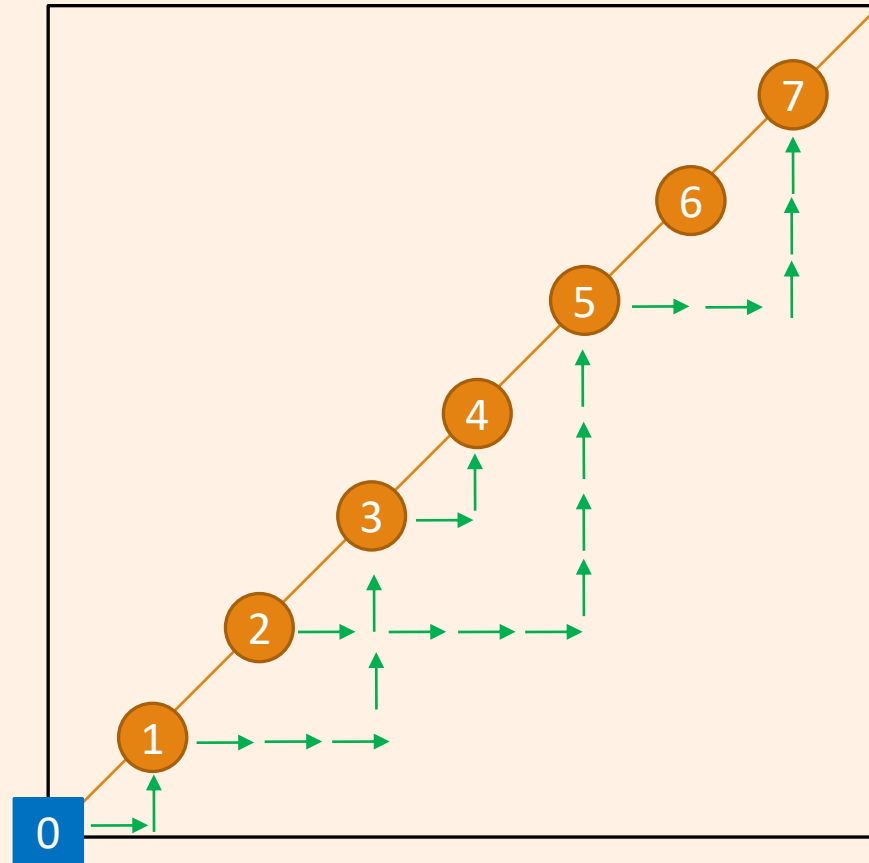
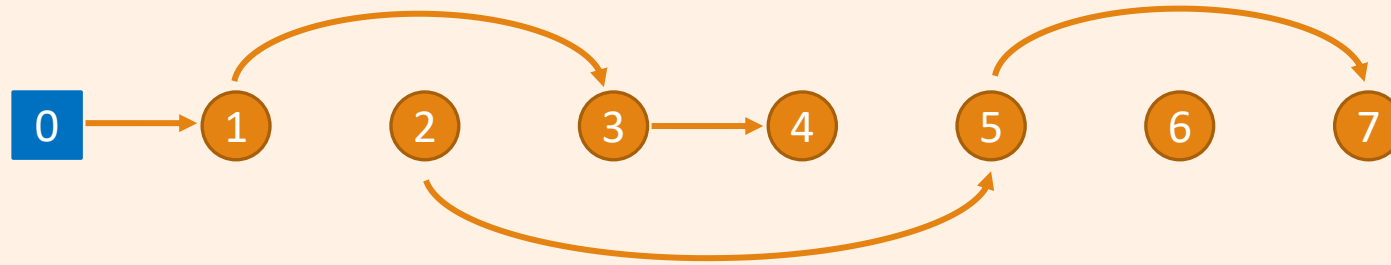
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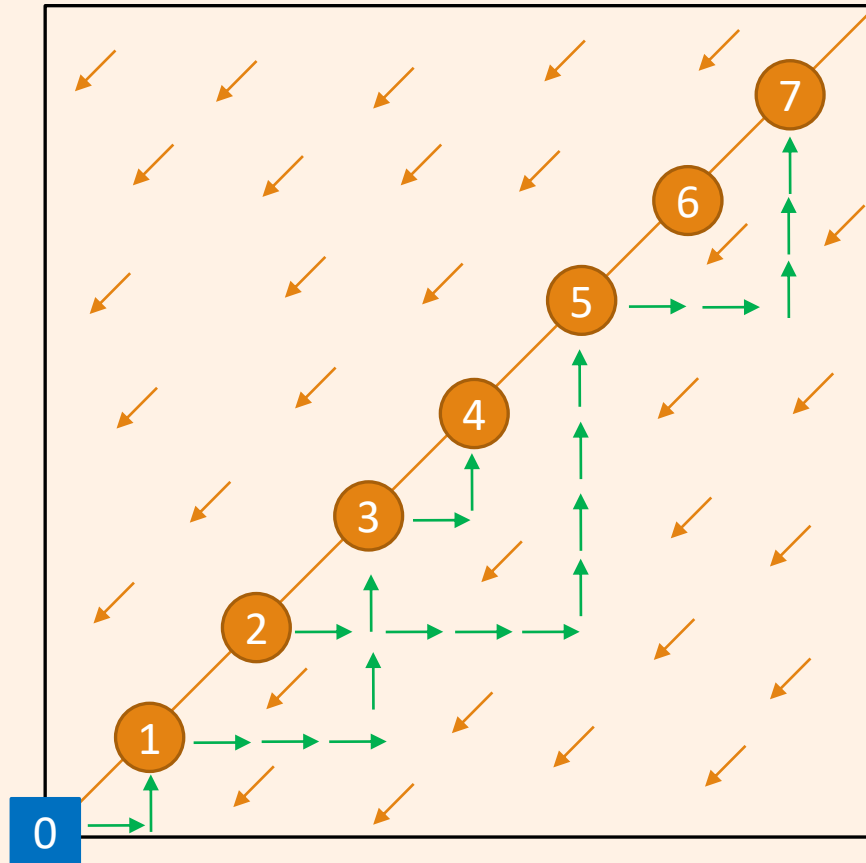
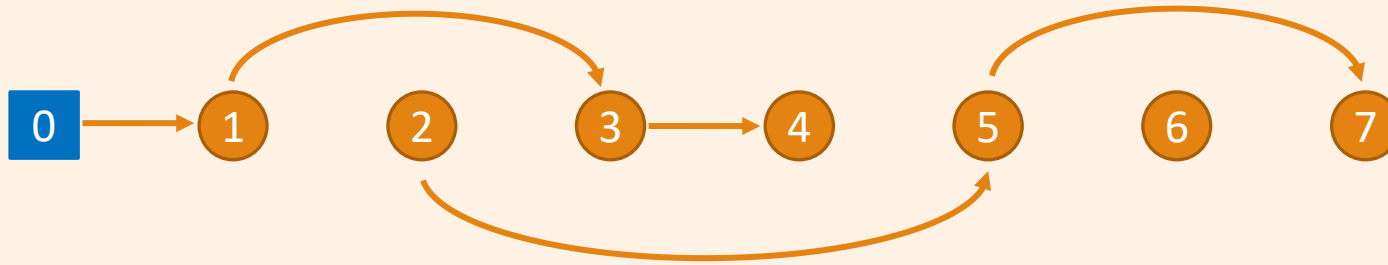


