

# Recent progress on geometric complexity theory

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# Agenda

- 1 Algebraic Complexity Theory
- 2 Geometric Complexity Theory

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1 Algebraic Complexity Theory

2 Geometric Complexity Theory

## The quest for computational complexity lower bounds

- The separation of complexity classes such as P and NP is one of the most fundamental open problems at the intersection of theoretical computer science and mathematics.
- Progress has been very slow! Proving lower bounds seems very difficult!
- Valiant (1979) found a close connection between complexity questions and natural questions in algebra:

### Theorem (Valiant 1979)

Every multivariate polynomial  $f$  can be written as the determinant of a matrix whose entries are polynomials of degree  $\leq 1$ . The dimension of the matrix is at most the smallest number of arithmetic operations in a formula computing  $f$ .

Example:  $f := y + 2x + xz + 2xy - x^2z = \det \begin{pmatrix} x & y & 0 \\ -1 & z + y + 2 & x \\ 1 & z & 1 \end{pmatrix}$

Def.: Required dimension of the matrix is called the **determinantal complexity**  $dc(f)$ .

In the example we have  $dc(f) \leq 3$ .

The class VDET consists of all sequences of polynomials  $f_m$  with polyn. bounded  $dc(f_m)$ .

“VDET = easy to compute”

Examples:  $\det_m \in \text{VDET}$ ,  $x_1 x_2 \cdots x_m \in \text{VDET}$ ,  $x_1^m + x_2^m + \cdots + x_m^m \in \text{VDET}$

## The permanent polynomial and VNP

$$\text{per}_m(x_{1,1}, x_{1,2}, \dots, x_{m,m}) := \sum_{\pi \in \mathfrak{S}_m} x_{1,\pi(1)} x_{2,\pi(2)} \cdots x_{m,\pi(m)}$$

- Set all  $x_{i,j}$  to 0 or 1: then  $\text{per}_m$  = number of perfect matchings in bipartite graph.
- Set all  $x_{i,j}$  to 0 or 1: then  $\text{per}_m$  = number of cycle covers in directed graph.
- Applications in theor. physics: Wavefunctions describing identical bosons
- $\#P$ -complete as a function

Valiant's universality theorem holds also for the permanent:

Every multivariate polynomial  $f$  can be written as the permanent of a matrix whose entries are polynomials of degree  $\leq 1$ .

Def.: Required size of the matrix is called the **permanental complexity**  $\text{pc}(f)$ .

The class VNP consists of all sequences of polynomials  $f_m$  with polyn. bounded  $\text{pc}(f_m)$ .

Valiant's "Determinant vs Permanent" Conjecture (1979)

- $\text{VDET} \neq \text{VNP}$ . Equivalently:  $\text{dc}(\text{per}_m)$  is not polynomially bounded.

Remark: Over characteristic 2 we have  $\text{per}_m = \text{det}_m$ , so we replace  $\text{per}_m$  by the Hamiltonian cycle polynomial.

## Connections to Boolean complexity

Separating  $\text{VDET} \neq \text{VNP}$  is “easier” than Boolean complexity (Bürgisser 1998):

- $\text{P/poly} \neq \text{NP/poly}$  implies  $\text{VDET} \neq \text{VNP}$  over finite fields.
- $\text{P/poly} \neq \text{NP/poly}$  implies  $\text{VDET} \neq \text{VNP}$  over  $\mathbb{C}$ , assuming the generalized Riemann hypothesis.

$\text{P/poly} \neq \text{NP/poly}$  is widely believed: If  $\text{NP} \subseteq \text{P/poly}$ , then

- $\text{PH} = \Sigma_2^{\text{P}}$  (Karp-Lipton, 1980, Sipser) and
- $\text{AM} = \text{MA}$  (Arvind, Köbler, Schöning, 1995).

## Determinantal complexity of the permanent

Upper bound:

- $\text{dc}(\text{per}_m) \leq 2^m - 1$  [Grenet; 2011]

Lower bounds:

- $\text{dc}(\text{per}_m) \geq \frac{m^2}{2}$  over  $\mathbb{C}$  [Mignon, Ressayre; 2004]
- $\text{dc}(\text{per}_m) \geq (m - 1)^2 + 1$  over  $\mathbb{R}$  [Yabe; 2015]
- $\text{dc}(\text{per}_3) = 7$  [Alper, Bogart, Velasco; 2015]
- $\text{dc}(\text{per}_4) \geq 9$  [Alper, Bogart, Velasco; 2015]

[Bringmann, I, Zuiddam; JACM 2018] **simplifies** the computational model:  
Same as determinantal complexity, but the only allowed matrices are:

- Tridiagonal matrices with secondary diagonals only 1s.

$$\det \begin{pmatrix} x & 1 & 0 & 0 \\ 1 & -1 & 1 & 0 \\ 0 & 1 & x & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} = x + 1 \quad \det \begin{pmatrix} \varepsilon^{-1}x & 1 & 0 & 0 & 0 \\ 1 & \varepsilon^2 & 1 & 0 & 0 \\ 0 & 1 & -\varepsilon^{-1}x & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & y \end{pmatrix} = \underbrace{x^2 + y - \varepsilon xy}_{\xrightarrow{\varepsilon \rightarrow 0} x^2 + y}$$

The required matrix dimension is called the **continuant complexity**  $cc(f)$ .

(Name based on the continuant polynomial from the theory of continued fractions)

For some polynomials  $cc(f) = \infty$  (Allender, Wang 2011).

### Definition (border continuant complexity)

Let  $\underline{cc}(f)$  denote the smallest  $n$  such that  $f$  can be approx. arbitrarily closely by polynomials  $f_\varepsilon$  with  $cc(f_\varepsilon) \leq n$ .

### Theorem [Bringmann, I, Zuiddam]

$\underline{cc}(f) < \infty$ . Moreover, if  $\underline{cc}(\text{per}_m)$  grows superpolynomially, then  $\text{VF} \neq \text{VNP}$   
( $\text{VF} = \text{VDET}$  up to quasipolynomial blowup).

→ The definition of  $\underline{cc}$  is analogous to border Waring rank (fast matrix multiplication)!

## Waring rank

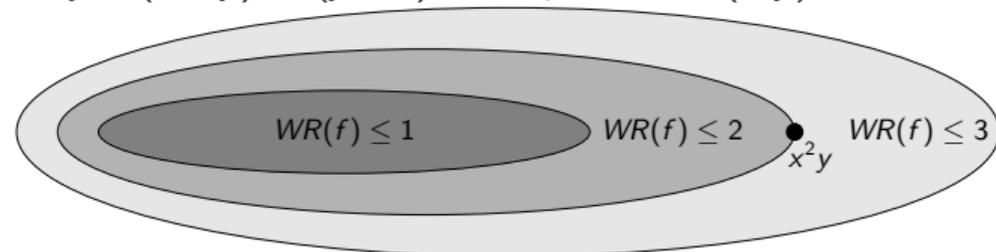
## Theorem (Waring rank is finite)

For every homogeneous degree  $d$  polynomial  $f$  there exists a decomposition  $f = \sum_{i=1}^r (l_i)^d$ , where each  $l_i$  is a homogeneous linear polynomial. The smallest possible  $r$  is called the **Waring rank**  $WR(f)$  or **symmetric rank** of  $f$ .

Remark: Waring rank was used by Pratt [FOCS 2019] to obtain a faster algorithm for approximately counting subgraphs of bounded treewidth.

Example:

$6x^2y = (x+y)^3 + (y-x)^3 - 2x^3$ , hence  $WR(x^2y) \leq 3$ . In fact,  $WR(x^2y) = 3$ .



$$3x^2y = \lim_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \left( (x + \varepsilon y)^3 - x^3 \right)$$

This makes determining  $WR(W)$  subtle! Continuous methods cannot prove  $WR(W) > 2$ .

The **border Waring rank**  $\underline{WR}(f)$  is defined as the smallest  $r$  such that  $f$  can be approximated arbitrarily closely by polynomials of Waring rank  $\leq r$ .

## Border Waring rank of cubic polynomials: fast matrix multiplication

$$M_m := \sum_{i,j,k=1}^m x_{i,j} \cdot x_{j,k} \cdot x_{k,i} \in \mathbb{C}[x_1, \dots, x_{m^2}]_3$$

$\omega$  := smallest  $k$  such that for all  $\varepsilon > 0$  there exists an  $O(n^{k+\varepsilon})$  time algorithm to multiply  $n \times n$  matrices.