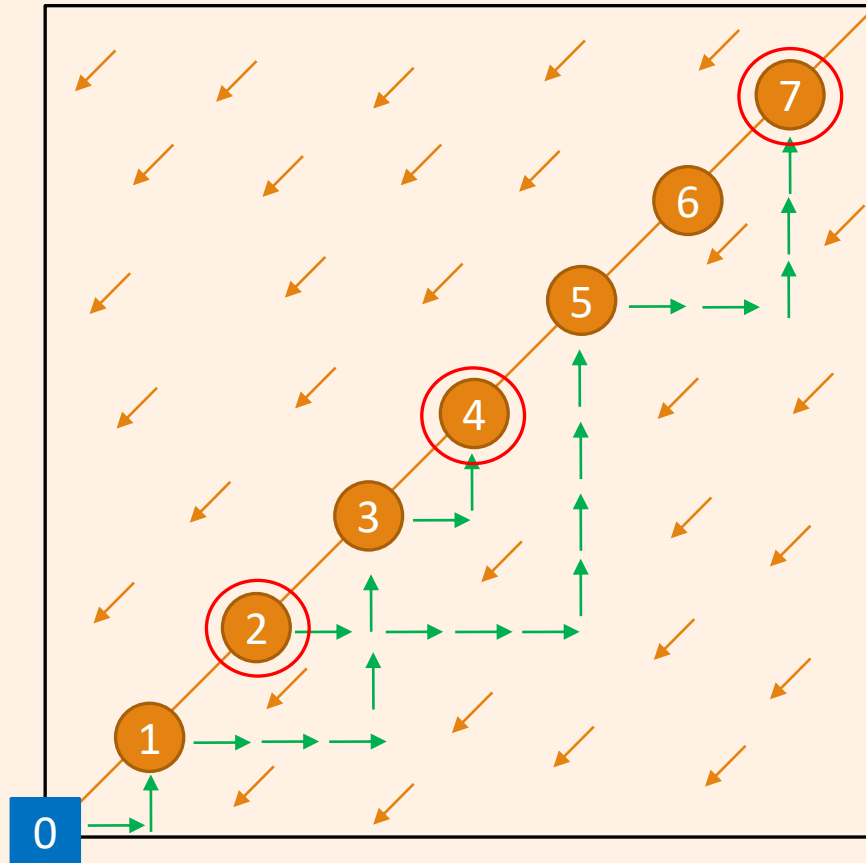
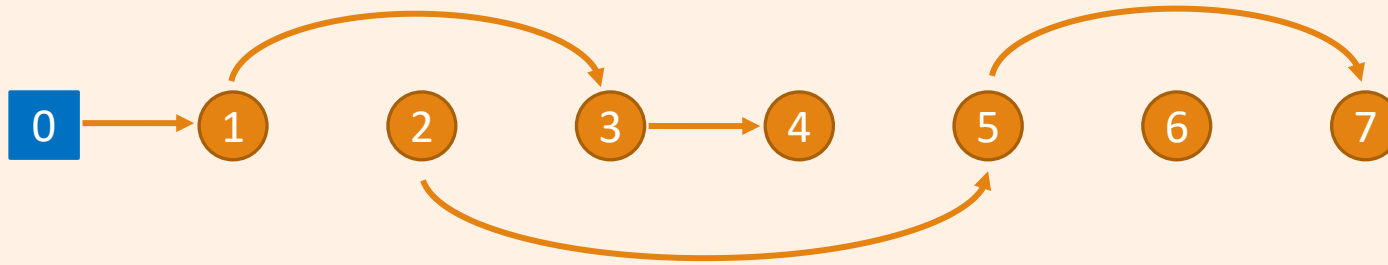


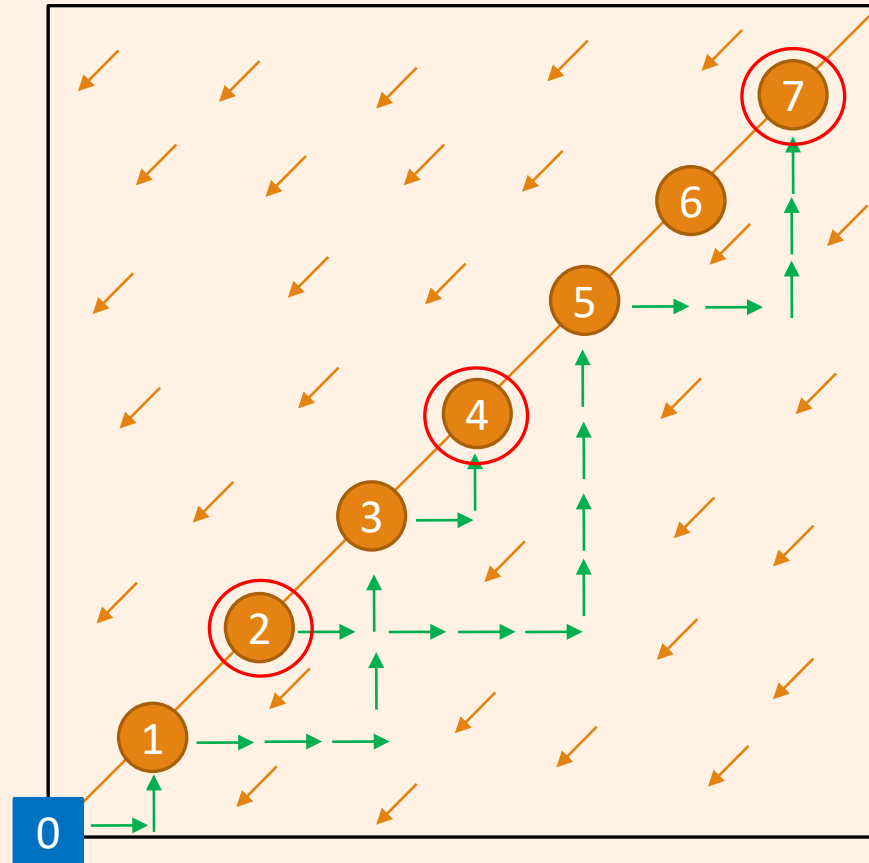
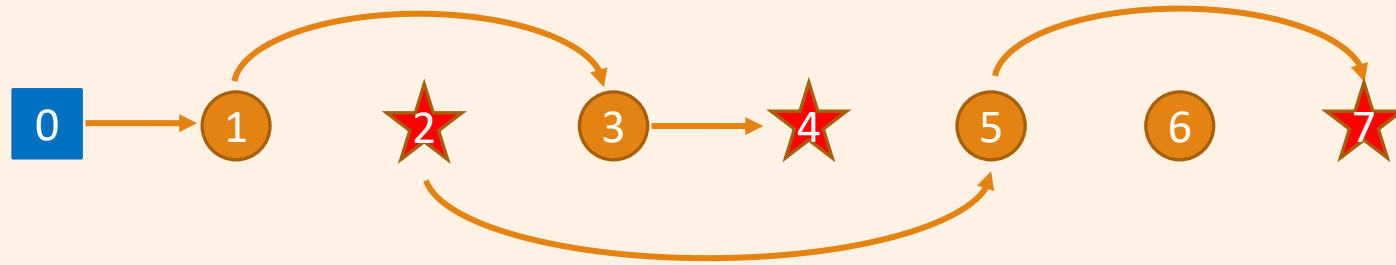