Theorem [Chiantini, Hauenstein, I., Landsberg, Ottaviani 2017]

$$\omega = \liminf \{ \log_m WR(M_m) \} = \liminf \{ \log_m \underline{WR}(M_m) \}$$

Recent progress (Alman and Vassilevska Williams, SODA2021):  $\omega \leq 2.3728639$

## Summary part I

- If  $\text{NP} \not\subseteq \text{P/poly}$ , then  $\text{dc}(\text{per}_m)$  grows superpolynomially (assuming GRH).
- The study of  $\text{dc}(\text{per}_m)$  is difficult. Continuant complexity is a simpler model of computation, but it requires approximations.
- Such approximations are classically studied in the setting of fast matrix multiplication.

We will now see: These approximations are hard-wired into GCT

1 Algebraic Complexity Theory

2 Geometric Complexity Theory

## Orbit closures and the padded permanent

Define  $E(\det_n) :=$  determinants of  $n \times n$  matrices whose entries are homogeneous linear polynomials.

$$\det \begin{pmatrix} x_{1,1} + x_{1,2} & x_{1,2} - 2x_{2,2} \\ x_{2,1} & x_{1,1} + x_{1,2} \end{pmatrix} = x_{1,1}^2 + 2x_{1,1}x_{1,2} + x_{1,2}^2 - x_{1,2}x_{2,1} + 2x_{2,1}x_{2,2} \in E(\det_2)$$

Using approximations can be naturally be phrased as the Euclidean closure (equivalent to Zariski closure here):

$$\mathcal{D}et_n := \overline{E(\det_n)}.$$

[Hüttenhain, Lairez; 2016] classify all polynomials that are in  $\mathcal{D}et_3$  but not in  $E(\det_3)$ . E.g.,

$$x_1^2 y_1 + x_2^2 y_2 + x_3^2 y_3 + x_1 x_2 z_3 + x_1 z_2 x_3 + z_1 x_2 x_3$$

## Lower bound method [Mulmuley and Sohoni, 2001]

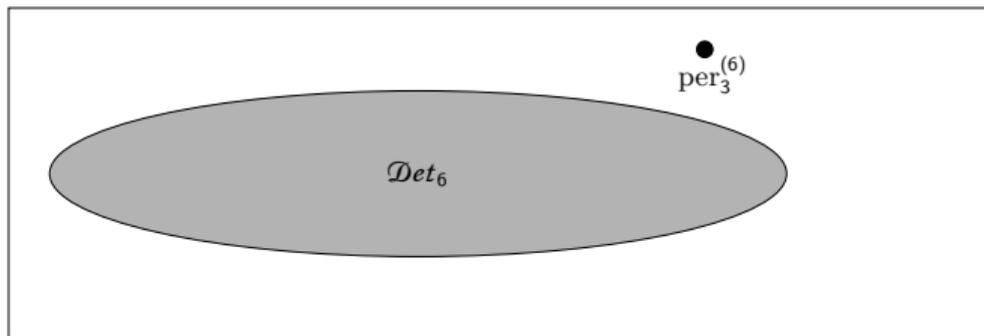
Define the **padded permanent**:  $\text{per}_m^{(n)} := x_{1,1}^{n-m} \text{per}_m$ .

$$\text{per}_m^{(n)} \notin \mathcal{D}et_n \quad \text{implies} \quad \text{dc}(\text{per}_m) > n.$$

With algebraic geometry one can show:  $\mathcal{D}et_n$  is a **projective variety**.

This gives a lot of additional structure to  $\mathcal{D}et_n$ !

In particular, we “know in principle how to separate”  $\text{per}_m^{(n)} \notin \mathcal{D}et_n$



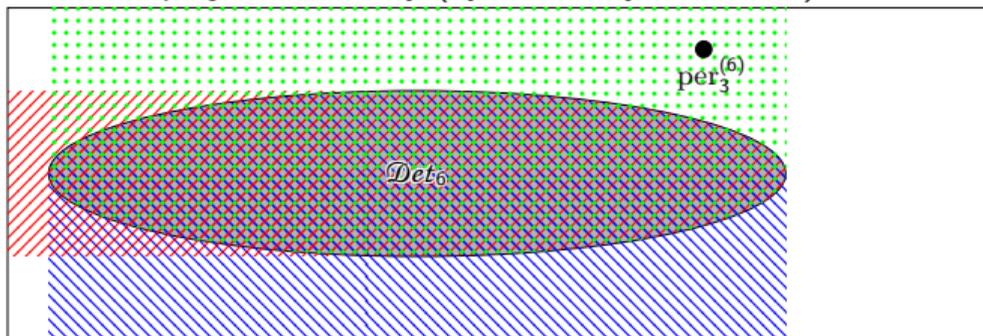
would imply  $\text{dc}(\text{per}_3) > 6$