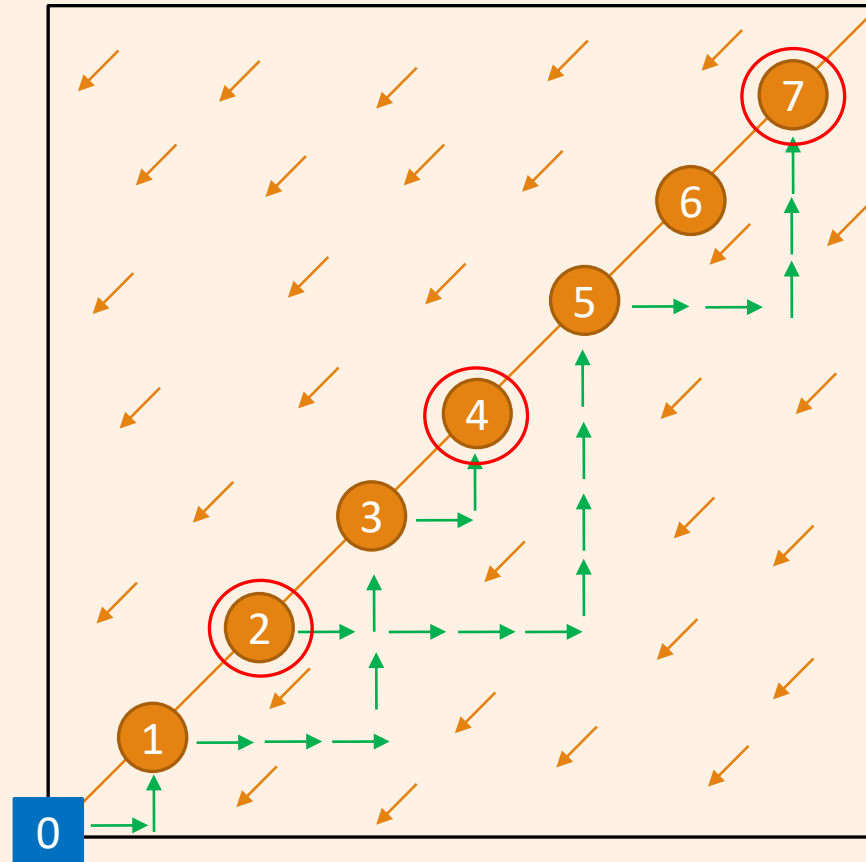
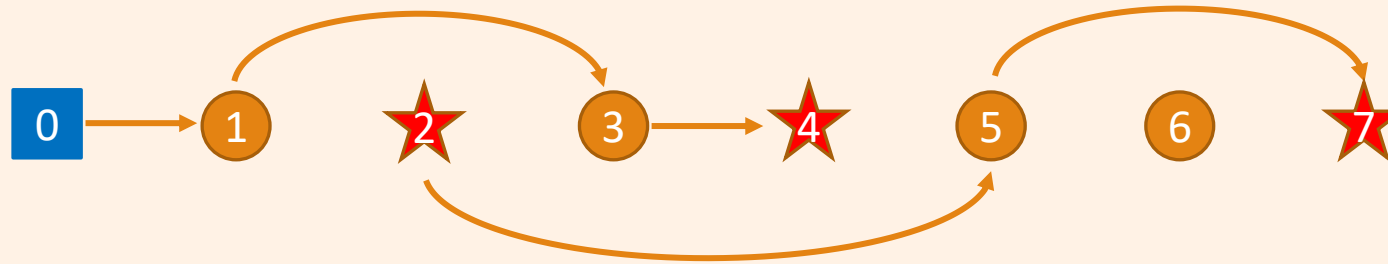












Locally computable!

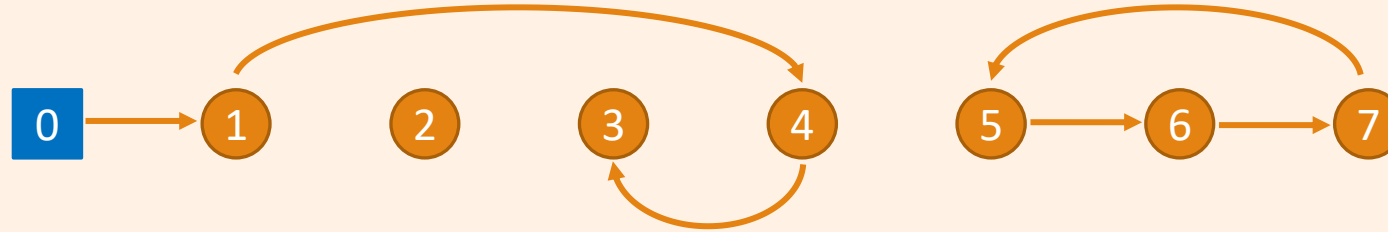
[Hubáček-Yogev, 2017] for CLS

Back to standard End-of-Line

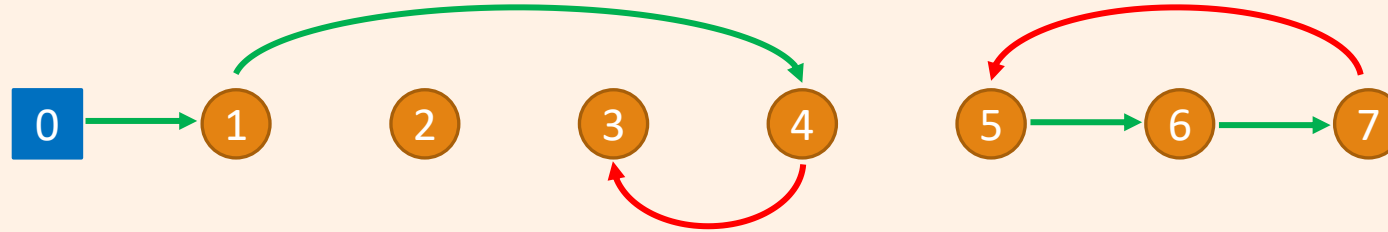
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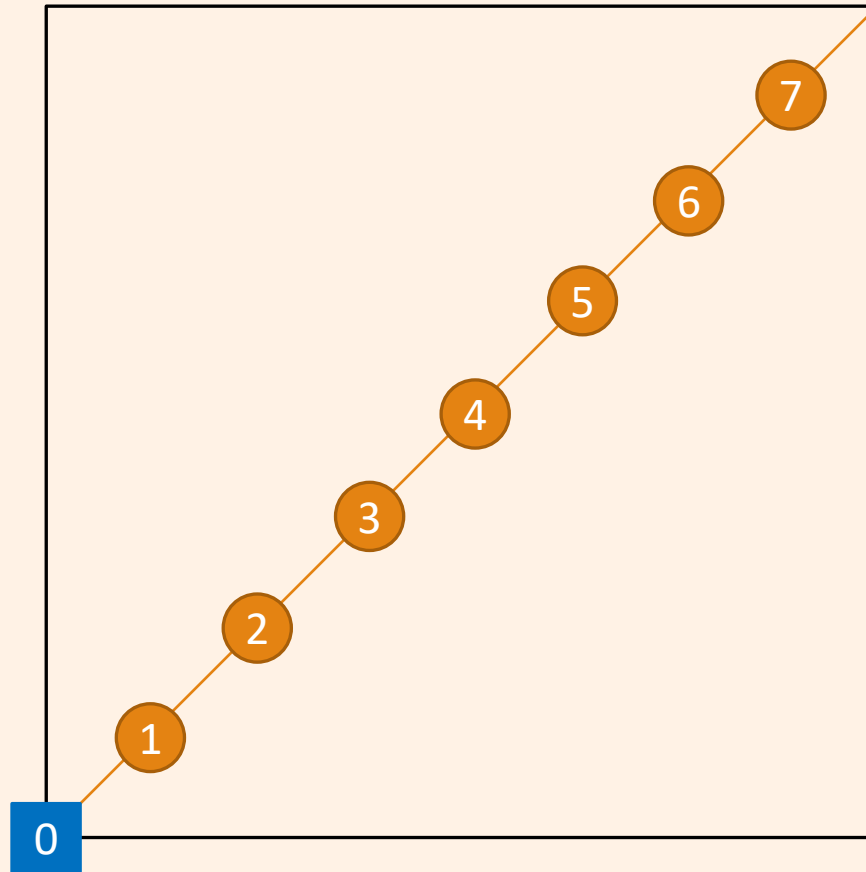
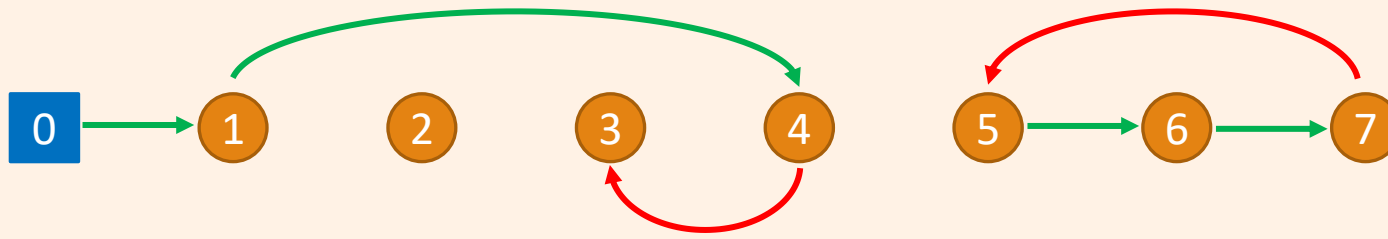
Back to standard End-of-Line

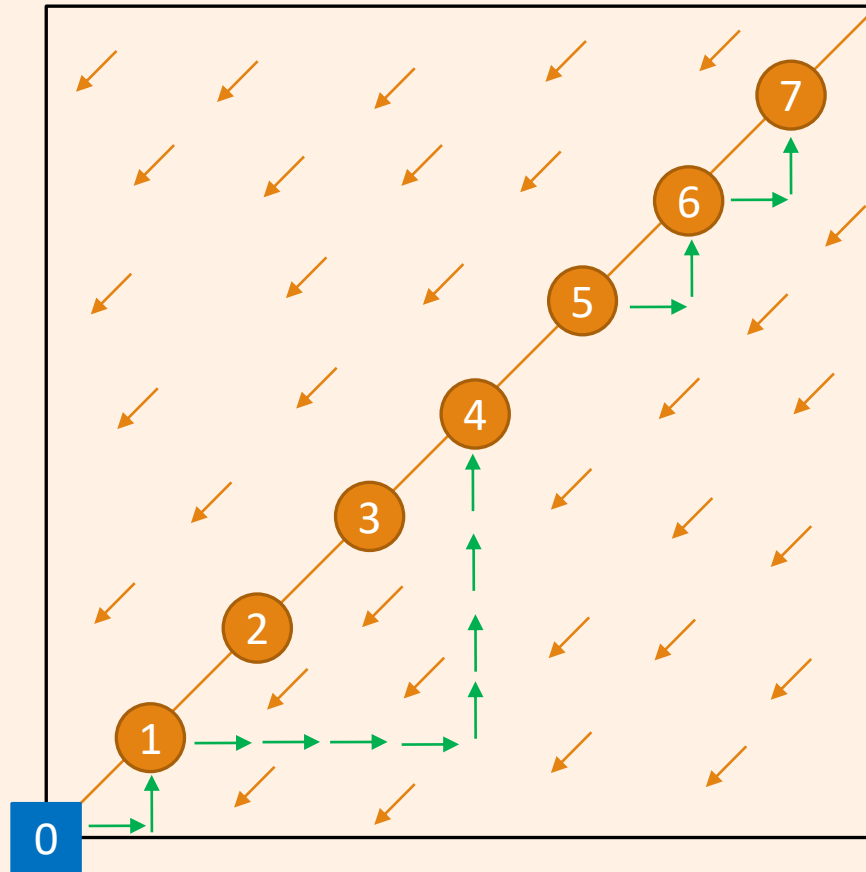
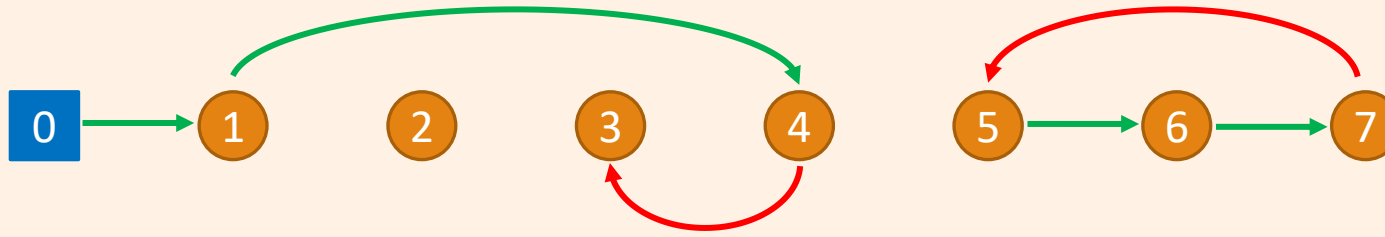