## $\mathcal{D}et_n$ is a projective variety

A subset  $\mathcal{D} \subseteq \mathbb{C}^N$  is a **projective variety** if there exist finitely many homogeneous polynomials  $\Delta_1, \dots, \Delta_k$  such that

$$f \in \mathcal{D} \quad \text{iff} \quad \Delta_1(f) = \Delta_2(f) = \dots = \Delta_k(f) = 0.$$

$\mathcal{D}et_n$  is a projective variety (by Chevalley's theorem).



would imply  $\text{dc}(\text{per}_3) > 6$

**Consequence:** Points can be separated from varieties via **polynomials**

$\text{per}_m^{(n)} \notin \mathcal{D}et_n$  iff there exists a homogeneous polynomial  $\Delta$  with

- $\Delta(f) = 0$  for all  $f \in \mathcal{D}et_n$  and
- $\Delta(\text{per}_m^{(n)}) \neq 0$ .

Meta-complexity (algebraic natural proofs): What can be said about the complexity of the  $\Delta_i$ ?

## Toy example (Waring rank)

$$\mathbb{A} := \mathbb{C}[x, y]_2 = \langle x^2, xy, y^2 \rangle.$$

Every element in  $\mathbb{A}$  can be represented as  $ax^2 + bxy + cy^2$ .

- $\mathcal{D} := \{f \in \mathbb{A} \mid \exists \alpha, \beta \in \mathbb{C} : f = (\alpha x + \beta y)^2\}$  Waring rank 1 polynomials
- $f \in \mathcal{D}$  iff  $\Delta(f) = b^2 - 4ac = 0$ .
- To prove  $f$  has  $\text{WR}(f) \geq 2$  we compute  $\Delta(f) \neq 0$ . For example,  $\Delta(xy) = 1 \neq 0$ , hence  $\text{WR}(xy) \geq 2$ .
- We want to study these functions that behave like  $\Delta$ : **Representation theory**

For  $f(x, y) \in \mathcal{D}$  we see that also  $f(y, x) \in \mathcal{D}$ .

What happens to  $b^2 - 4ac$  if we switch the roles of  $x$  and  $y$ ?

- $\tau(x) = y$  and  $\tau(y) = x$
- $\tau(x^2) = y^2$ ,  $\tau(y^2) = x^2$ ,  $\tau(xy) = xy$
- $\tau(a) = c$ ,  $\tau(c) = a$ ,  $\tau(b) = b$
- $\tau(b^2) = b^2$ ,  $\tau(ac) = ac$
- $\tau(b^2 - 4ac) = b^2 - 4ac$

## Group actions

$$\Delta := b^2 - 4ac.$$

Switching the roles of  $x$  and  $y$  is denoted by a multiplication with the matrix  $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ .

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \Delta = \Delta.$$

For any  $2 \times 2$  matrix  $A$ :  $A\Delta = \det(A)^2 \Delta$ .

In particular

$$\begin{pmatrix} 1 & \alpha \\ 0 & 1 \end{pmatrix} \Delta = \Delta; \quad \begin{pmatrix} \alpha_1 & 0 \\ 0 & \alpha_2 \end{pmatrix} \Delta = \alpha_1^2 \alpha_2^2 \Delta$$

Thus  $\Delta$  is a **highest weight polynomial of weight (2,2)**.

### Definition (highest weight polynomial)

A function  $\Delta$  is called a **highest weight polynomial** of weight  $\lambda = (\lambda_1, \dots, \lambda_N)$ , if

- $\Delta$  is invariant under the action of upper triangular matrices with 1s on the diagonal
- and  $\Delta$  gets rescaled by  $\alpha_1^{\lambda_1} \dots \alpha_N^{\lambda_N}$  under the action of diagonal matrices  $\text{diag}(\alpha_1, \dots, \alpha_N)$ .

## Complexity lower bounds via highest weight polynomials

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Recall: Want  $\Delta$  vanishing on  $\mathcal{D}et_n$  and  $\Delta(\text{per}_m^{(n)}) \neq 0$ .

### Theorem (representation theory)

If  $\text{per}_m^{(n)} \notin \mathcal{D}et_n$ , then there exists a highest weight polynomial  $\Delta$  such that  $A\Delta$  vanishes on  $\mathcal{D}et_n$  and  $A\Delta(\text{per}_m^{(n)}) \neq 0$  for a generic matrix  $A$ .

This works in high generality. We just need that  $\mathcal{D}et_n$  is closed under the action of  $\text{GL}_{n^2}$ .

### Crucial conclusion

If complexity lower bounds exist, then there exist highest weight polynomials proving them.

## Complexity of highest weight polynomials

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If complexity lower bounds exist, then there exist highest weight polynomials proving them.

### Theorem (Garg, I, Makam, Oliveira, Walter, Wigderson, CCC 2020)

The hyperpfaffian, which is a highest weight polynomial, is VNP-complete.

### Theorem (Bläser, Dörfler, I, arXiv:2002.11594)

If highest weight polynomials are encoded efficiently (not as a coefficient list, but as Young tableaux), then it is NP-hard to evaluate them at a point of Waring rank 3.

(Efficient evaluation is possible if the tableau has low treewidth.)

## Mulmuley and Sohni's heuristic attempt: Occurrence Obstructions

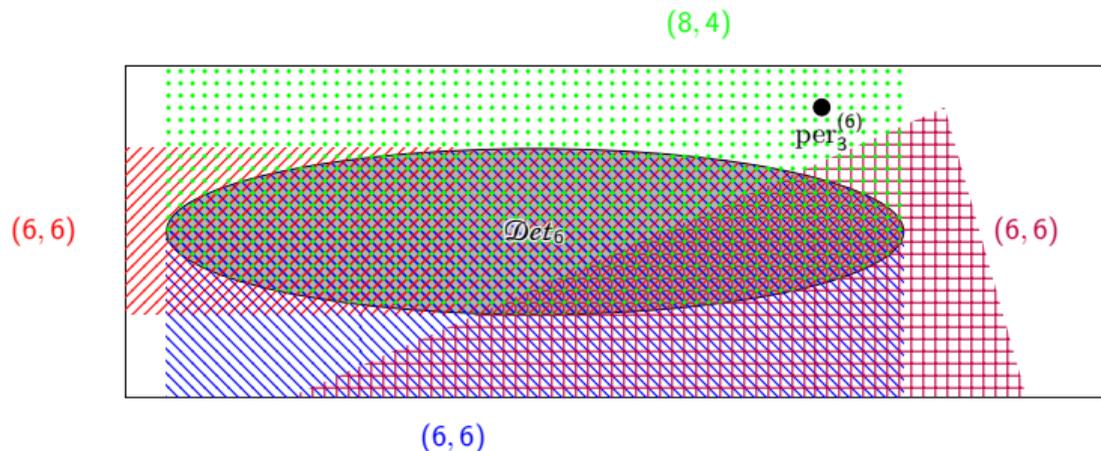
Consider the finite dimensional vector space of highest weight polynomials  $\Delta$  of weight  $\lambda$ .

**Proposition** (a coarse technique for finding complexity lower bounds)

If there exists  $\lambda$  such that for a generic matrix  $A$  we have

- for **all (!)** highest weight polynomials  $\Delta$  of weight  $\lambda$ :  $A\Delta$  vanishes on  $\mathcal{D}et_n$
- there exists a highest weight polynomial  $\Delta$  of weight  $\lambda$  such that  $A\Delta(\text{per}_m^{(n)}) \neq 0$

then  $\text{per}_m^{(n)} \notin \mathcal{D}et_n$ .



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then  $\text{per}_m^{(n)} \notin \mathcal{D}et_n$ .

- We used this approach to show nontrivial border rank lower bounds for the matrix multiplication tensor [Bürgisser, I; STOC 2011, STOC 2013].
- Mulmuley and Sohoni conjectured that this approach could show superpolynomial lower bounds on  $\text{dc}(\text{per}_m)$ . This was too optimistic:

In [I, Panova; FOCS 2016] and later [Bürgisser, I, Panova; FOCS 2016, JAMS] we prove that this approach **cannot** give  $\text{dc}(\text{per}_m) > m^{25}$ .

Remark: The setting can be homogenized so that there is no known no-go result.