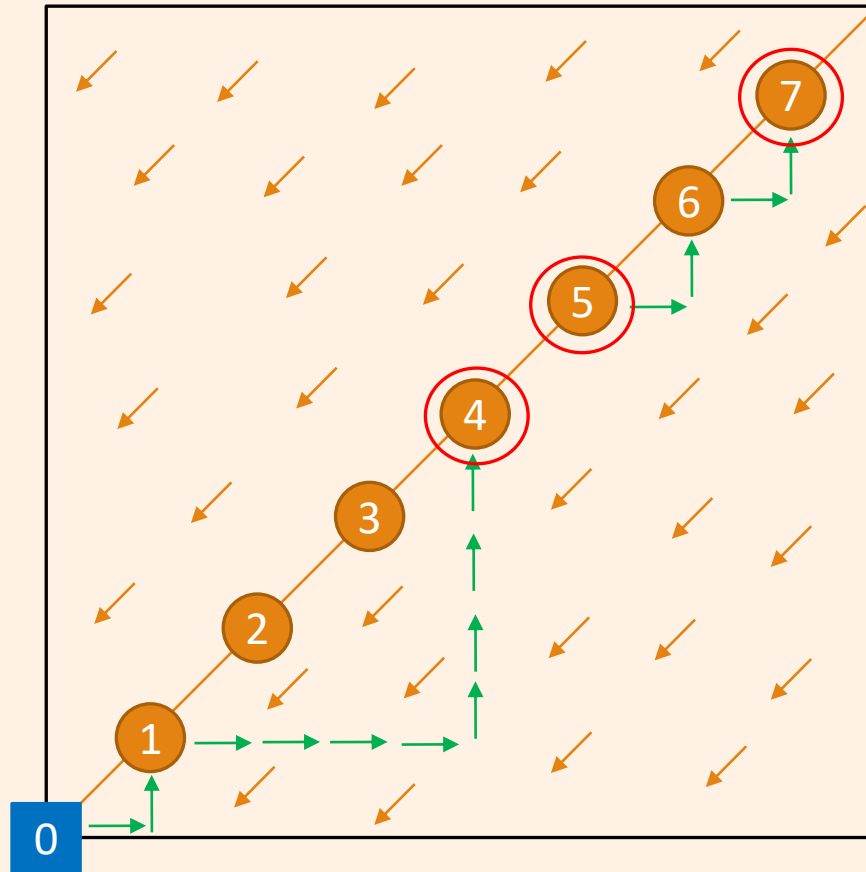
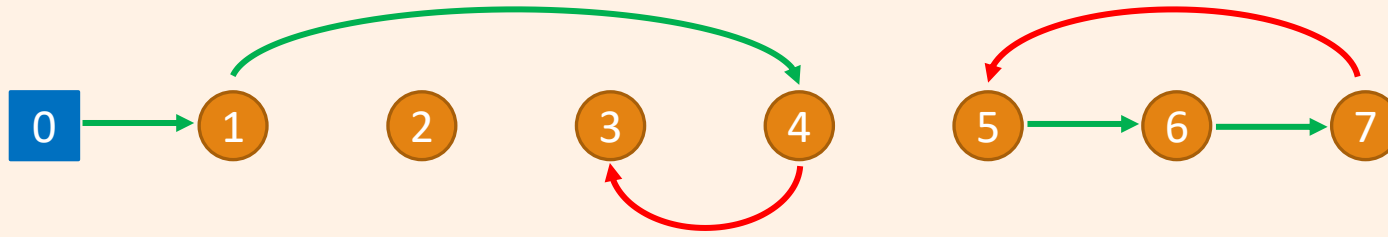
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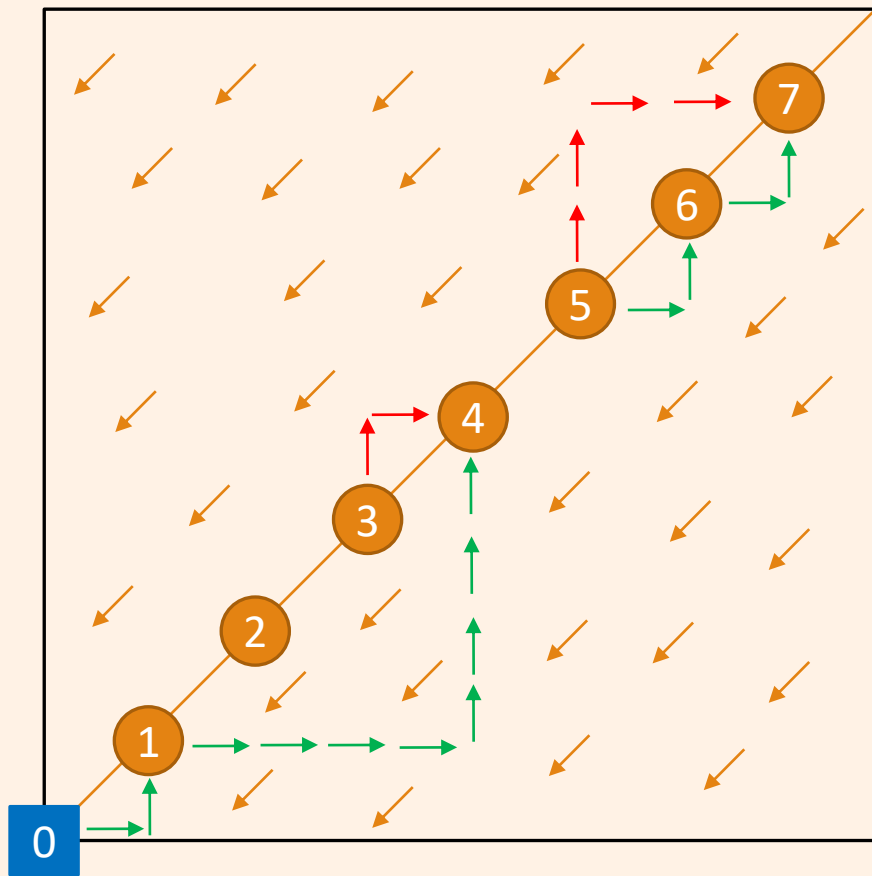
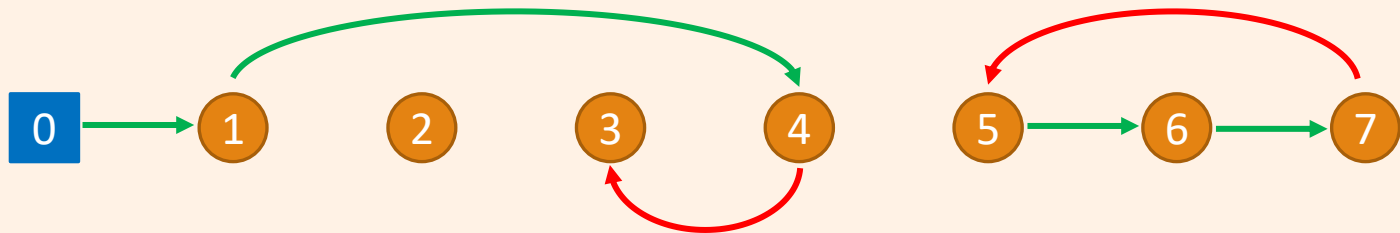


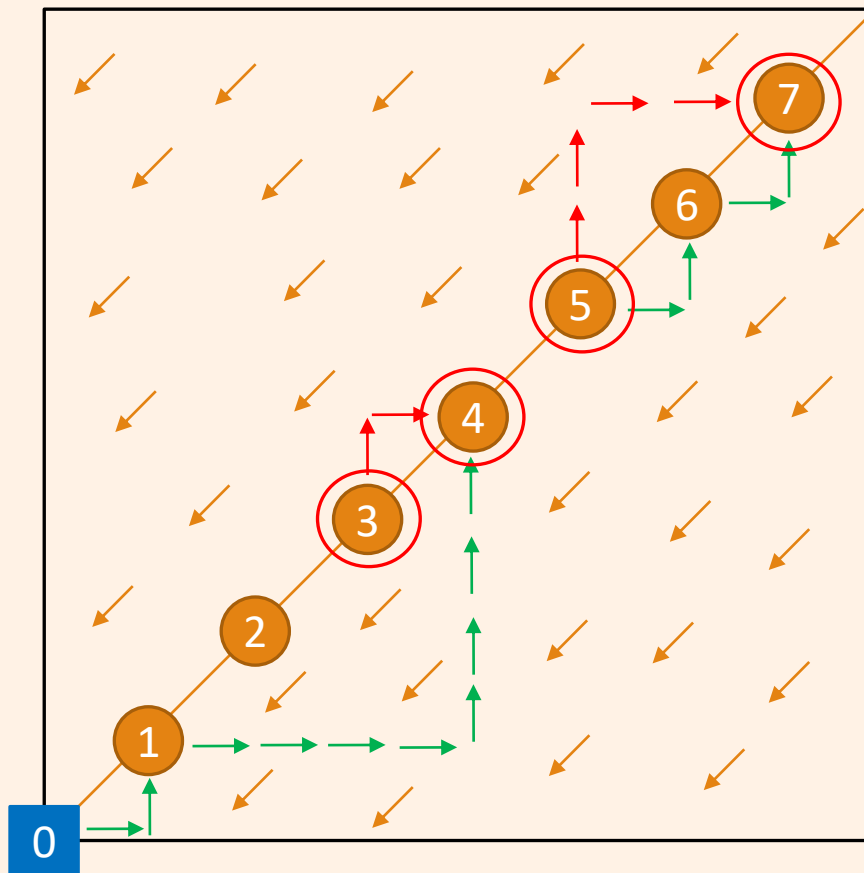
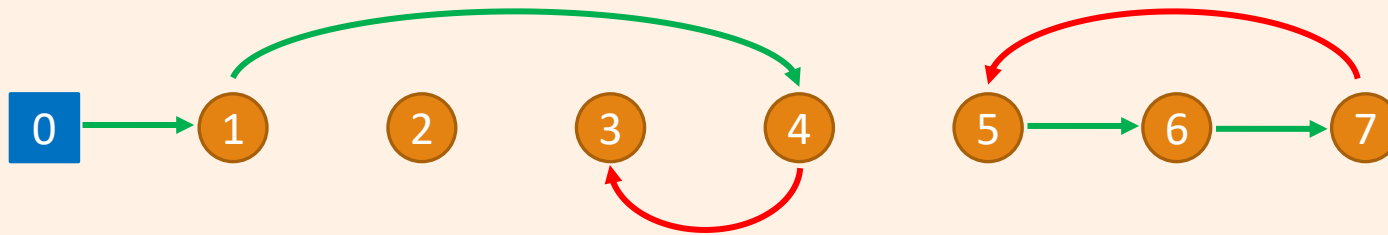
green edges: forward
red edges: backwards

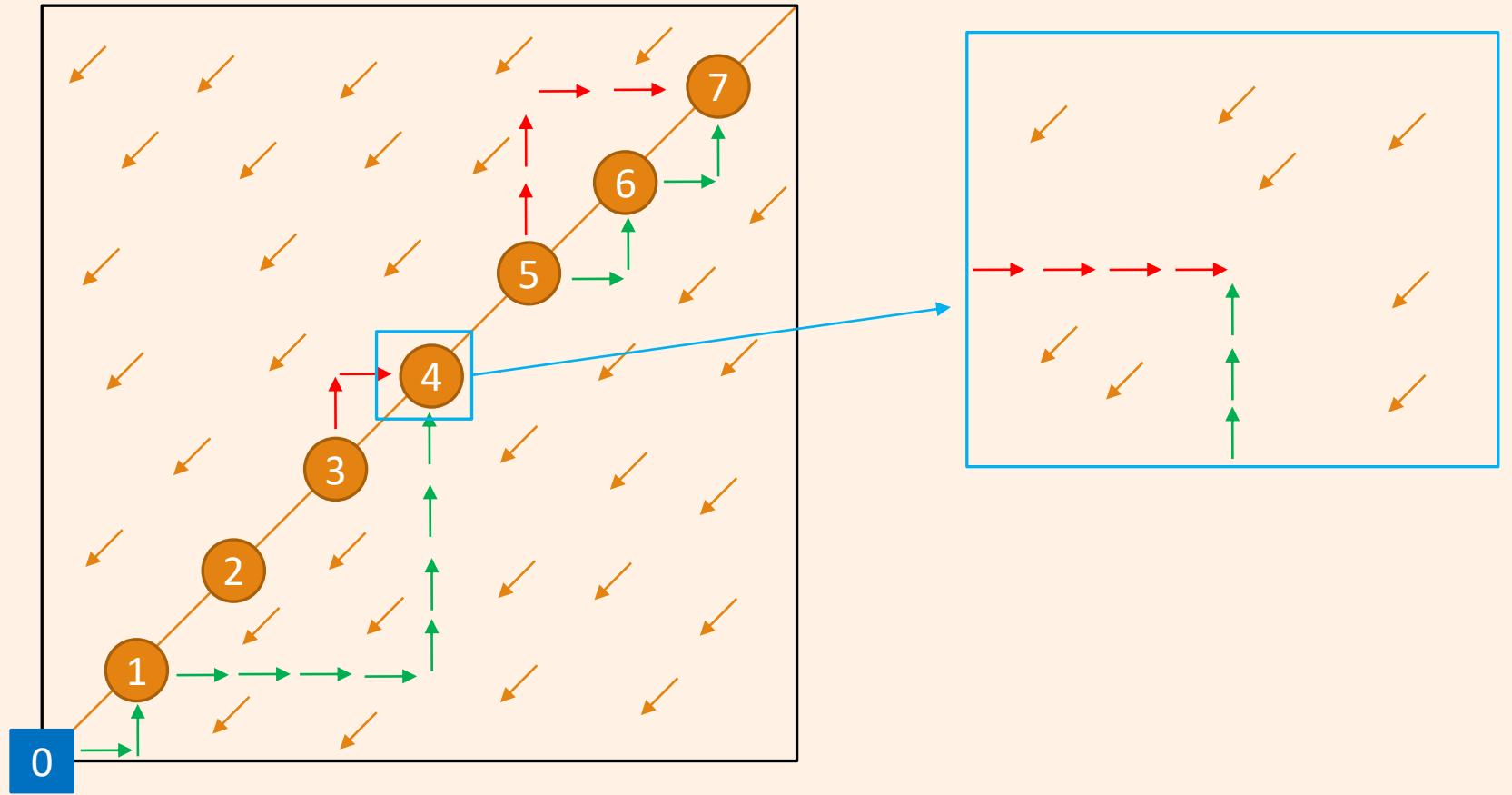
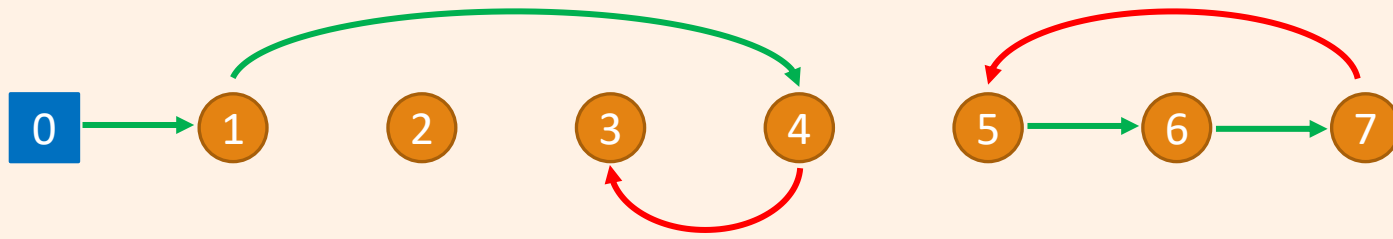