## More general heuristic attempt: “Multiplicities”

Mulmuley and Sohoni also proposed a more general approach based on **multiplicities**.

Analogously to  $\mathcal{D}et_n := \overline{E(\det_n)}$  we define the **padded permanent orbit closure**  $\mathcal{P}er_m^{(n)} := \overline{E(\text{per}_m^{(n)})}$ . Key property:

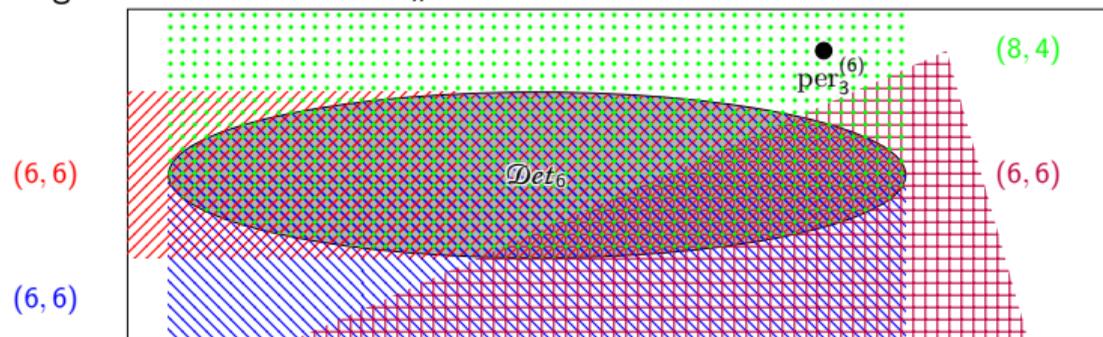
$$\text{per}_m^{(n)} \notin \mathcal{D}et_n \iff \mathcal{P}er_m^{(n)} \not\subseteq \mathcal{D}et_n$$

**Orbit closure containment** problem (NP-hard, [Bläser, I, Jindal, Lysikov STOC 2018]).

We compare **two** varieties. If  $\dim \mathcal{P}er_m^{(n)} > \dim \mathcal{D}et_n$ , then  $\mathcal{P}er_m^{(n)} \not\subseteq \mathcal{D}et_n$ .

Instead of  $\dim \mathcal{D}et_n$  we can also take other properties:

Def.: The **multiplicity**  $\text{mult}_\lambda(\mathbb{C}[\mathcal{D}et_n])$  is defined as the dimension of the space of highest weight polynomials of weight  $\lambda$  restricted to  $\mathcal{D}et_n$ .



If  $\text{mult}_\lambda(\mathbb{C}[\mathcal{P}er_m^{(n)}]) > \text{mult}_\lambda(\mathbb{C}[\mathcal{D}et_n])$ , then  $\text{per}_m^{(n)} \notin \mathcal{D}et_n$ .

## Hope for multiplicities

Theorem [Dörfler, I, Panova; ICALP 2019]

There are situations where occurrences do **not** work, but multiplicities do.

(Cluster computation to rule out occurrence obstructions)

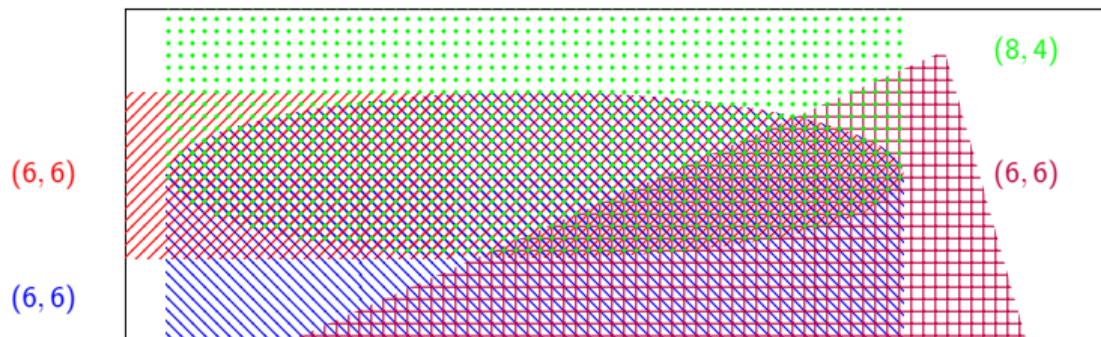
Recent work on dimension data ([Larsen, Pink; 1990], [Yu; 2016]) suggest that the method could be fine enough for separations.