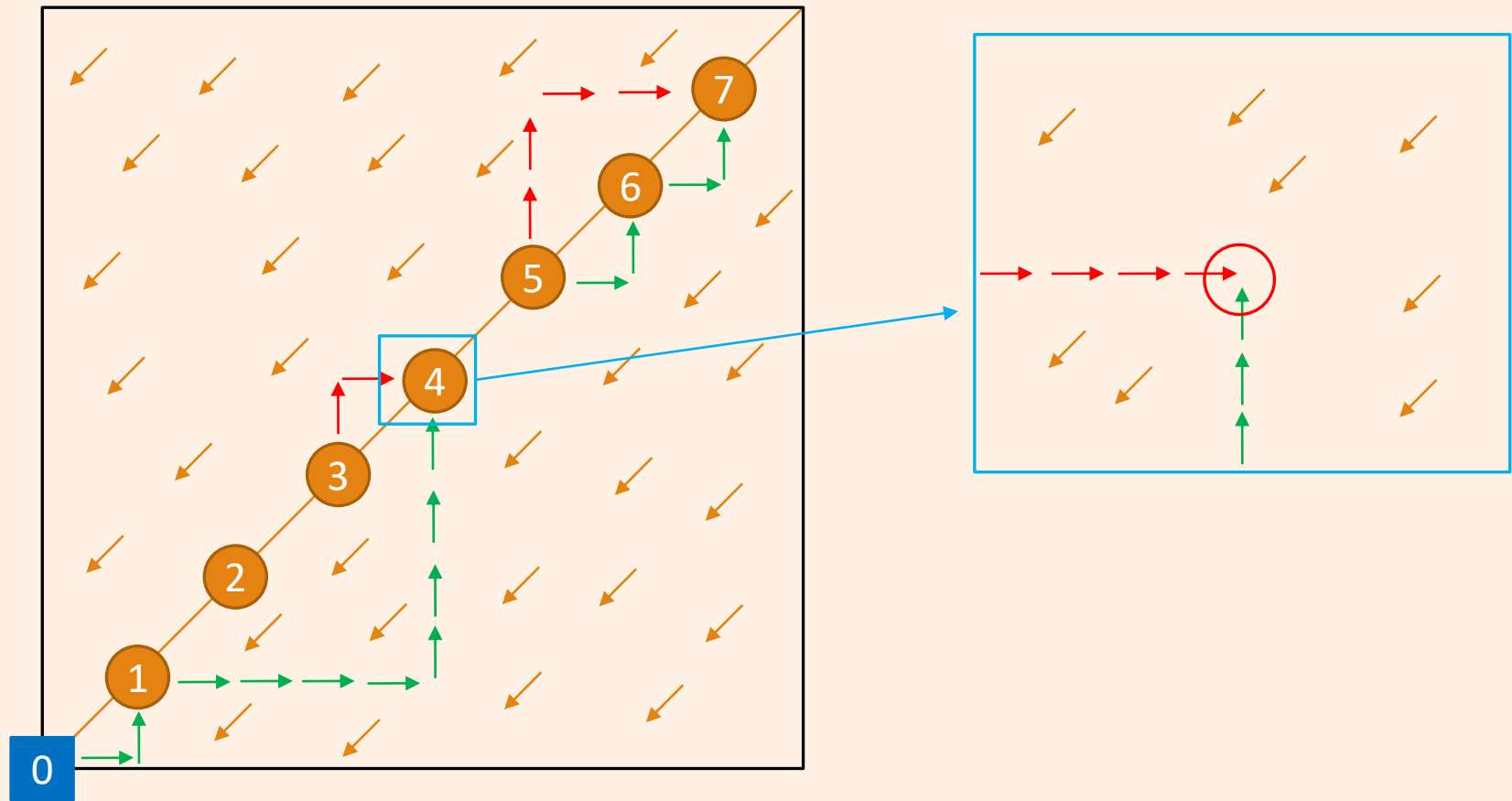
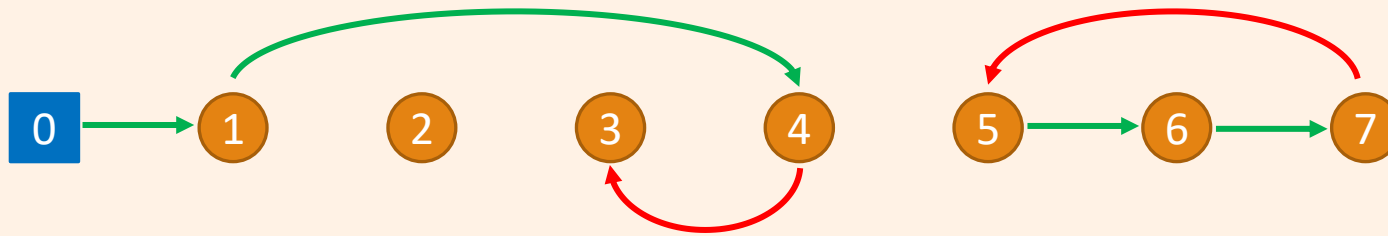


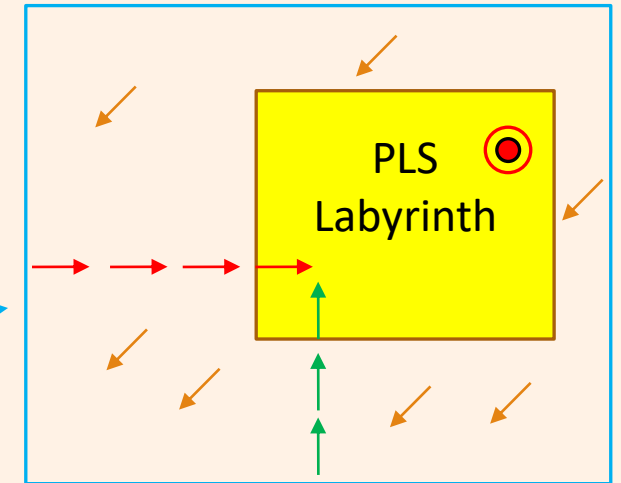
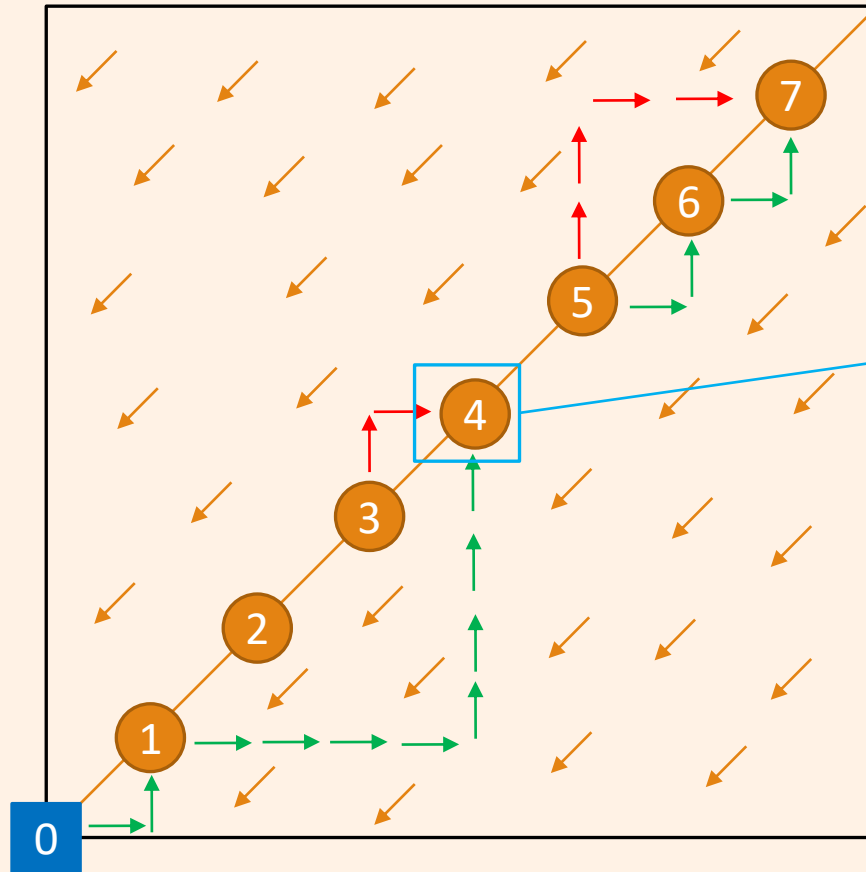
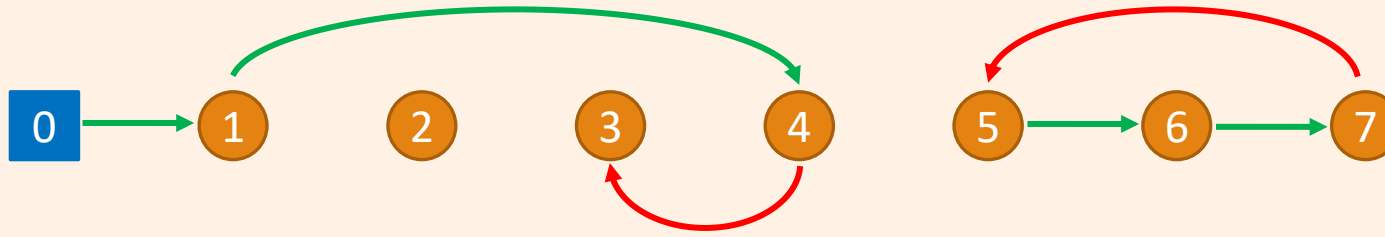