Intuitively, the multiplicities  $\text{mult}_\lambda(\mathbb{C}[\mathcal{P}er_m^{(n)}])$  and  $\text{mult}_\lambda(\mathbb{C}[\mathcal{D}et_n])$  should be very different, because det and per have very different **symmetry groups**.

## Computation of representation theoretic multiplicities

Almost all multiplicities are  $\#P$ -hard to compute (in particular NP-hard), even in “simpler” cases:

- For the famous Kronecker coefficient even deciding positivity is NP-hard [I, Mulmuley, Walter; 2017].
- This is also true for plethysm coefficients, which is just the dim. of the highest weight polynomial space. [Fischer, I; 2020].



## Theorem [I, Kandasamy; STOC 2020]

Let  $m \geq 3$ . Let  $\Pi_m := \overline{E(x_1 x_2 \cdots x_m)}$ . Let  $\Gamma_m := \overline{E(x_1^m + x_2^m + \cdots + x_m^m)}$ . Let  $\lambda := (4m, \underbrace{2m, 2m, 2m, \dots, 2m}_{m-1 \text{ many}})$ .

Then

$$\text{pleth. coeff.}(\lambda) \geq 3 > \text{mult}_\lambda(\mathbb{C}[\Gamma_m]) \geq 2 > 1 \geq \text{mult}_\lambda(\mathbb{C}[\Pi_m]) \stackrel{m=p\pm 1}{>} 0.$$

Therefore

- $\Gamma_m \not\subseteq \Pi_m$ .

and hence

$x_1^m + \cdots + x_m^m$  is not a product of homogeneous linear polynomials.

The bounds are derived from the **symmetry groups** of  $x_1^m + \cdots + x_m^m$  and  $x_1 \cdots x_m$ .

This is the first time we get both lower and upper bounds from the symmetry groups.

## Algebraic natural proofs

Definition [Forbes, Shpilka, Volk; 2017] and independently [Grochow, Kumar, Saks, Saraf; 2017]

Given a sequence of varieties  $(\mathcal{C}_n)_n$  (of polynomials of degree  $n$  in  $\text{poly}(n)$  variables), then a sequence  $\Delta \in \text{VP}$  of nonzero polynomials is called a (VP-) **algebraic natural proof** against  $\mathcal{C}$  if  $\forall n : \Delta_n(\mathcal{C}_n) = \{0\}$ .

This notion is dual to  $\mathcal{C}$  being a hitting set for VP.

The sequence  $\mathcal{C}_n = \{f \mid \text{dc}(f) \leq n\}$  "captures VDET".

Theorem [Bläser, I, Jindal, Lysikov; STOC 2018]

If there are  $\text{VP}^0$ -algebraic natural proofs over char 0 against the set of matrices with permanent zero, then  $\text{P}^{\#\text{P}} \subseteq \exists\text{BPP}$ .

But this variety can be described with occurrence obstructions: very succinct encoding for hard functions.

Theorem [Bläser, I, Jindal, Lysikov; STOC 2018] + [Bläser, I, Lysikov, Pandey, Schreyer SODA 2021]

If  $\text{coNP} \not\subseteq \text{NP}^{\text{BPP}}$ , then no VP-algebraic natural proofs exist for minrank 1.

Generalization in [Bläser, I, Lysikov, Pandey, Schreyer SODA 2021] to arbitrary varieties that are efficiently sampleable and where membership testing is NP-hard, for example: slice rank.

Challenging open question: How hard it is to decide membership in  $\{f \mid \text{dc}(f) \leq n\}$ ?

## Summary

- If we allow approximations (=Euclidean closures) in algebraic complexity, then all complexity lower bounds can be proved via highest weight polynomials. Some are VNP-complete.
- Multiplicity obstructions use only the dimension of the vector space of highest weight polynomials. Occurrence obstructions even only use their occurrence.
- Even though computing multiplicities is NP-hard, sometimes enough information about the multiplicities can be extracted from the symmetry groups of the two polynomials. They might be good enough to prove strong lower bounds.
- GCT "breaks the algebraic natural proofs barrier" in toy settings by encoding hard functions succinctly.
- Slice rank and related notions give new natural testbeds for GCT.

Thank you for your attention!