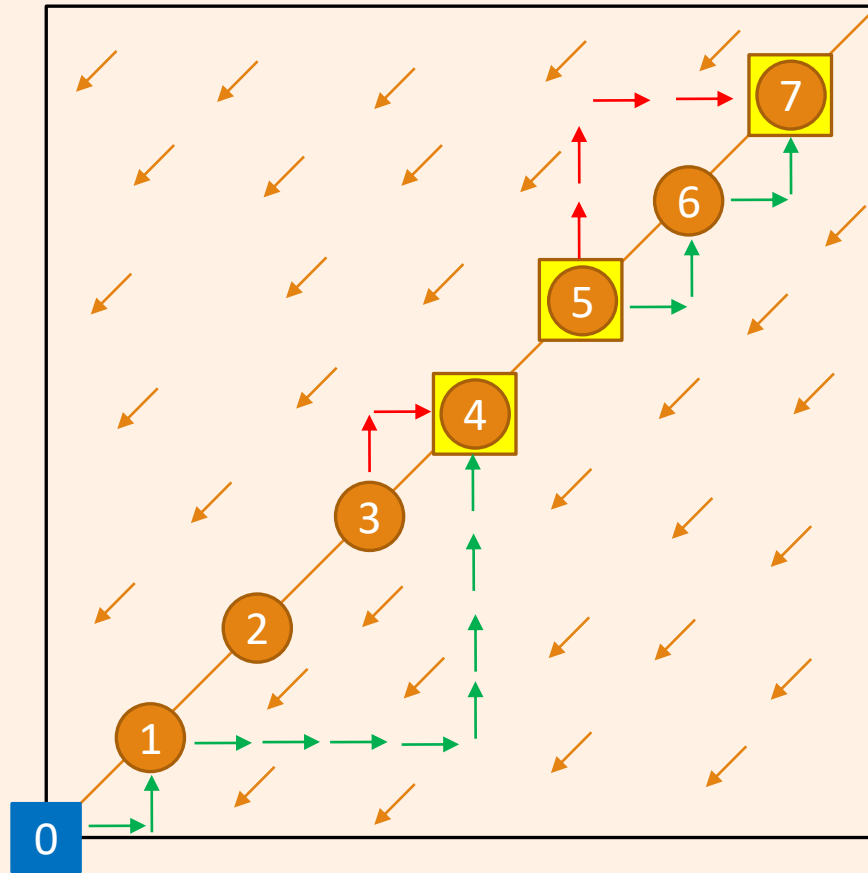
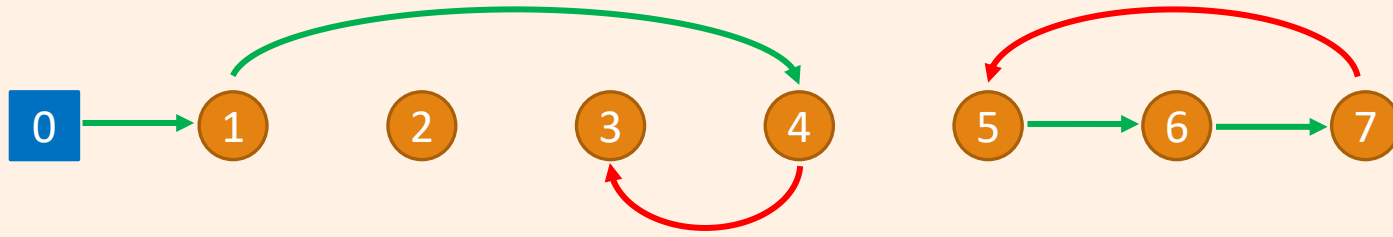


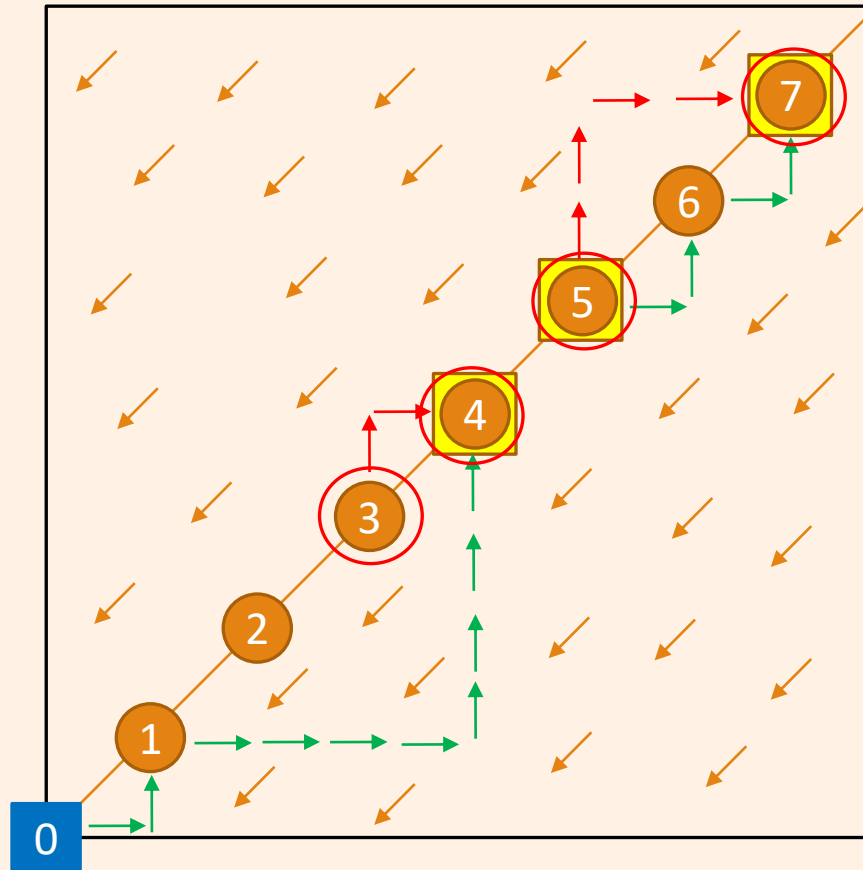
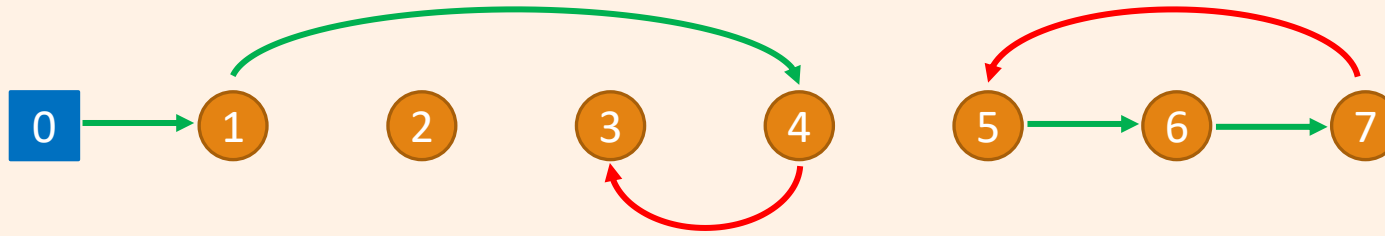






Requires solving the PLS instance!





→ to find a gradient descent fixed point, we have to solve the PPAD problem or the PLS problem

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[Babichenko-Rubinstein, 2020]

2D-GD-FIXED-POINT \leq MIXED-CONGESTION \leq POLYNOMIAL-KKT

Thank You!